# Sketch-based Modeling

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#### Sketch stroke acquisition & processing

Karan Singh

# Issues in digital sketching

Stroke filtering

fairing, curve-fitting.

Stroke processing

segmentation, recognition, regularization.

Stroke dynamics

pressure, tilt, speed, temporal order.

Stroke appearance

NPR, stylization, perception.

Stroke-based UI Control

widgets, crossing, gestures.



## Stroke filtering: noise & error sources

- User error
  - Intent (wants a square but draws a rectangle).
  - Execution (unsteady hand).
  - Ergonomic (awkard drawing posture).
- Device error
  - Input (tablets better than mice or trackpads).
  - Resolution (projected better than surface capacitance).
  - Signal Noise.



### What are desirable strokes?

**Smoothness**: "tangent and perhaps curvature continuous curves" [Farin et al. 87].

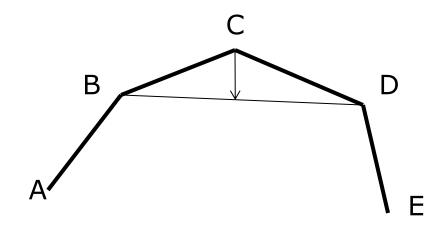


# Simple smoothing approaches

- Laplacian. (neighbour averaging).
- Bi-Laplacian.
- LSQ spline fitting.



# Simple smoothing: Laplacian

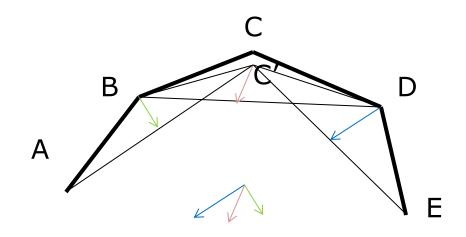


$$lap(C) = (B+D)/2-C$$
  
 $C' = C + d*lap(C) 0 < d < 1$ 

Best to run many iterations with A small d, for eg. 5 iterations d=0.2.



# Simple smoothing: Bi-Laplacian



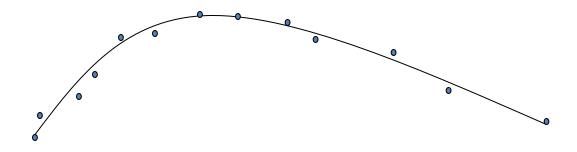
Find a C' such that:

$$lap(C') = (lap(B) + lap(D))/2$$
  
(B+D)/2-C'= (((A+C')/2-B)+((E+C')/2-D))/2

$$C'= 2/3 (B+D-A/4-E/4)$$
  
bi-lap(C)=C'-C



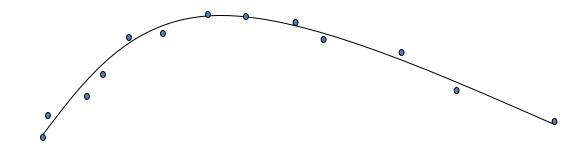
# Simple smoothing: LSQ fitting



f(t)=(x,y) from points  $(x_i, y_i)$ 



# Simple smoothing: LSQ fitting



LSQ solves for f to minimize error  $\sum_{i} |f(t_i)-(x_i, y_i)|^2$ 

Approach: guess  $t_i$ ;

LSQ solve for f;

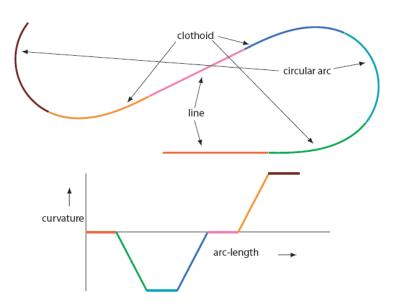
refine t<sub>i</sub> for current f;

iterate...



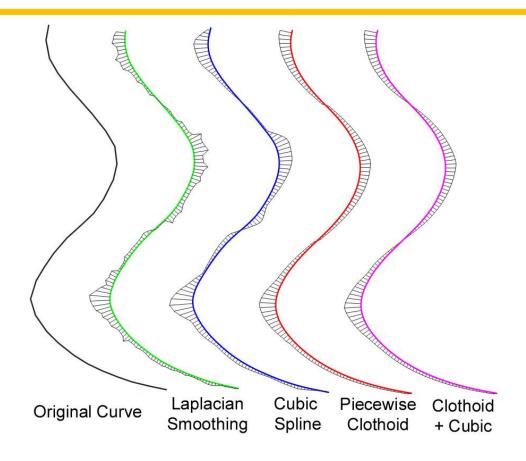
### What are desirable strokes?

- **Fairness**: "curvature continuous curves with a small number of segments of almost piecewise linear curvature" [Farin et al. 87].
- Lines, circles and clothoids are the simplest primitives in curvature space.





# Comparative approaches to fairing



[McCrae & Singh, Sketching Piecewise Clothoid Curves, SBIM 2008] source code: <a href="http://www.dgp.toronto.edu/~mccrae/clothoid/">http://www.dgp.toronto.edu/~mccrae/clothoid/</a>



### Desirable strokes

- **Neatness**: "a combination of fairness and fine detail as intended by the user".
- Requires either implicit knowledge of user-intent, or an explicit neatening directive by the user.



# Stroke neatening: French curves

Physical tools, used to model curves.



French curves + smooth shape priors, specify a style/standard

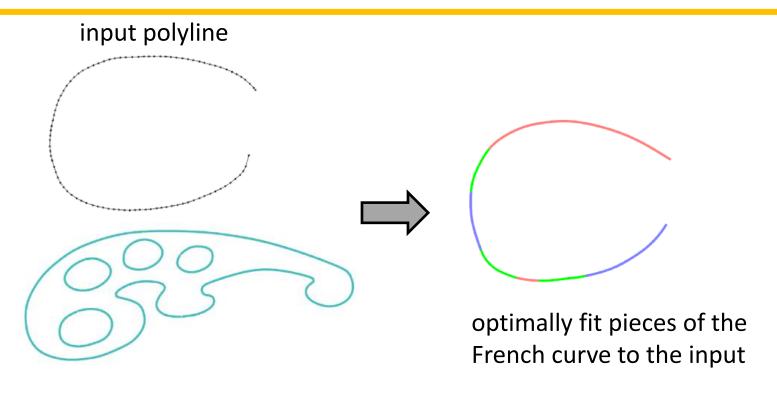


sketch interface

fluid free-form



# Stroke neatening: French curves

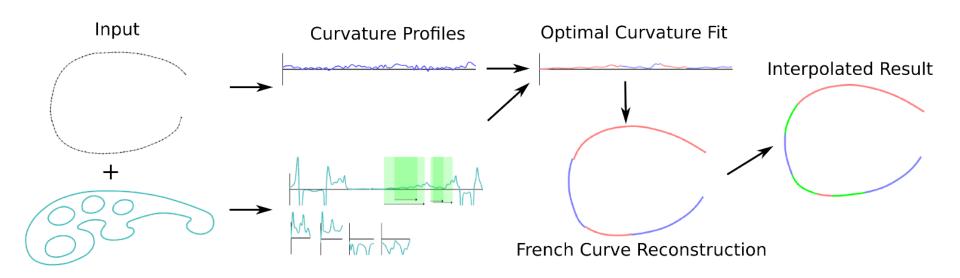


French curve

[McCrae & Singh, Neatening sketched strokes using piecewise French Curves, SBIM 2011]

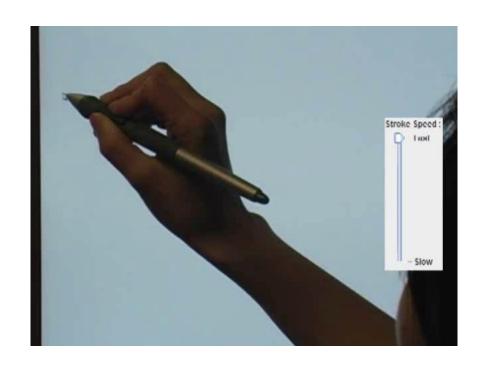


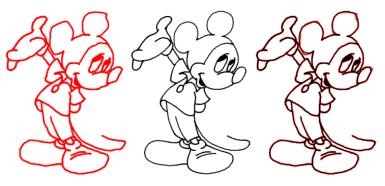
# Stroke neatening: French curves





#### Stroke neatening & dynamics: elasticurves



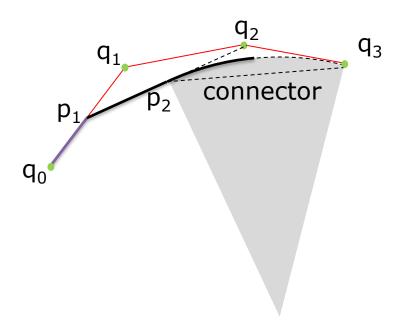


[Thiel, Singh, Balakrishnan Elasticurves: Exploiting Stroke Dynamics and Inertia for the Real-time Neatening of Sketched 2D Curves, *UIST 2011*] java applet: <a href="http://www.dgp.toronto.edu/~ythiel/Elasticurves/">http://www.dgp.toronto.edu/~ythiel/Elasticurves/</a>



### Elasticurve

Input q<sub>i</sub>'s sampled at a time interval of dt



responsiveness = connector arc-length fraction extending an elasticurve.

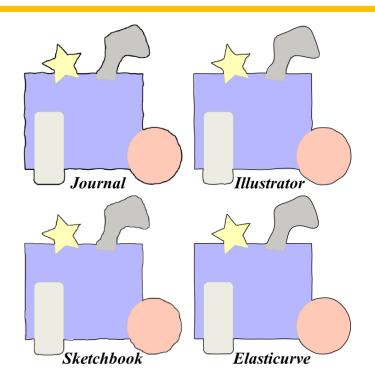


# **Elasticurve Properties**

- **Explicit and real-time**: neatness is directly correlated to drawing speed and *responsiveness*.
- Analytic: resilience to dt sampling variation.
- Precise: embodies desirable shapes as connectors.



## Elasticurve evaluation & curve quality



Intermediate user, trackpad, visual best of 7 attempts.



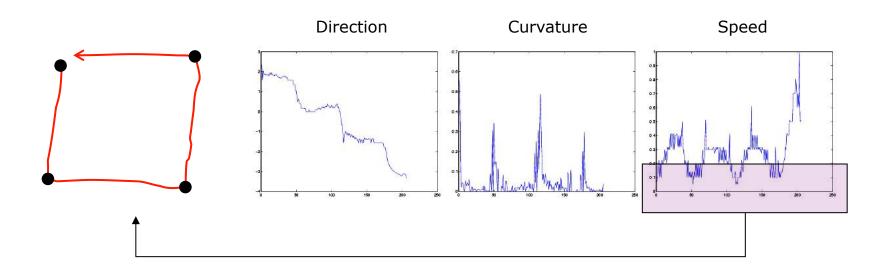


# Stroke Processing

- Filtering, neatening, beautification can also be considered as stroke processing.
- Segmentation, classification, recognition.
- Regularization.
- Abstraction.



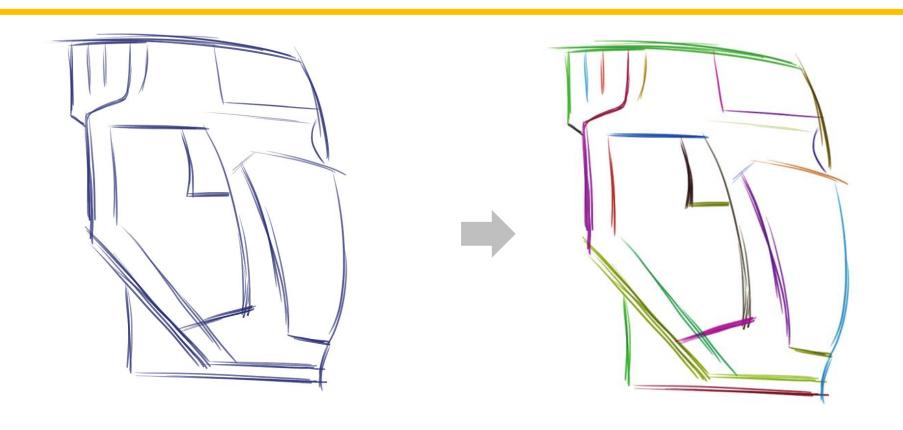
## Stroke segmentation: finding corners



[**T. Sezgin et al.**, Sketch Based Interfaces: Early Processing for Sketch Understanding, Workshop on Perceptive User Interfaces, 2001.]



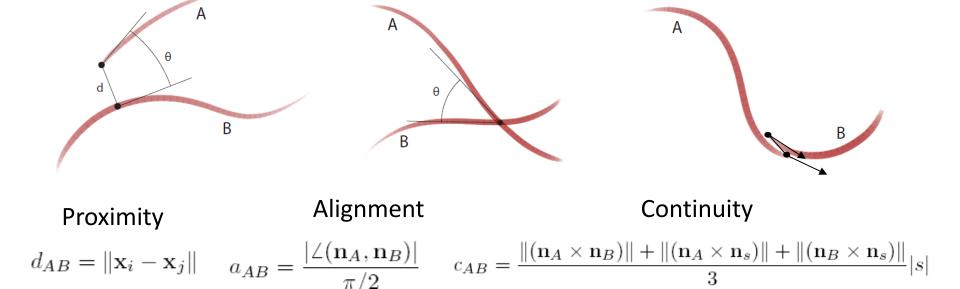
# Stroke classification: pentamenti



[G. Orbay & L. Kara., Beautification of Design Sketches Using Trainable Stroke Clustering and Curve Fitting. IEEE Transactions on Visualization and Computer Graphics 17, 5 (May 2011).]



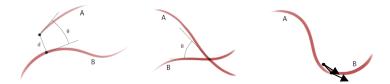
#### Geometric Stroke Features



- Pairwise features
- Stroke proximity
- Local learning



## **Group Strokes by Affinity**



Affinity = Proximity + Alignment + Continuity

learning approaches with or without examples:
 neural network
 spectral clustering
 greedy grouping (single-link clustering)



# Stroke grouping and regularization

#### **Gestalt Principle**

"The whole is greater than the sum of its parts"



# Gestalt grouping and regularization

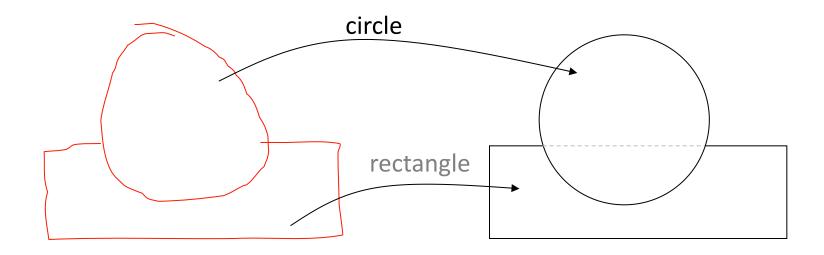
- Similarity
- Symmetry
- Continuation
- Closure
- Proximity



Regularization makes strokes that are nearly isometric, parallel, symmetric, perpendicular etc. precisely so!



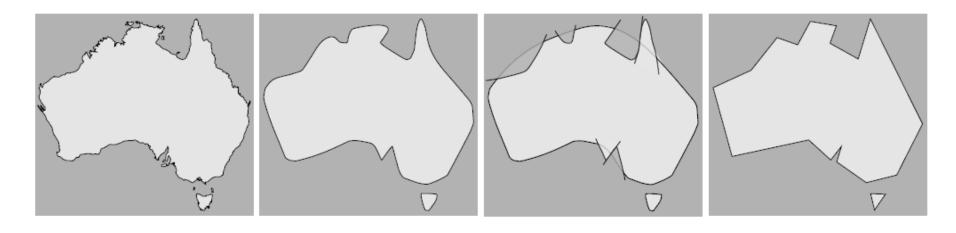
# Stroke recognition





### Stroke Abstraction

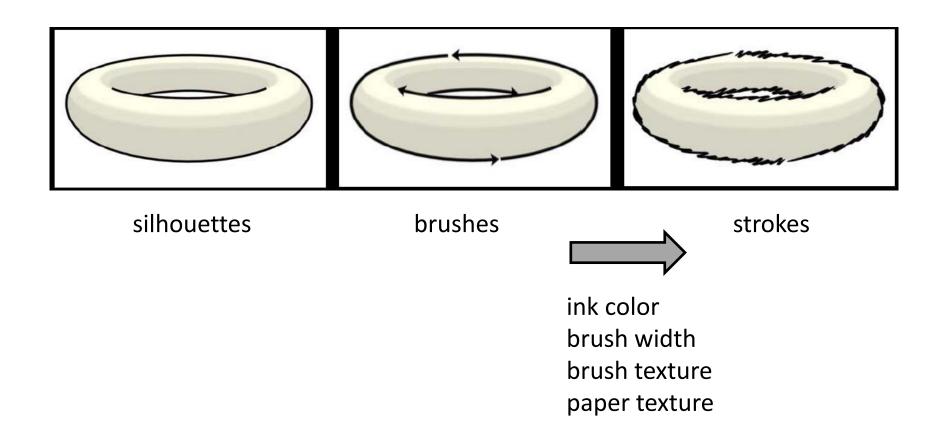
Stroke neatening that captures the essence of the stroke.



[**D. De Carlo & ...**, *Fitting*.]

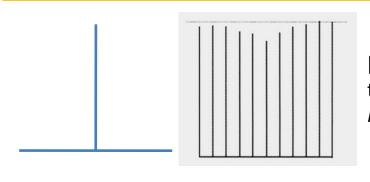


# Stroke Appearance: NPR

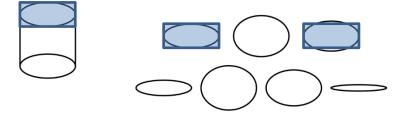




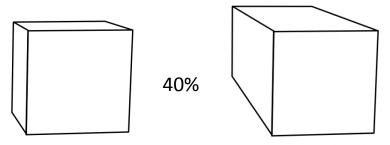
## Stroke Perception



[Wolfe, Maloney & Tam, Distortions of perceived length in the frontoparallel plane: tests of perspective theories, Perception & pyschophysics, 2005]



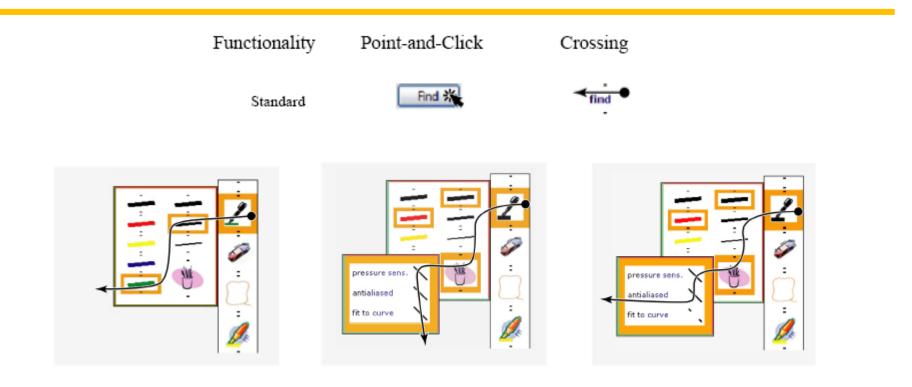
[**Taylor & Mitchell**, Judgements of apparent shape contaminated by knowledge of reality: viewing circles obliquely, *British Jnl. of Psych.*, 1997]



[Schmidt, Khan, Kurtenbach, Singh, On expert performance in 3D curve drawing tasks. SBIM 2009]



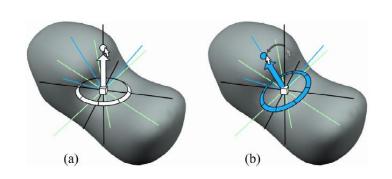
# Stroke UI: crossing



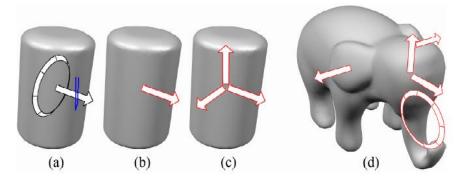
[Apitz, G. and Guimbretière, F. CrossY: A Crossing-Based Drawing Application ACM UIST, 2004]



# Stroke UI: widgets



suggested axes



crossing interaction and composition

[Schmidt, Singh & Balakrishnan Sketching and Composing Widgets for 3D Manipulation, Eurographics 2008]



# Stroke UI: gestures

- Ad-hoc or pre-defined:
  - Application specific: shorthand, chinese Brush Painting, musical scores, chemical formulas.
  - Platform specific: gesture libraries.
- Template-based:
  - Toolkit or framework
  - Simple algorithm based on geometric matching



# Ad-hoc vs. template-based

- Ad-hoc can recognize more complex gestures.
- Harder to train template-based gestures.
- Better consistency of gestural use in ad-hoc systems.
- Better gesture collision handling in ad-hoc systems.

Ad-hoc doesn't allow new gestures and limited customization.



#### GRANDMA

- 1. Encode gestures as a linear function of 13 features.
- 2. Draw a gesture ~15 times.
- 3. Train asset of feature weights for each gesture.
- 4. Classify gestures based on highest feature function score.
- [D. Rubine. Specifying gestures by example. SIGGRAPH 1991]



## \$1 recognizer goals

- Resilience to sampling.
- Require no advance math.
- Small code.
- Fast.
- 1-gesture training.
- Return an N-best list with scores.

[J. Wobbrock, A. Wilson & Y. Li. 2007. Gestures without libraries, toolkits or training: a \$1 recognizer for user interface prototypes. ACM UIST '07.]



## \$1 algorithm

- Resample the input
  - N evenly spaced points
- Rotate
  - "Indicative" angle between centroid and start point
- Scale
  - Reference square
- Re-rotate and Score
  - Score built from average distance between candidate and template points



## \$1 limitations

- Cannot distinguish aspect ratios, orientations.
  - Square from rectangle
  - Up arrow from down arrow
- Cannot be distinguished based on speed.
- Only single strokes.
- Stroke order is important.
- Closed strokes?
- Gestalt gestures!



### Take-aways

- Understand your application:
  - Does it need strokes?
  - Are strokes natural and of low-complexity, 2D or 3D?
- Understand source of stroke error before filtering?
- Ensure users can control stroke dynamics before you exploit it.
- Both clean and sketchy stroke appearances are useful.
- Understand perceptual bias in drawn strokes.
- Develop a GUI suited to stroke interaction.



# Multi-view sketch-based modeling of 3D curves and surfaces

Yotam Gingold

## How can we turn sketch strokes into 3D shapes?

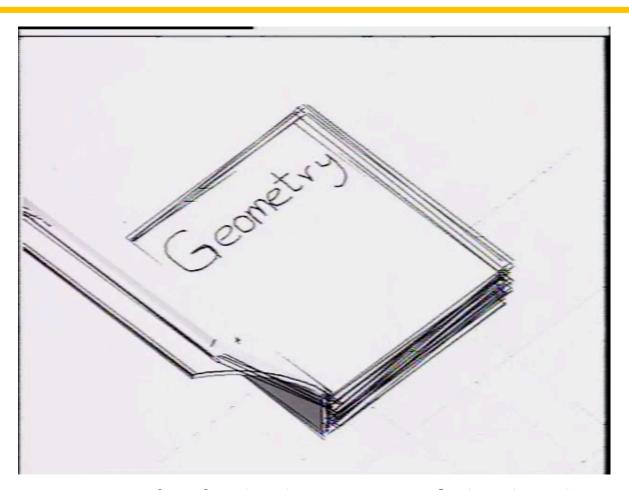
- Interpreting them as gestures
- Interpreting them as silhouettes
- Projecting them in 3D

 General principle: Drawing from different points of view.



## Interpreting stokes as gestures

### **SKETCH**



SKETCH: An Interface for Sketching 3D Scenes [Zeleznik et al. 1996]



## Interpreting strokes as silhouettes

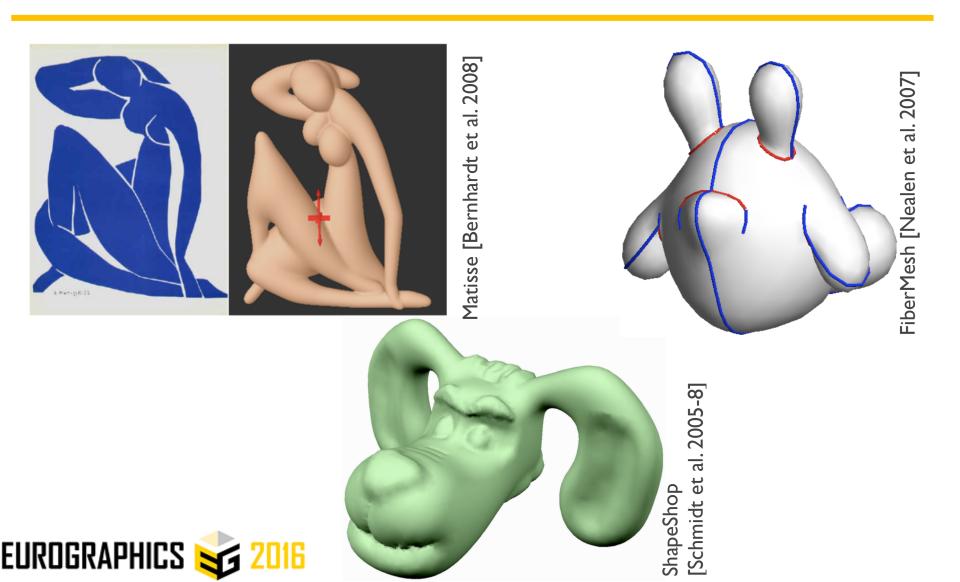
## Teddy



Teddy: A Sketching Interface for 3D Freeform Design [Igarashi et al. 1999]



## More freeform inflation approaches



## Inflation (Teddy)

a) before

b) elevate spines

T S J a) initial 2D polygon b) result of CDT c) chordal axis d) fan triangles e) resulting spine f) final triangulation

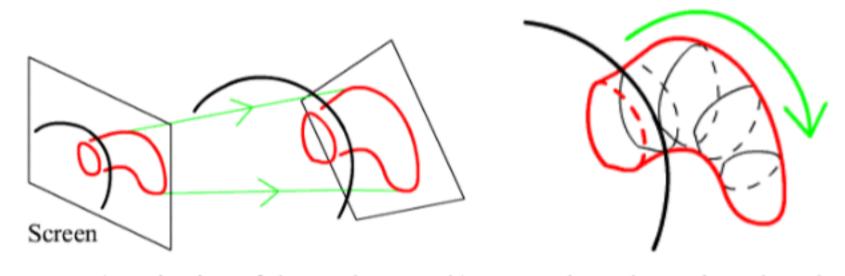
c) elevate edges d) sew elevated edges

• Step 2

Step 1



## Extrusion (Teddy)

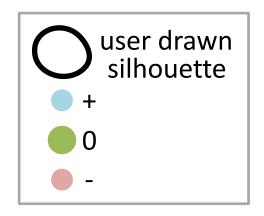


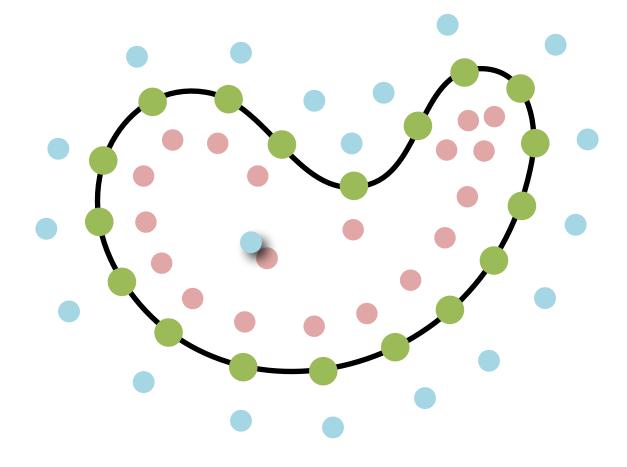
a) projection of the stroke

b) sweep along the projected stroke



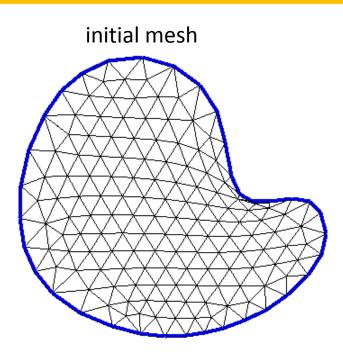
## Inflation (implicit surface)

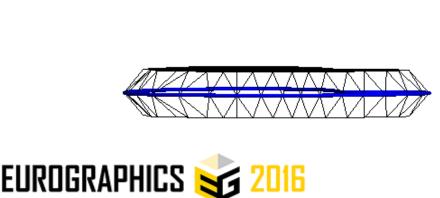




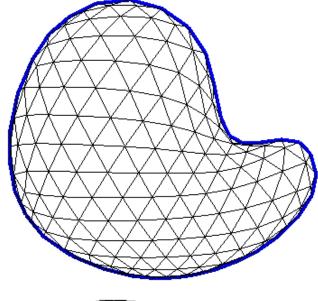


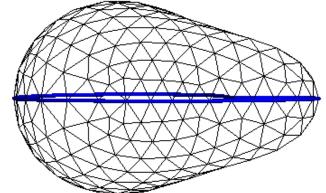
## Inflation (surface optimization)





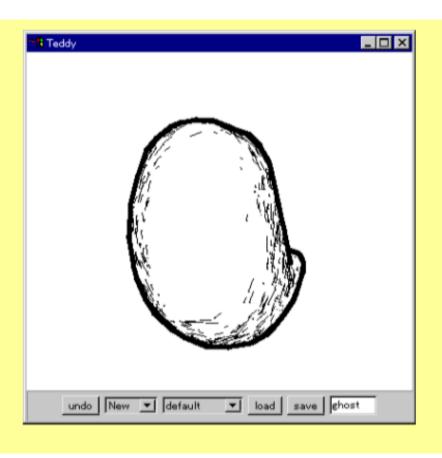
#### minimum variation of curvature

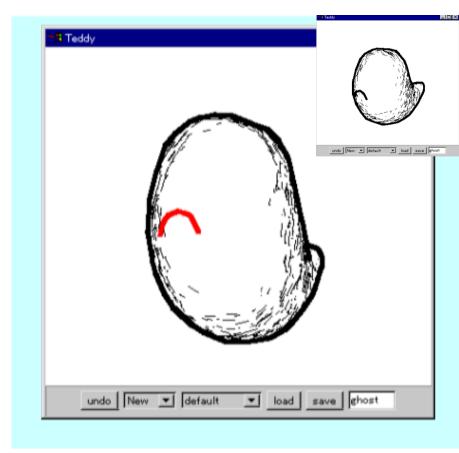




FiberMesh [Nealen et al. 2007]

## Painting (Teddy)

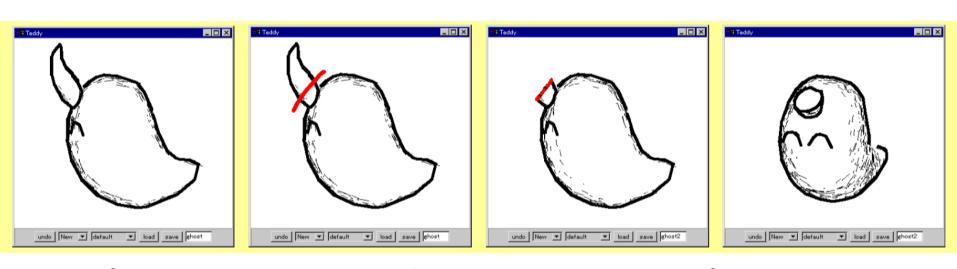




Before After



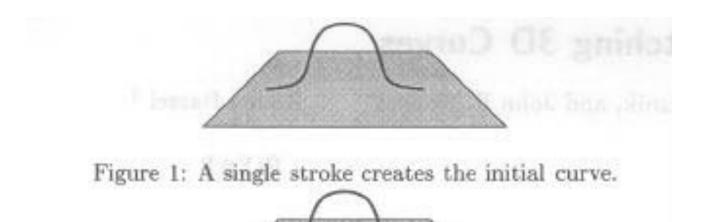
## Cutting (Teddy)



Before Cutting stroke After



## Projecting strokes in 3D



around stroke defines the murue's shadow

Figure 2: A second stroke defines the curve's shadow and hence its 3D shape.



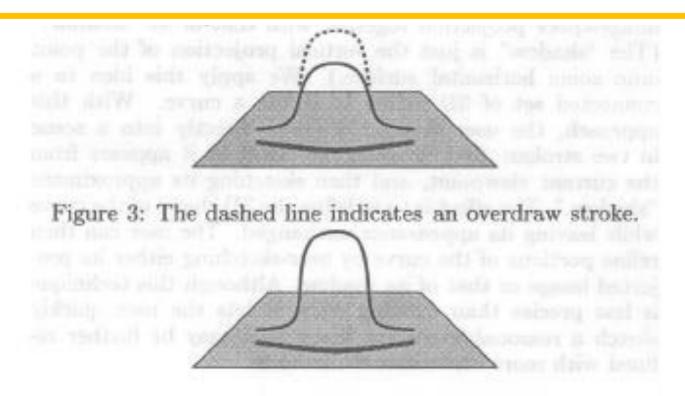


Figure 4: The system blends the overdraw with the original curve to get the final result.



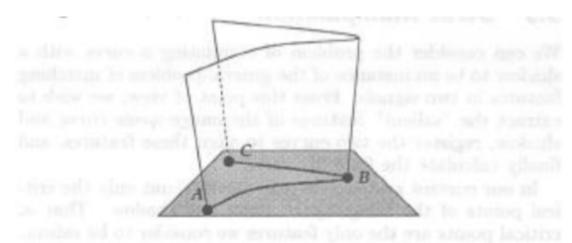


Figure 7: The shadow defines a ruled surface with a silhouette above the interior critical point of the shadow, B.



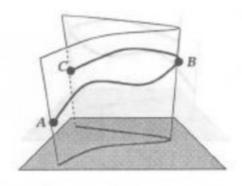


Figure 8: The curve must turn around at B to stay on the surface.

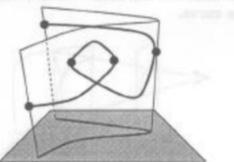


Figure 9: The curve may have more critical points than the shadow and still be valid.

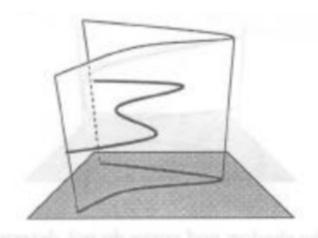
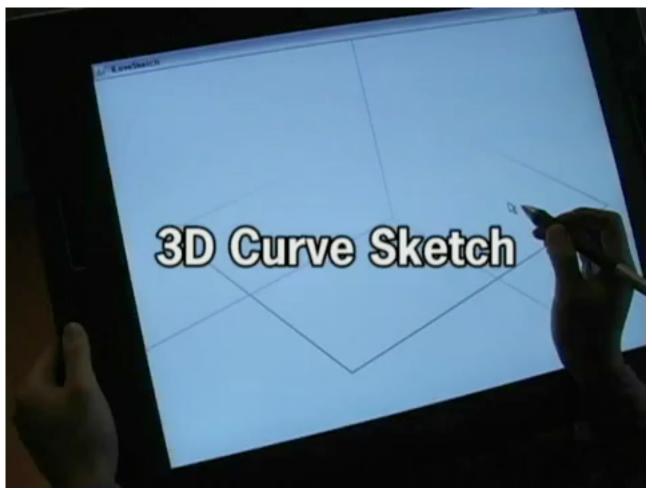


Figure 10: There is no way to project this curve onto the surface to get a continuous 3D curve.



#### iLoveSketch



iLoveSketch: As-natural-as-possible sketching system for creating 3D curve models [Bae et al 2008]



## Takeaways

- We can remove the ambiguity in depth in several ways:
  - with initial assumptions (rotund surfaces)
  - by projecting onto other surfaces
  - by sketching from multiple points of view

#### References

[Zeleznik et al. 1996] Robert C. Zeleznik, Kenneth P. Herndon, John F. Hughes: SKETCH: an interface for sketching 3D scenes. SIGGRAPH

Courses 2007: 19

[Igarashi et al. 1999] Takeo Igarashi, Satoshi Matsuoka, Hidehiko Tanaka: Teddy: A Sketching Interface for 3D Freeform Design.

SIGGRAPH 1999: 409-416

[Bernhardt et al. 2008] Adrien Bernhardt, Adeline Pihuit, Marie-Paule Cani, Loic Barthe: Matisse: Painting 2D regions for Modeling Free-Form Shapes. SBM 2008: 57-64

[Schmidt et al. 2005-8] Ryan Schmidt, Brian Wyvill, Mario Costa Sousa, Joaquim A. Jorge: ShapeShop: Sketch-Based Solid Modeling with BlobTrees. SBM 2005: 53-62



#### References

[Nealen et al. 2007] Andrew Nealen, Takeo Igarashi, Olga Sorkine, Marc Alexa: FiberMesh: designing freeform surfaces with 3D curves. ACM Trans. Graph. 26(3): 41 (2007)

[Cohen et al. 1999] Jonathan M. Cohen, Lee Markosian, Robert C. Zeleznik, John F. Hughes, Ronen Barzel: An interface for sketching 3D curves. SI3D 1999: 17-21

[Bae et al 2008] Seok-Hyung Bae, Ravin Balakrishnan, Karan Singh: ILoveSketch: as-natural-as-possible sketching system for creating 3d curve models. UIST 2008: 151-160







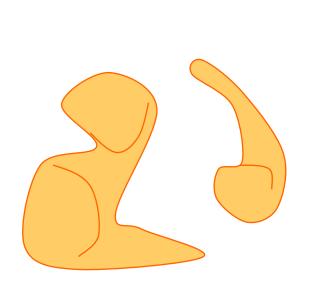
# Sketch-based modelling using prior knowledge

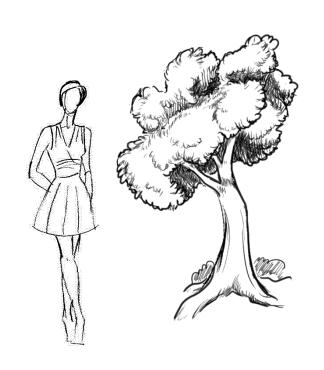
Even Entem & Marie-Paule Cani

Grenoble University & Inria



### Use of prior knowledge: Motivation

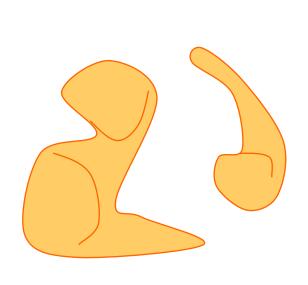




Why do we "see" 3D shapes when we look at a sketch?



## Use of prior knowledge: Motivation



Unknown shape

• We infer the simplest one



Well known shapes

• We use prior knowledge



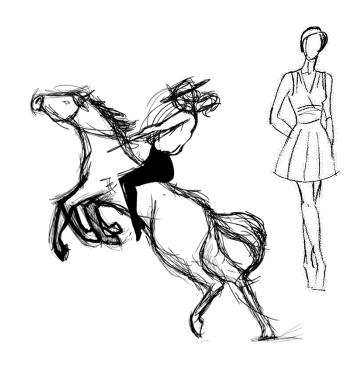
## Use of prior knowledge: Motivation

#### Well known shapes

- Model prior knowledge
- It can help us to infer 3D from a single sketch!

#### Two examples in this talk

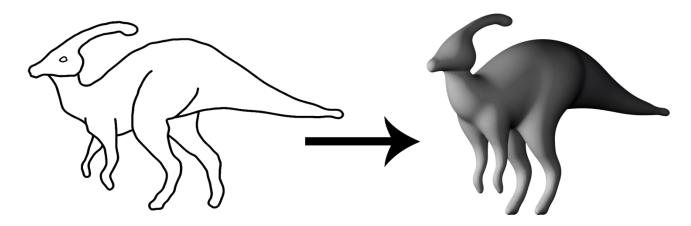
- Animals
- Garments





# Sketching specific shapes Example 1: Animals from a side-view sketch

Goal: Modeling animals and other creatures from a single sketch



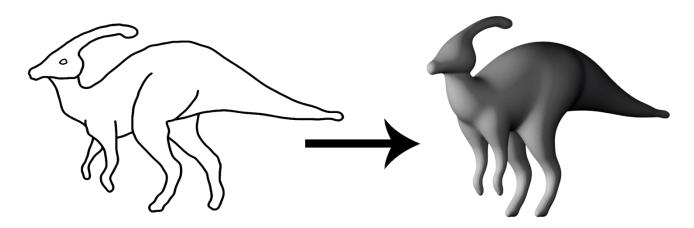
#### Prior knowledge:

- Organic shapes: Rather smooth, volumetric shapes
- Structural symmetries (limbs in arbitrary postures)
- Anatomic principles



#### Strategy:

- What kind of drawing gives the best trade-off between user-friendliness and explicitness? In terms of:
  - View: Side
  - Style: Processed sketch (beautified and regularized)





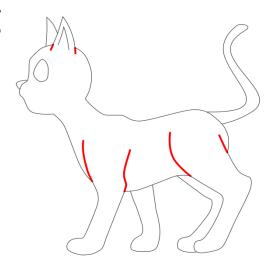
#### What kind of 3D shape representation to use?

- Inflated polygon meshes:
  - ~ Enable flat areas and full control over the geometry. But ambiguities inherent to the sketch make it unnecessary
  - Post-editing is not user-friendly
- Convolution surfaces:
  - + Ensures the smoothness of the shape
  - + 3D line skeleton suited for user-friendly post-editing



#### How to infer a 3D line skeleton from the sketch?

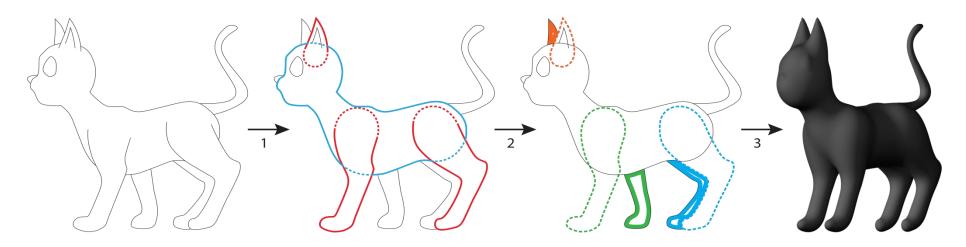
- Perceptual process: segmentation into subparts
  - Subparts are partially/fully bounded by curves and may be partially occluded.
  - Depth ordering from cues ("T-junctions" and inclusions)
- -> Identify curves in terms of meaning
  - Silhouette contours
  - Suggestive contours
    - Silhouette in most nearby views





#### Identify the ambiguities and tasks

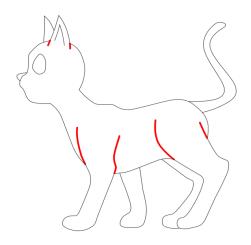
- Suggestive contours pairing (and closures)
- Structural symmetries in the background
- Depth positioning

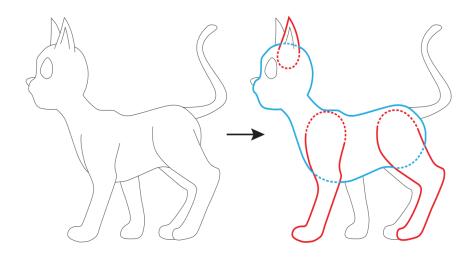




#### Identify the ambiguities and tasks

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- Depth positioning

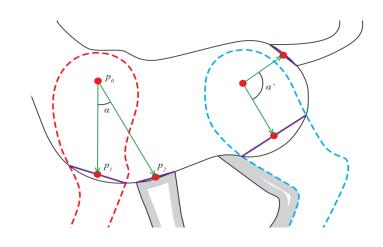


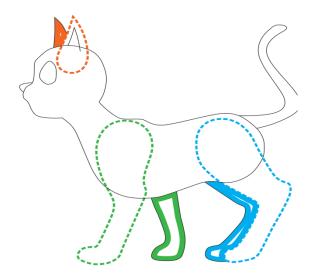




#### Identify the ambiguities and tasks

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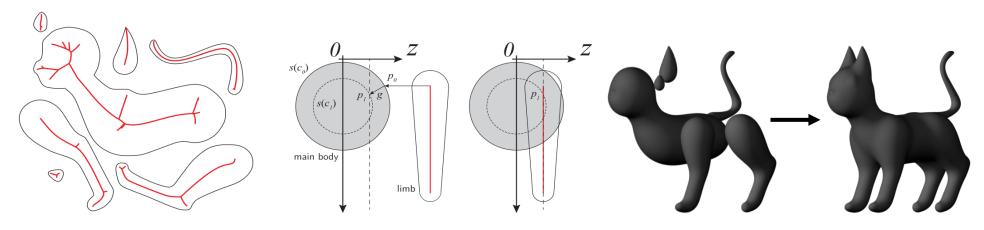




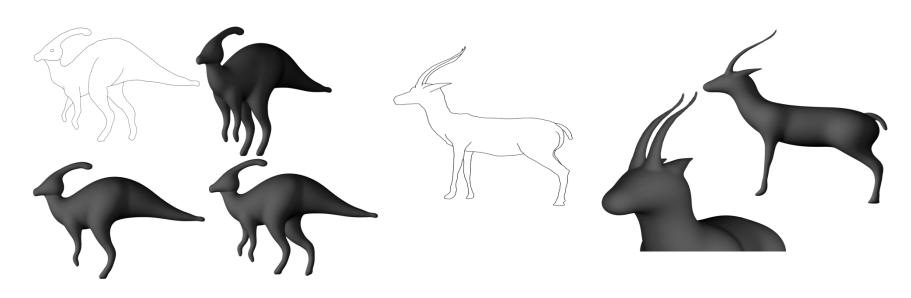


#### Generation of the 3D model

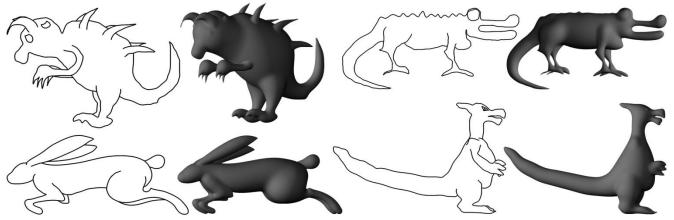
- Medial-Axis to get skeleton lines
- Prior knowledge let us define relative depths
  - "flesh around bones" considering lateral agonist and antagonist muscles equally developed.







[Entem, Barthe, Cordier, Cani, Van de Panne, SMI'2014]

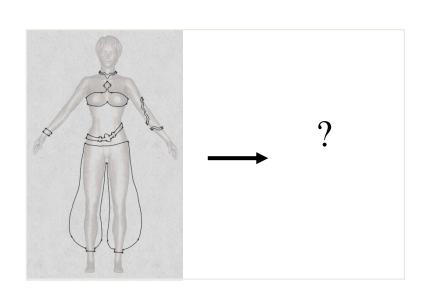


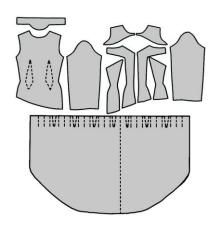


# Sketching specific shapes Example 2: Clothing design

#### Standard virtual clothing in Computer Graphics

- Design & place patterns
- Run a simulation!







3D model from 2D fashion sketch?

→ would compute the patterns!



Using silhouette information only

#### Virtual clothing from a sketch?

Sketch on a view of a 3D model



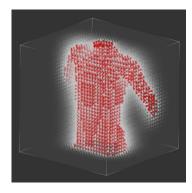


- Knowledge? Rule of thumb:
  - Fitting is the same in all directions!





Sketch in a distance field!





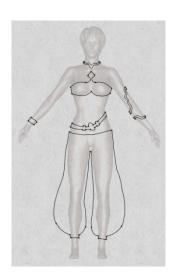
#### Using silhouette information only

#### Results lack folds!

Allow the designer to sketch them?



[Turquin, Cani, Hughes 2007]





[Turquin, Cani, Hughes 2004]

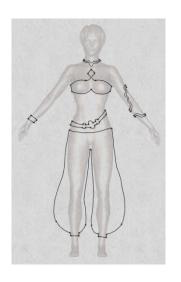
Nice if the designer is good!



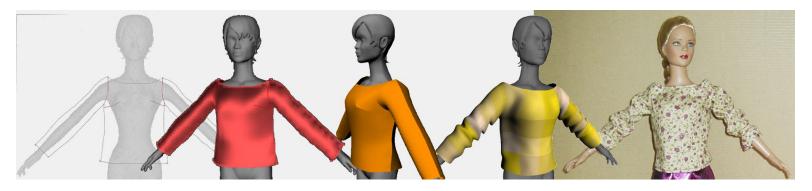
#### Using silhouette information only

#### Results lack folds!

- Ask the designer to sketch them...
- Or use more a priori knowledge?
  - Garment is piece-wise developable
  - Folds can be computed



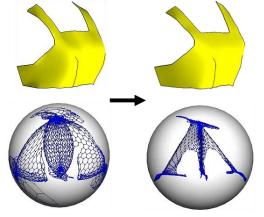




#### Developable surfaces from a sketch

#### Developable surface from sketch?

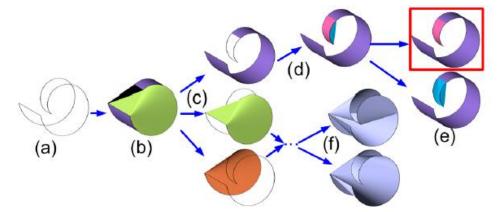
- Solution 1: increase developability
  - Start with the rough surface
  - Locally optimize the shape (1D normal map)

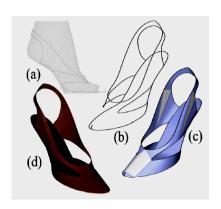


Solution 2: smooth developable surface from contours

Convex edges?

Recursively split & triangulate the convex hull

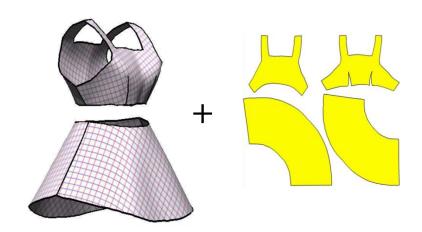






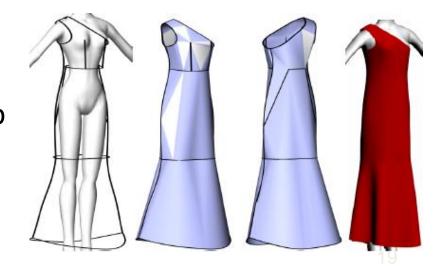
#### Developable surfaces from a sketch

Results still lack folds!



#### Run a simulation?

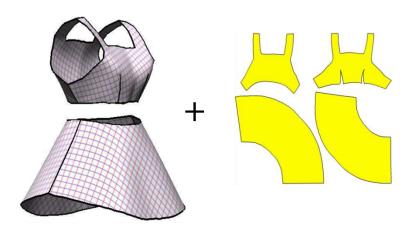
- Physically-based parameters to set up
- Stiff system for un-extensible cloth





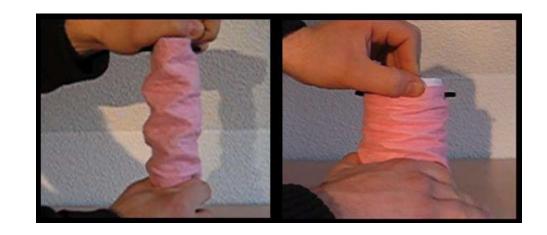
#### Developable surfaces from a sketch

Results still lack folds!



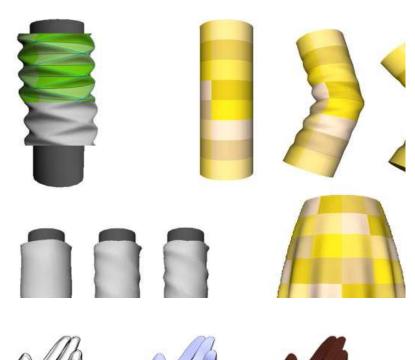
Or use more knowledge...

 Cloth wrapped on cylinders always folds the same way!



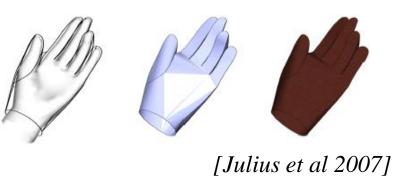


#### Developable surfaces from a sketch





[Decaudin & al 2006]





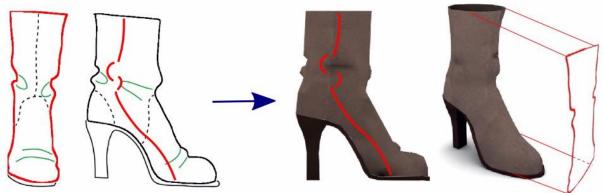


Sketching folds?

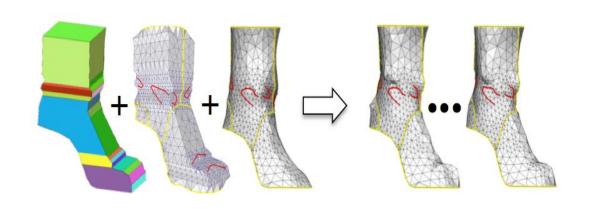
#### Folds are part of design



Challenge: Non-flat silhouettes!



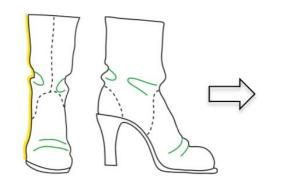
#### Sketching a folded surface



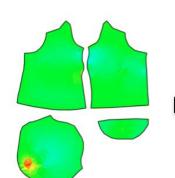
#### Iterate:

- Optimize developability
- Match the sketch

[Jung et al. TOG 2015]





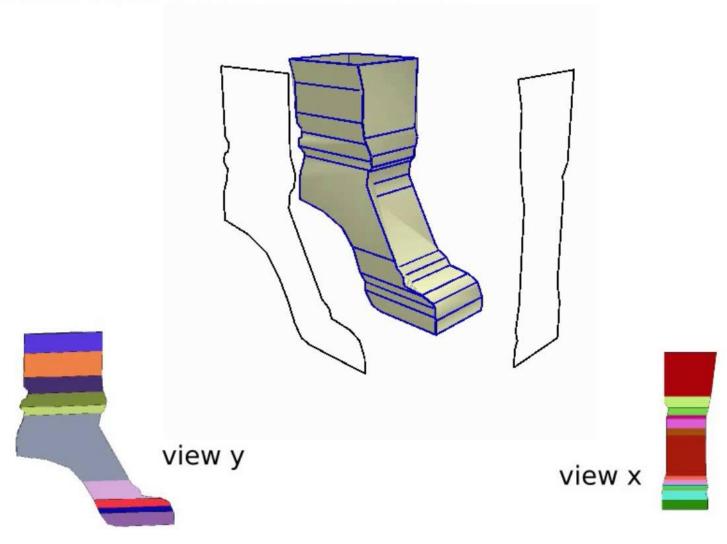




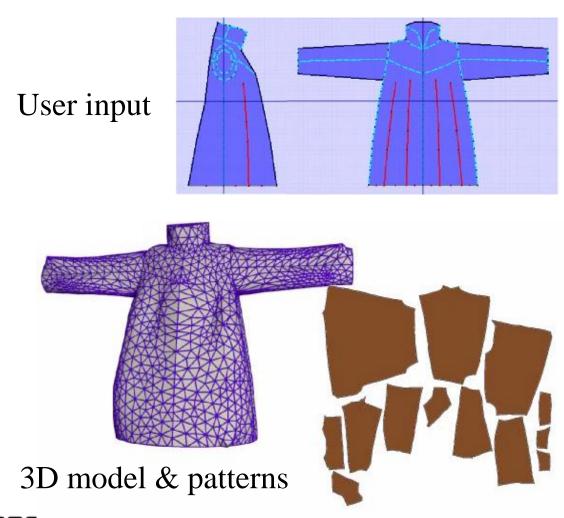


#### Initialization

Visual hull from silhouettes



Sketching a folded surface: Results



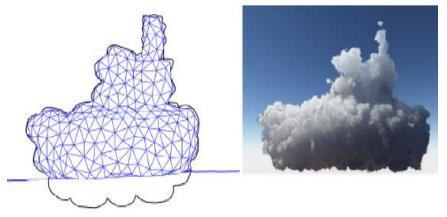


## Sketch-based modelling using prior knowledge

#### Many other examples!



[Wither Bertails Cani 2007]



[Wither Bouthors Cani 2008]



[Tasse, Emilien, Cani, Hahmann, Dogson, GI'2014]



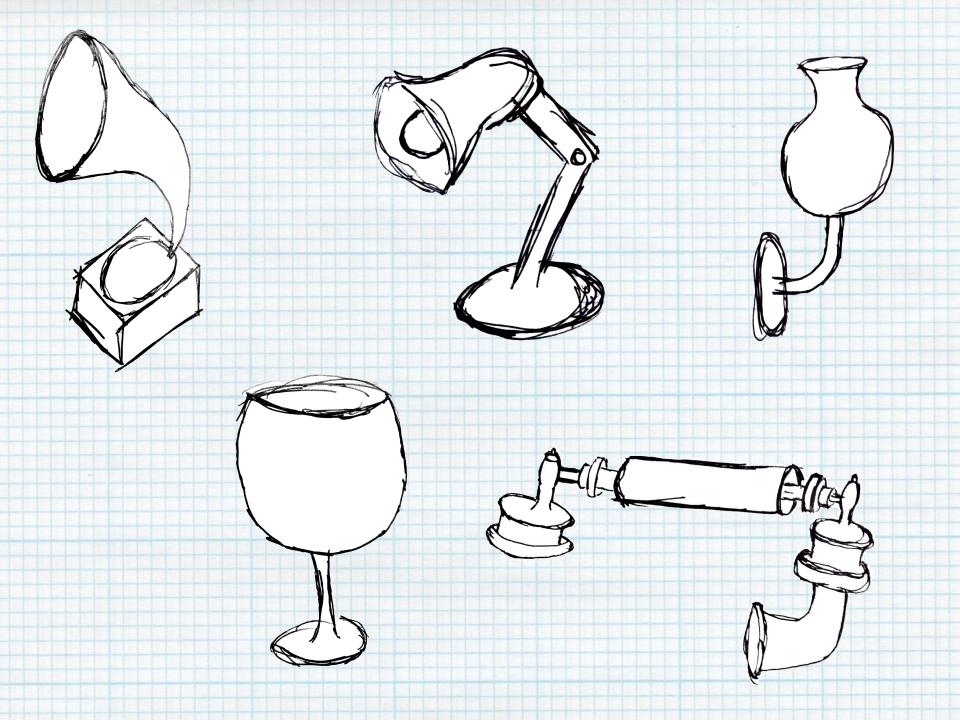
#### References

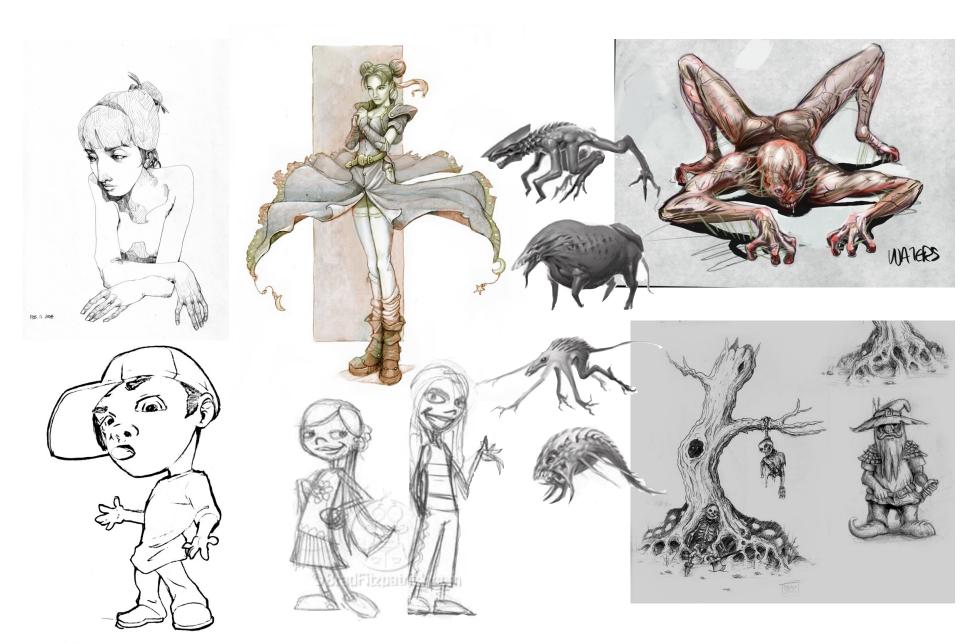
- ENTEM ET AL. Modeling 3D animals from a side-view sketch Shape Modeling International (SMI), 2014
- Turquin, Cani, Hughes Sketching Garments for Virtual Characters Eurographics Workshop on Sketch-Based Interfaces and Modeling (SBM), 2004
- DECAUDIN ET AL. Virtual Garments: A Fully Geometric Approach for Clothing Computer Graphics Forum (CGF), 2006
- Julius, Sheffer, Cani Developable surfaces from arbitrary sketched boundaries Symposium on Geometry Processing (SGP), 2007
- Jung, Hahmann, Rohmer, Cani Sketching Folds Transactions On Graphics (TOG), 2015
- WITHER, BOUTHORS, CANI Rapid sketch modeling of clouds Eurographics Workshop on Sketch-Based Interfaces and Modeling (SBM), 2004
- WITHER, BERTAILS, CANI Realistic Hair from a Sketch Shape Modeling International (SMI), 2007
- TASSE ET AL. Feature-based terrain editing from complex sketches Computers and Graphics, 2014



# Single-view sketch-based modeling of 3D curves and surfaces Part I

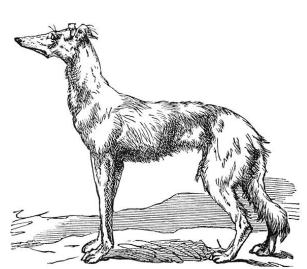
Yotam Gingold







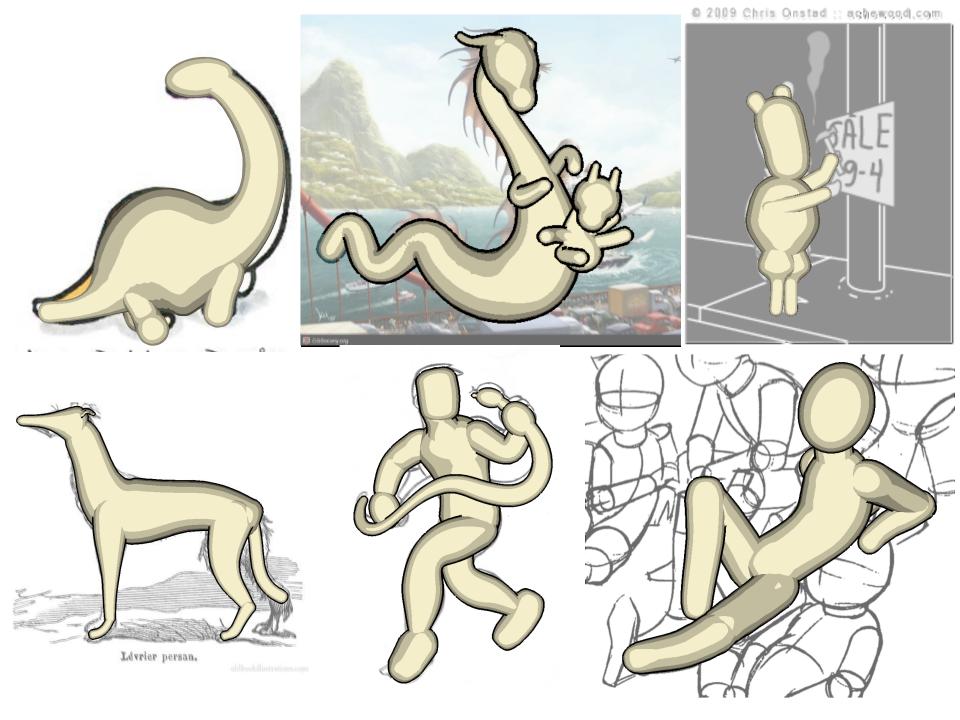












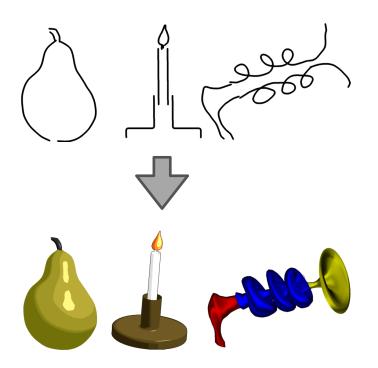
### Goals

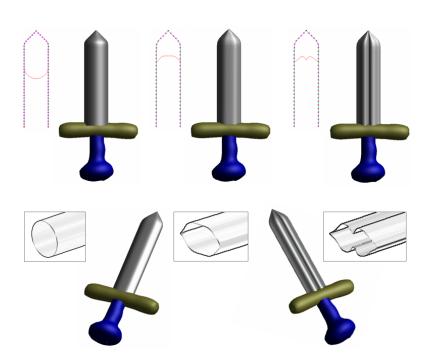
- Model by "describing" an existing 2D image with primitives and annotations.
- Usable by novices, including those with poor drawing skills.
- Create structured models.



## Sketch-based modeling with few strokes [Cherlin et al. 2005]

 Generalized cylinders with varying cross sections and "spines"





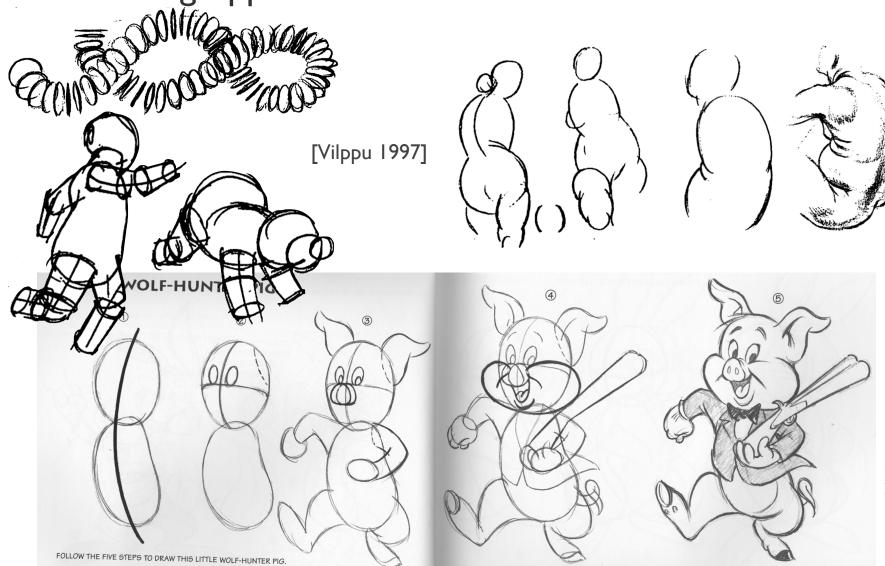


# Structured Annotations for 2D-to-3D Modeling

[Gingold et al 2009]

## Inspiration

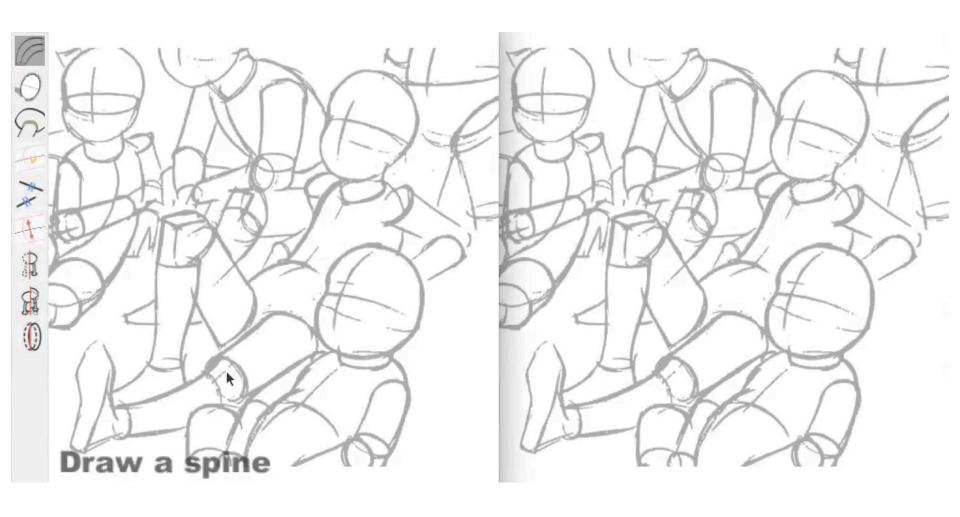
2D Drawing Approaches



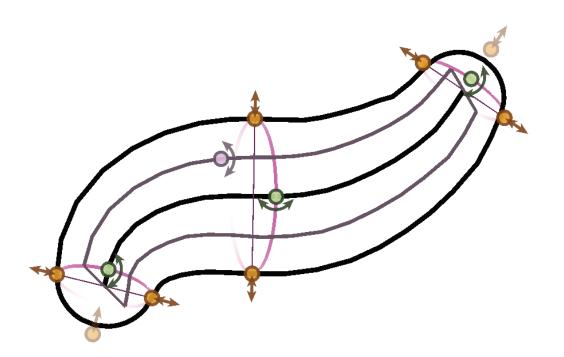
[Blair 1994]

## Primitives

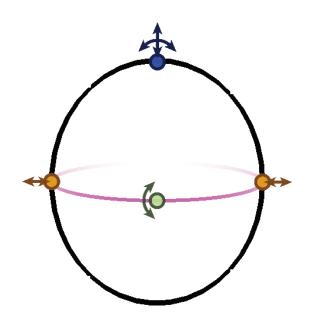
Generalized Cylinders & Ellipsoids



## Primitives



Generalized Cylinder



Ellipsoid

## Primitive: Generalized Cylinder

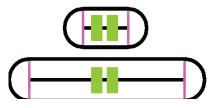
## Generalized Cylinder

## Primitive: Ellipsoid

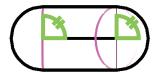
## Ellipsoid

## **Annotations**

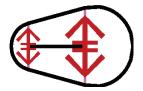
Same-length



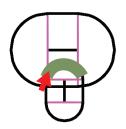
Same-tilt



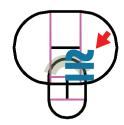
Same-scale



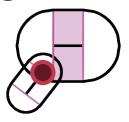
Connection curve

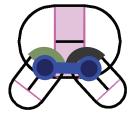


Mirror



Alignment

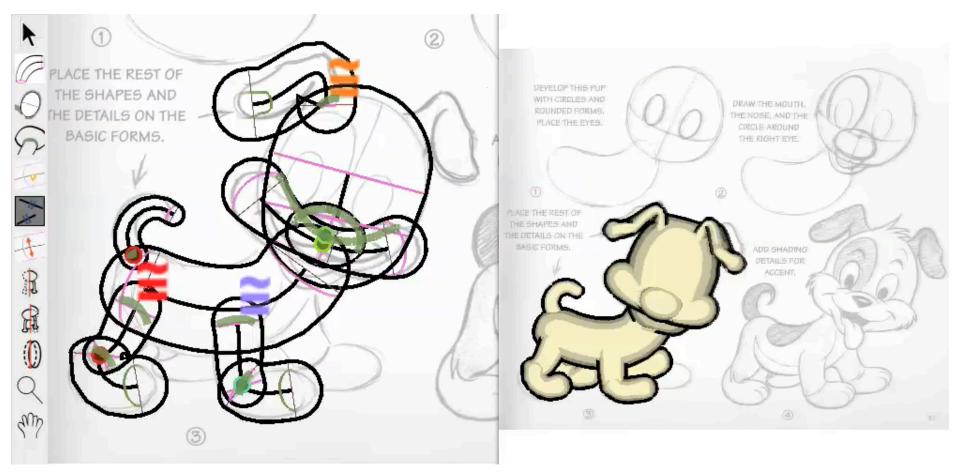




## Demo

# Modeling Session 5x Speed

## Results



Guide images: [Blair 1994]; © Alex Rosmarin; © Kei Acedera, Imaginism Studios 2008; © Björn Hurri, www.bjornhurri.com; © Alex Rosmarin; © Alex Rosmarin; [Kako 1973]; [Kako 1973]

## Limitations

## Limitations

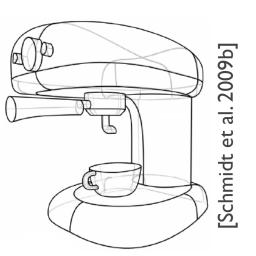
Limited range of models

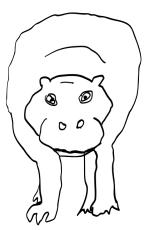


#### Limitations

Limited range of models

• Can't be used for certain drawings



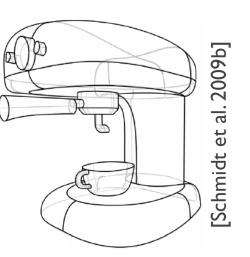


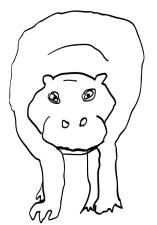
#### Limitations

Limited range of models

Can't be used for certain drawings

No cycles of connection curves







#### Limitations

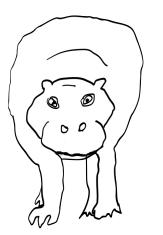
Limited range of models



No cycles of connection curves

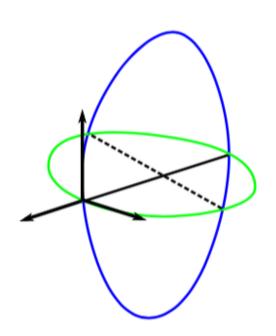
Doesn't actually use the guide image





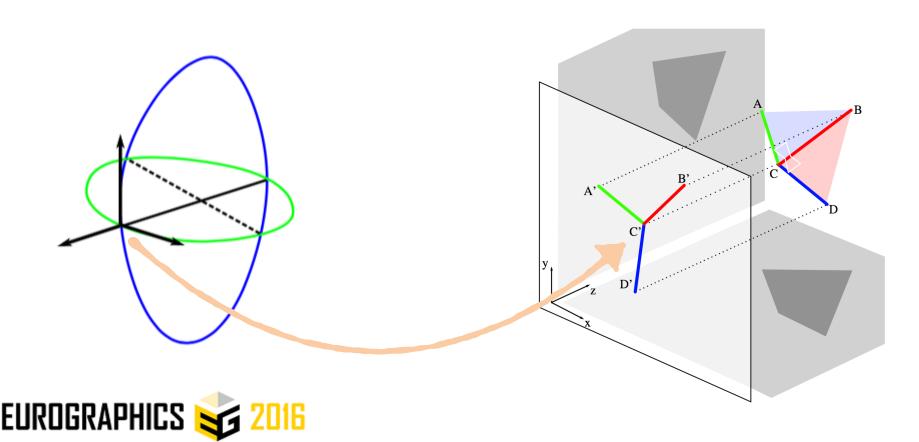


 Two perpendicular cross sections form the projection of a cubic corner (which is well-defined)

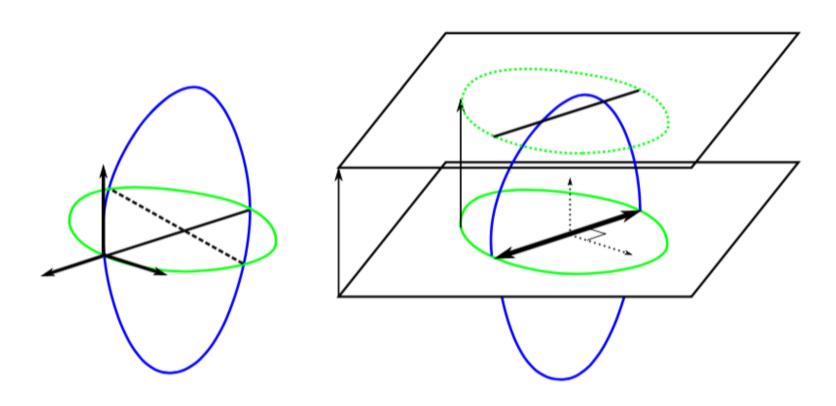




 Two perpendicular cross sections form the projection of a cubic corner (which is well-defined)

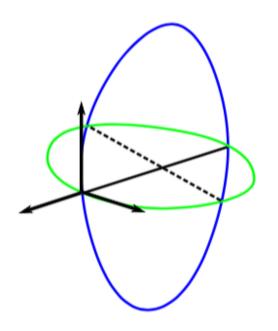


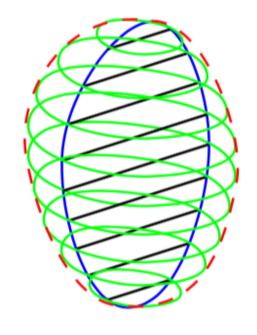
That gives us 3D axes for the shape



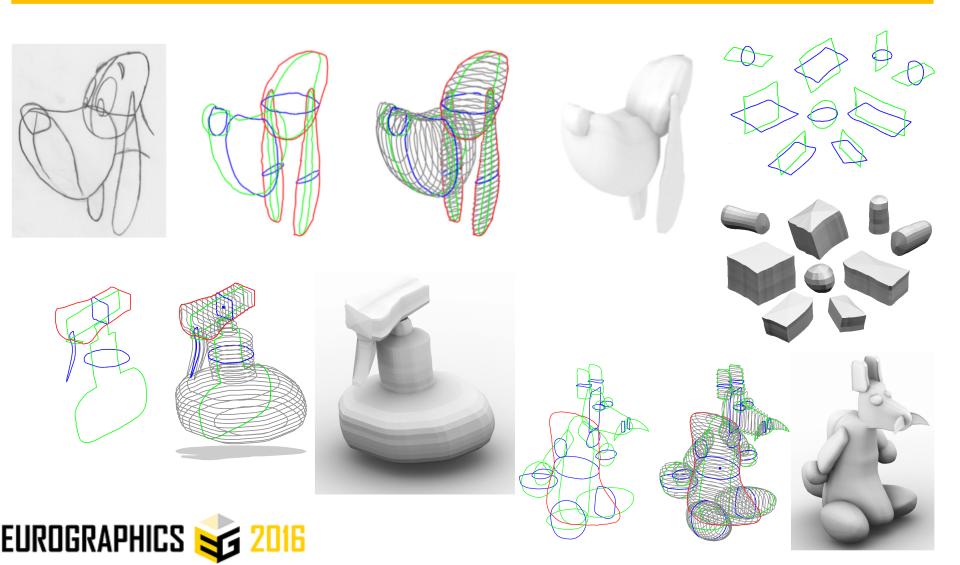


Which we can use to sweep out a surface



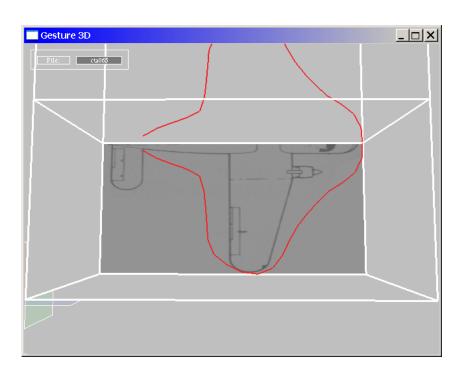






### A suggestive interface for image guided 3D sketching [Tsang et al. 2004]

Use the guide sketch to snap strokes.



User sketch

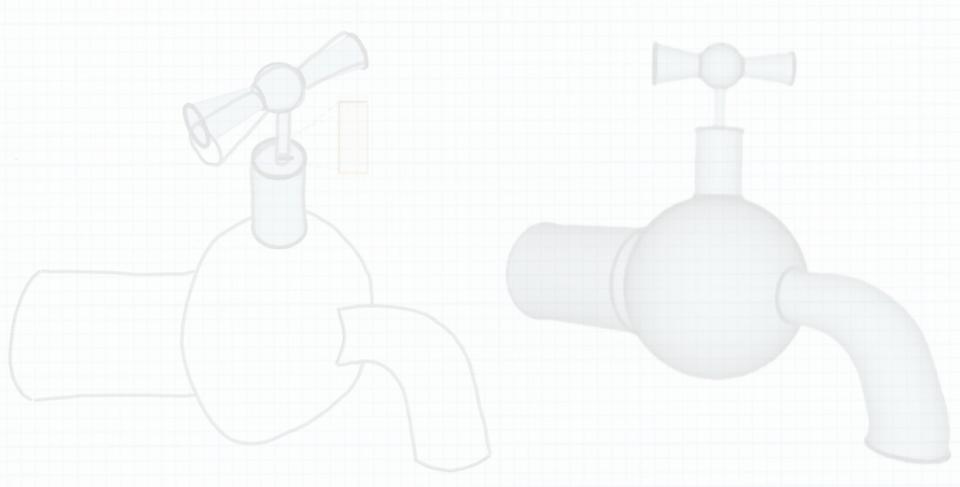


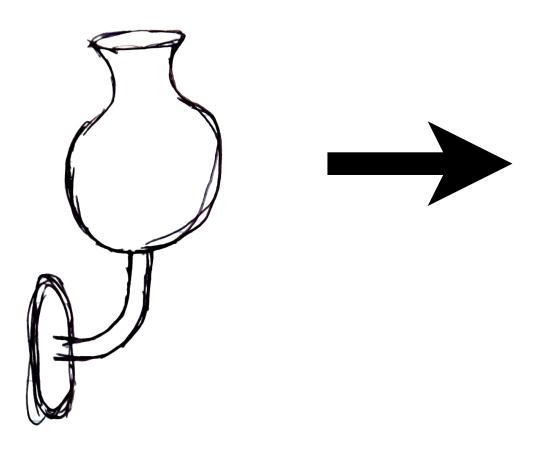
Automatically snapped to the guide image

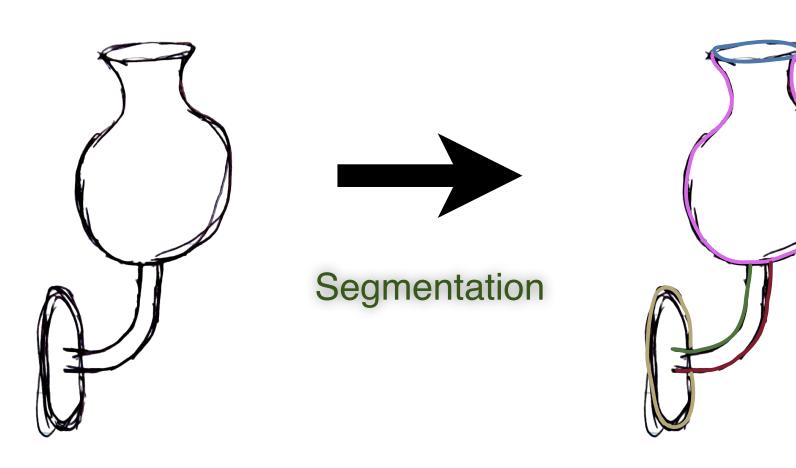


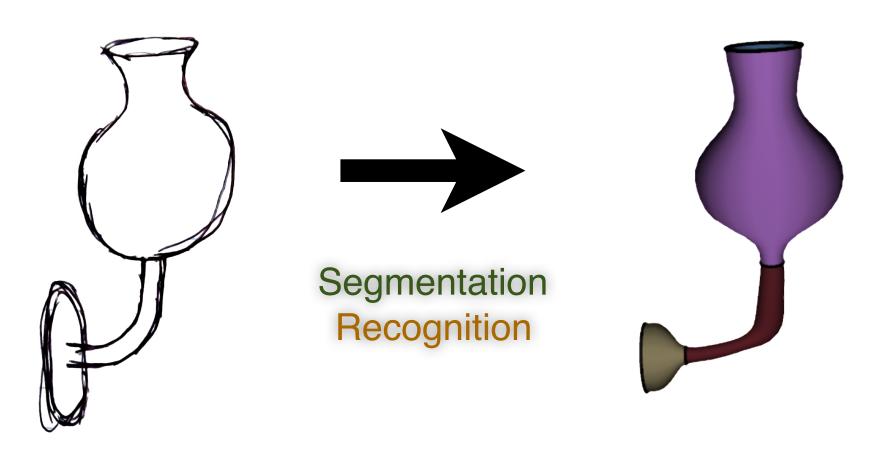
### Geosemantic Snapping for Sketch-Based Modeling

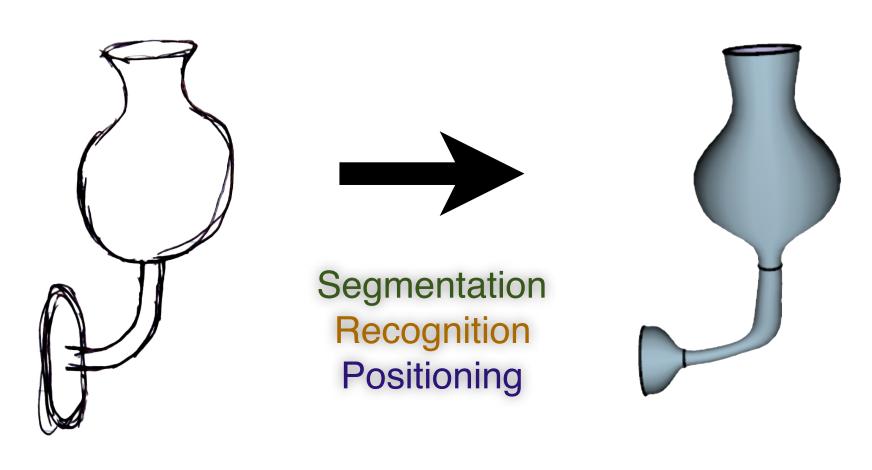
[Shtof et al. 2013]

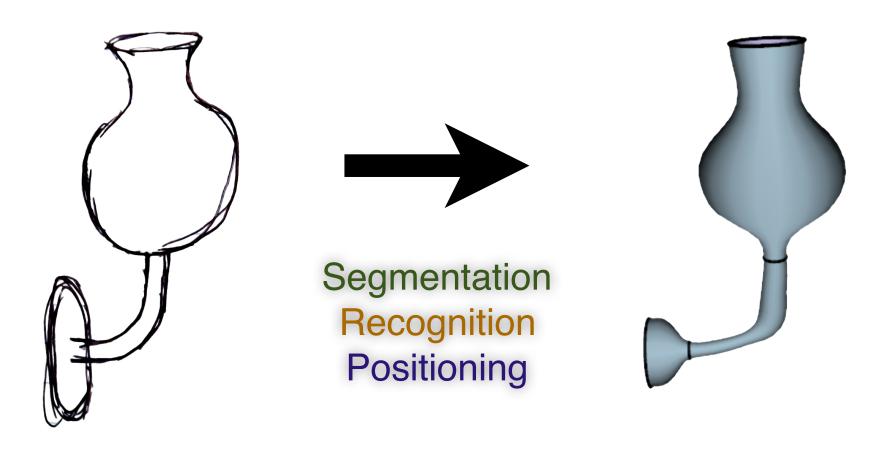






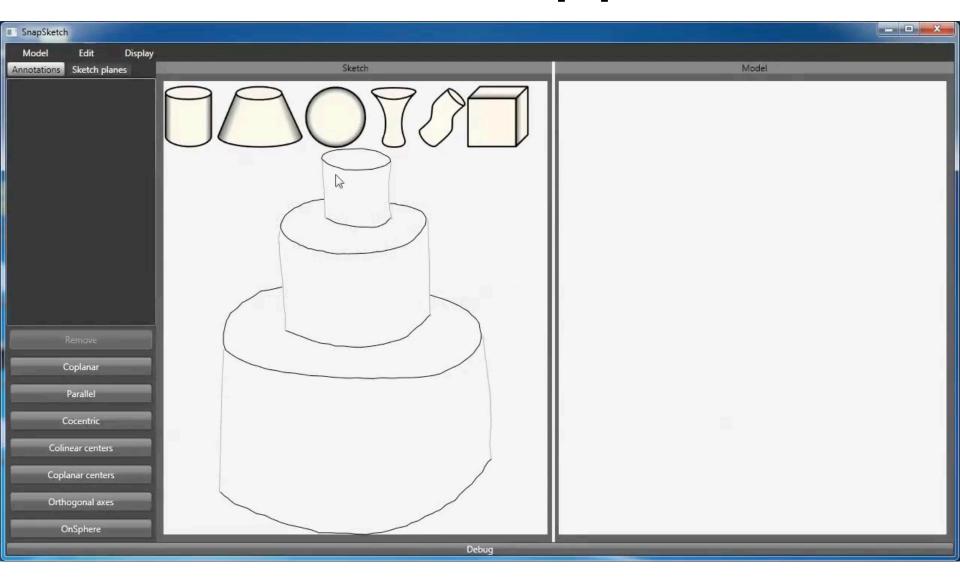






An automatic solution entails solving a **complex**, **non-convex** optimization problem with **many local minima**.

#### Interactive Approach



### Separate the problem into semantic and geometric tasks



**semantic**: interpreting the sketch's individual strokes and parts

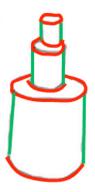


**geometric**: fitting and reconstructing precise geometry

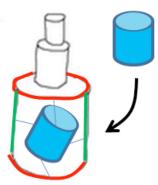
#### Overview



input Skotch



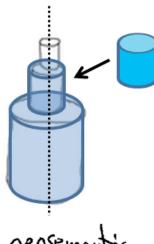
semantic classification



interactive matching

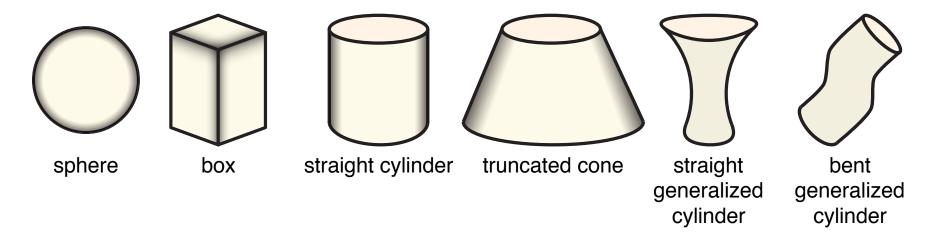


real-time Snapping

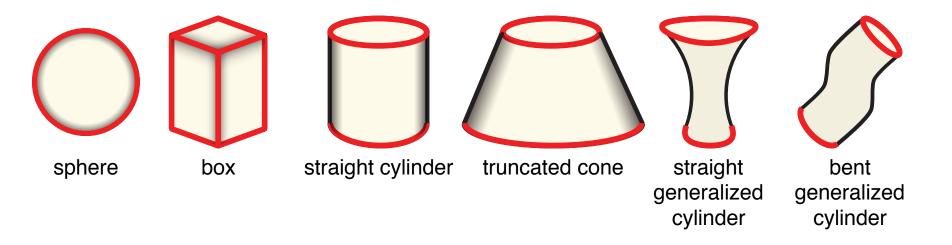


geosemantic Snapping

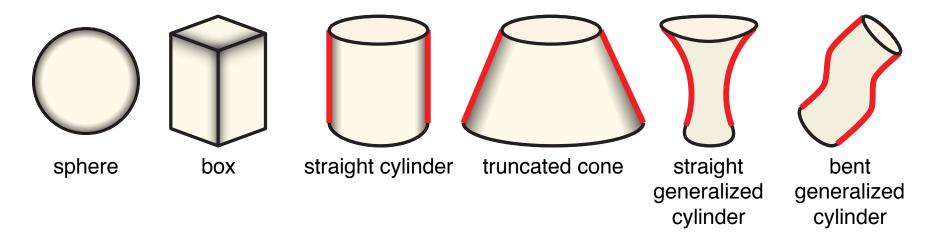
#### Primitives



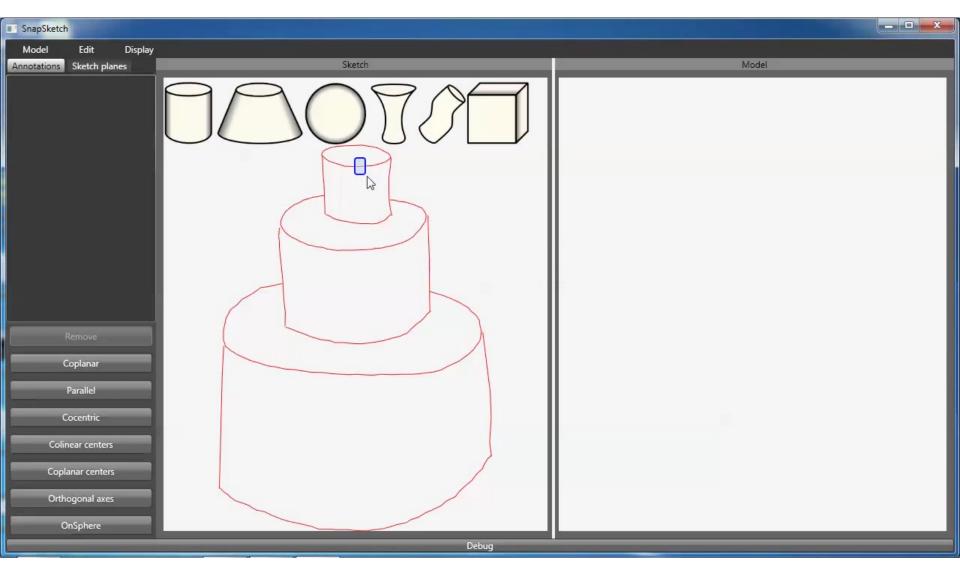
#### Primitives: Feature Curves



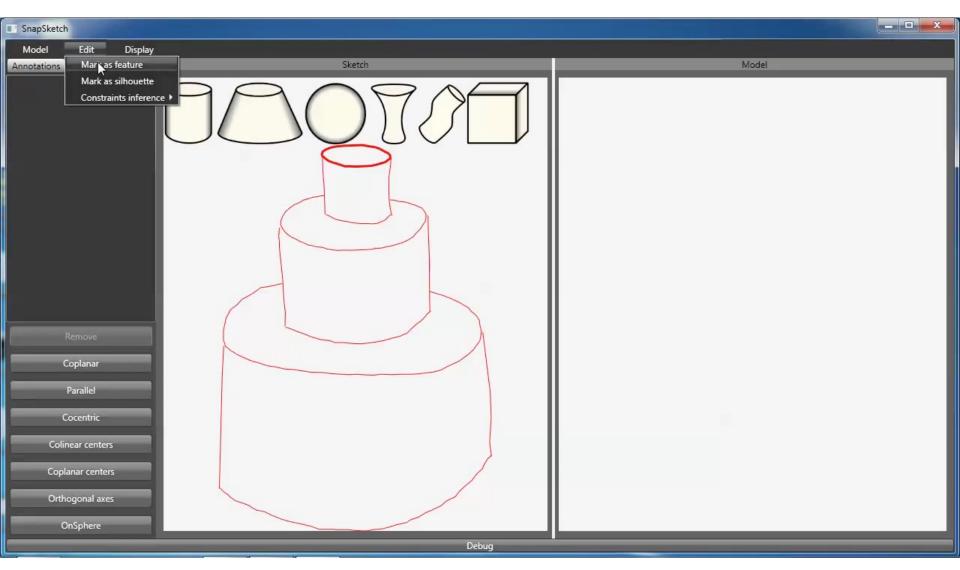
## Primitives: Silhouette Curves



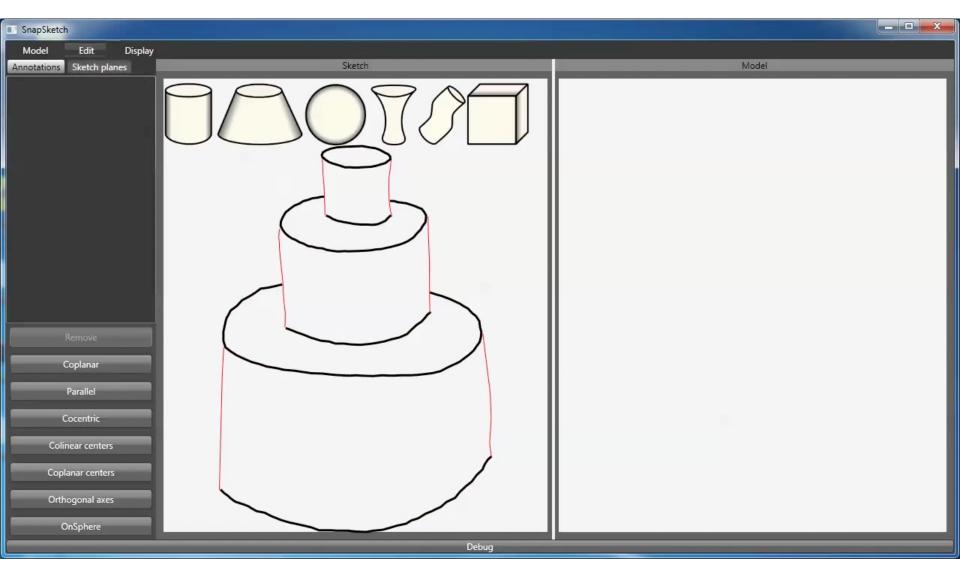
### Tagging



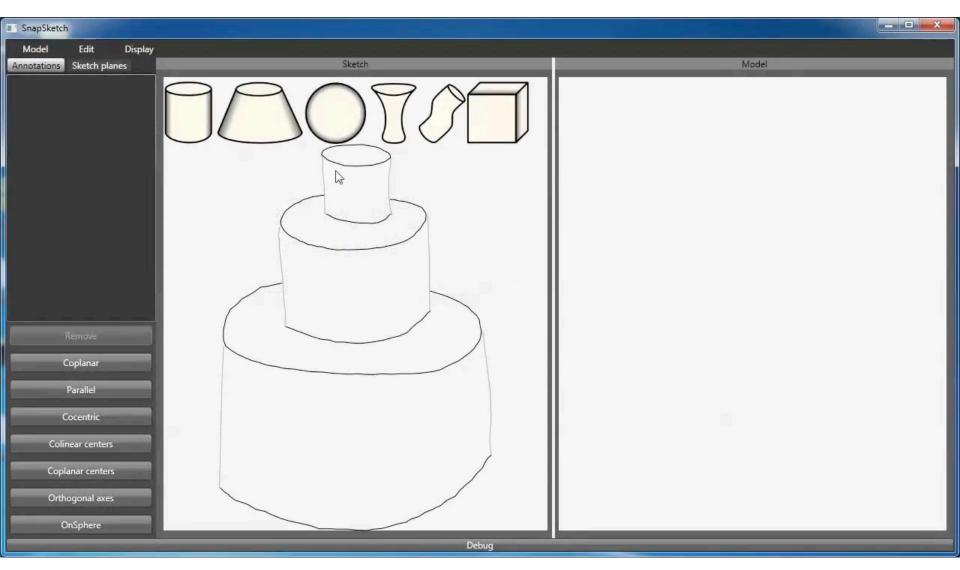
### Tagging

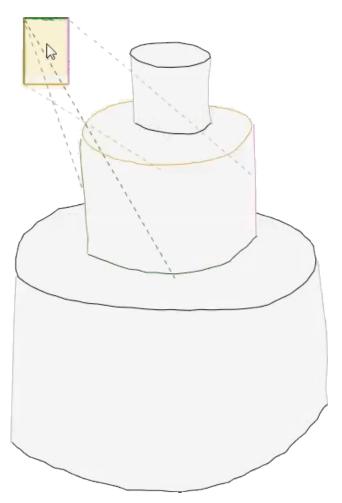


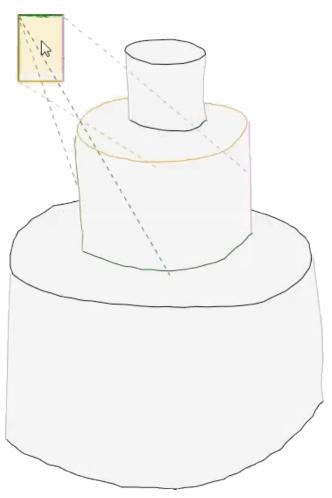
### Tagging

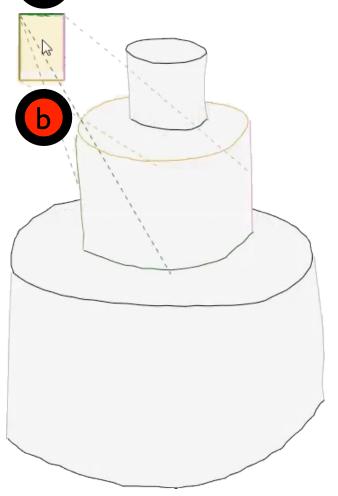


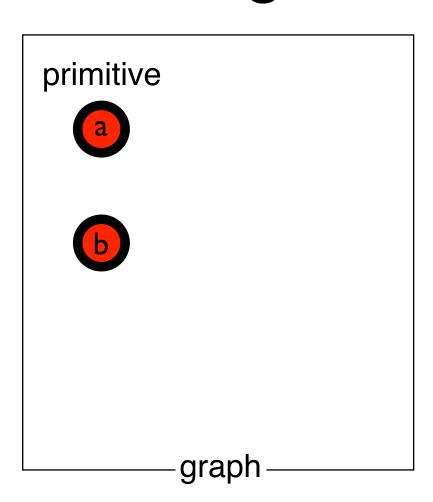
#### Drag-and-Drop

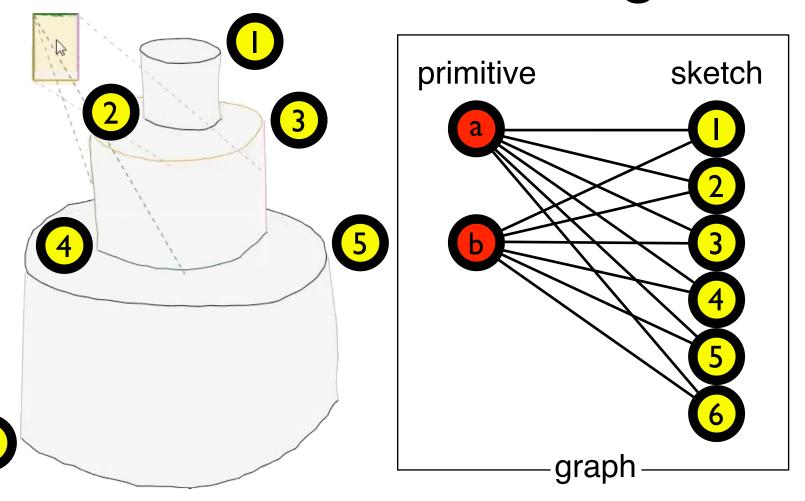


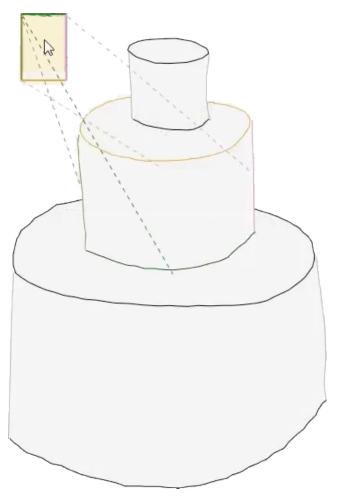


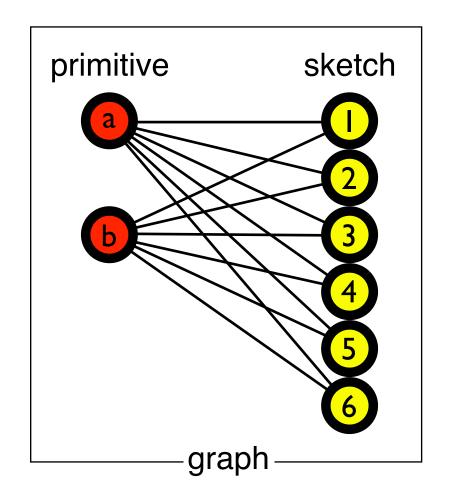


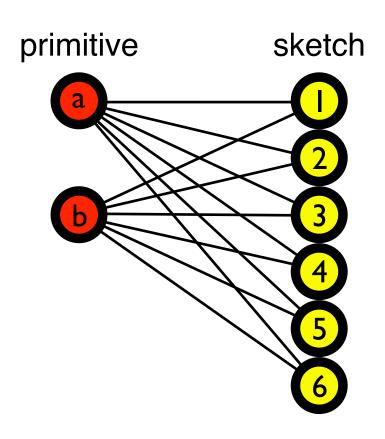


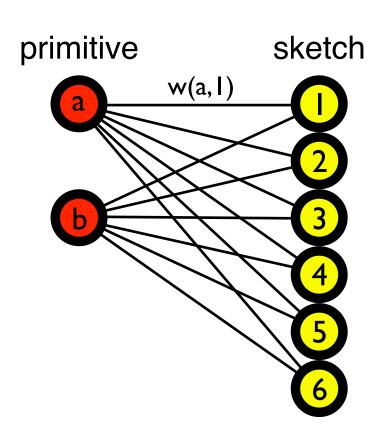


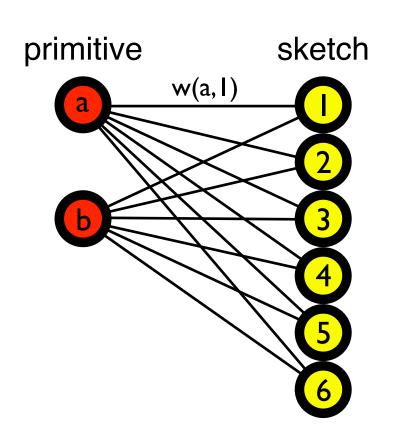


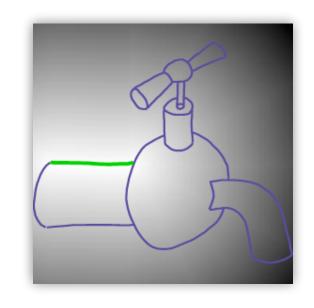


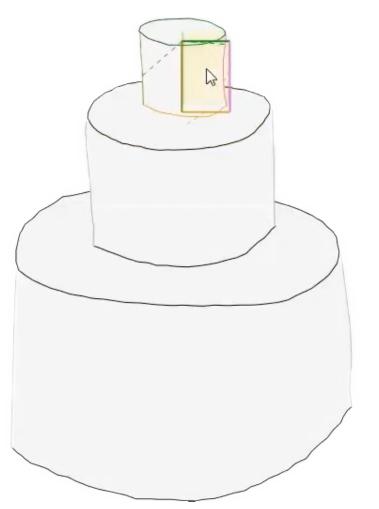




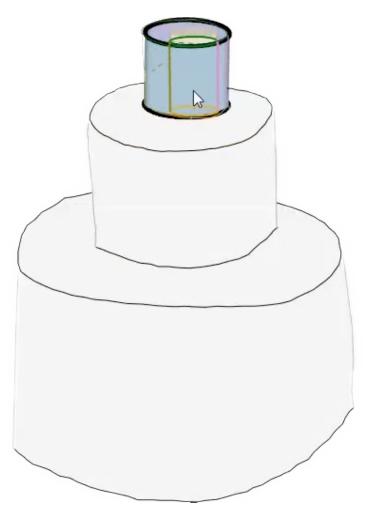




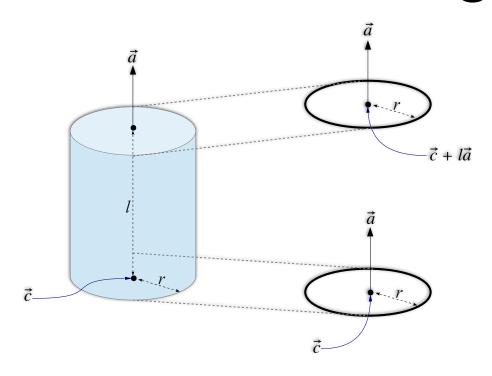




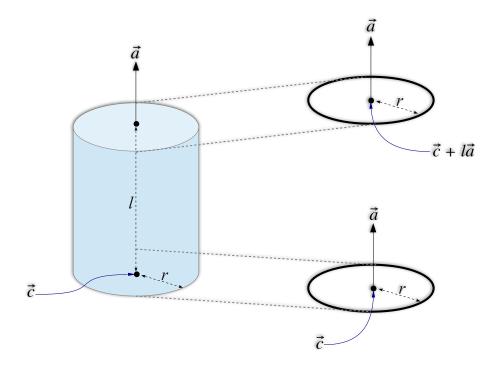
# Anatomy of a Drag: Primitive Fitting



# Anatomy of a Drag: Primitive Fitting

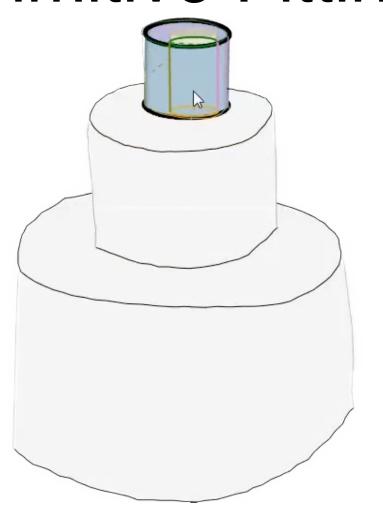


### Anatomy of a Drag: Primitive Fitting

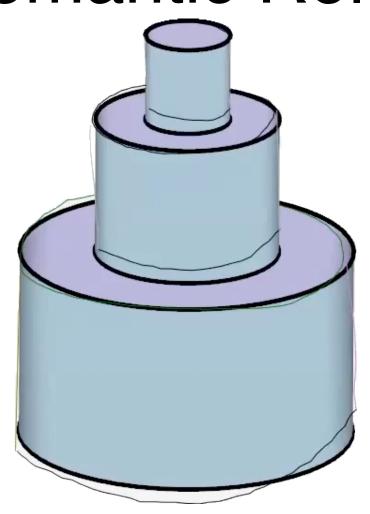


 $min: \phi_p(x_p)$   $s.t.: C_p(x_p) = 0$ 

# Anatomy of a Drag: Primitive Fitting

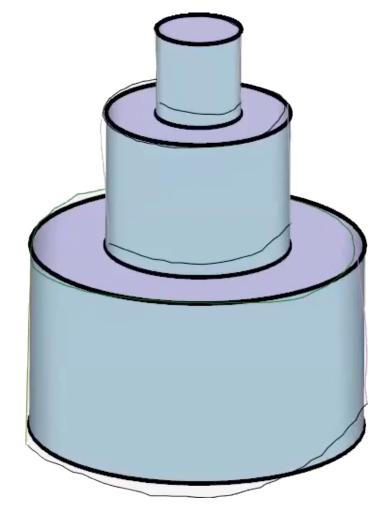


### Anatomy of a Drag: Geosemantic Relations

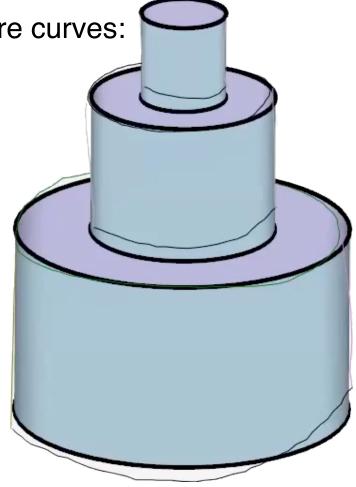


### Anatomy of a Drag: Geosemantic Relations

 $\begin{aligned} & \underset{x}{min}: & \sum_{p \in P} \phi_p(x_p) \\ & s.t.: & C_p(x_p) = 0 & \forall p \in P \\ & \psi_g(x_g) = 0 & \forall g \in G \end{aligned}$ 

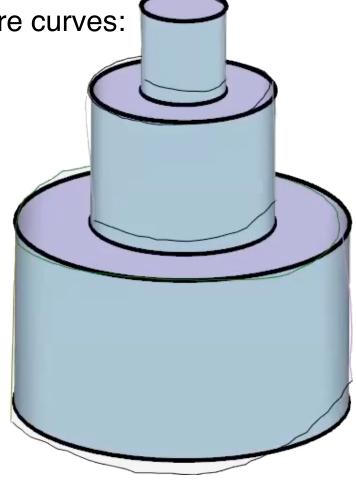


Constraints linking two or more feature curves:



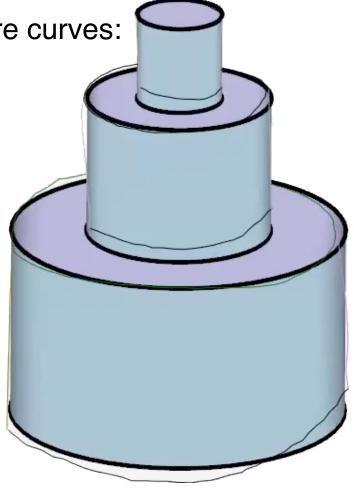
Constraints linking two or more feature curves:

· Parallelism



Constraints linking two or more feature curves:

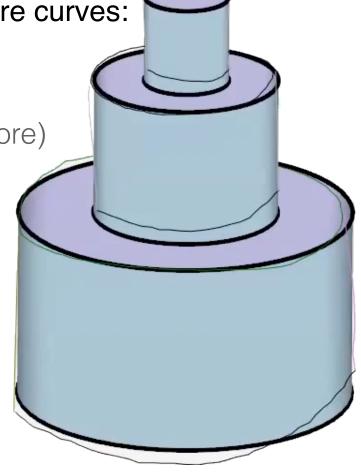
- · Parallelism
- · Orthogonality



Constraints linking two or more feature curves:

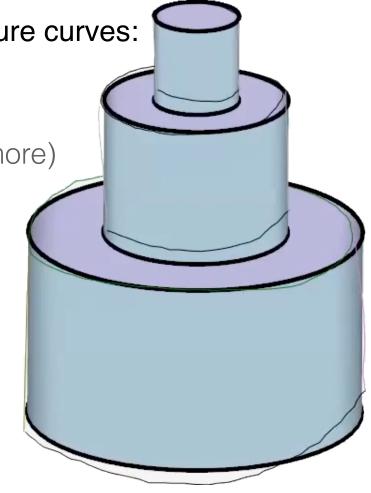
- · Parallelism
- Orthogonality

· Collinear centers (three or more)



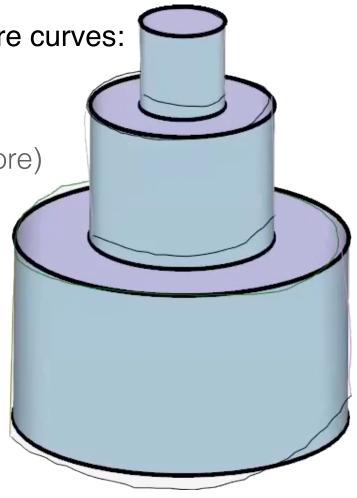
Constraints linking two or more feature curves:

- · Parallelism
- Orthogonality
- · Collinear centers (three or more)
- · Concentric

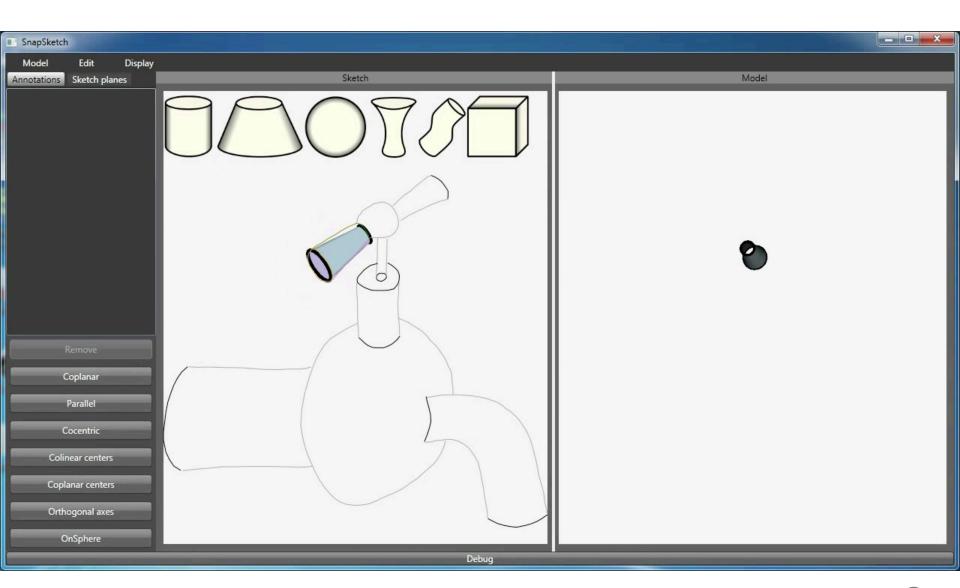


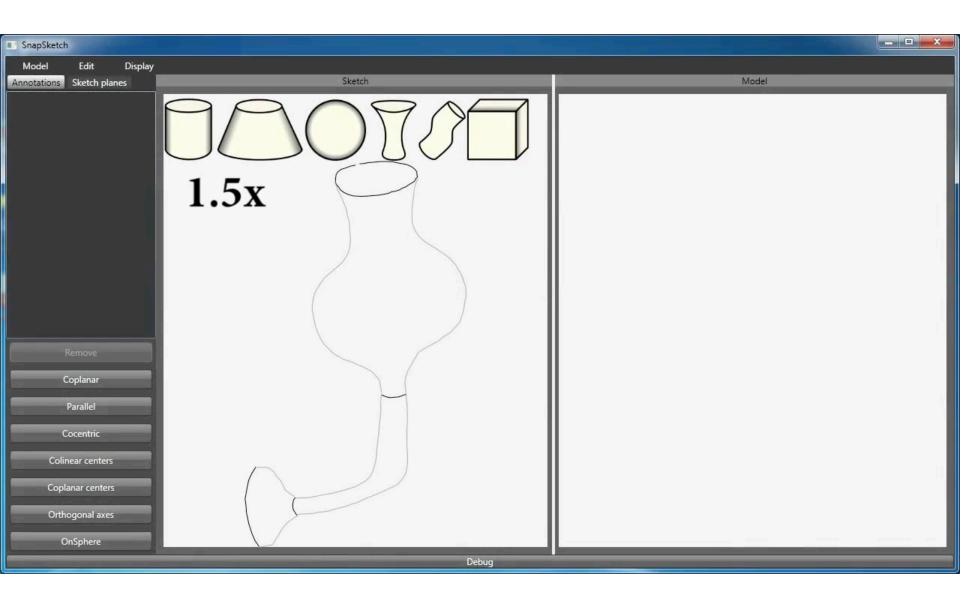
Constraints linking two or more feature curves:

- · Parallelism
- Orthogonality
- · Collinear centers (three or more)
- · Concentric
- · Coplanar

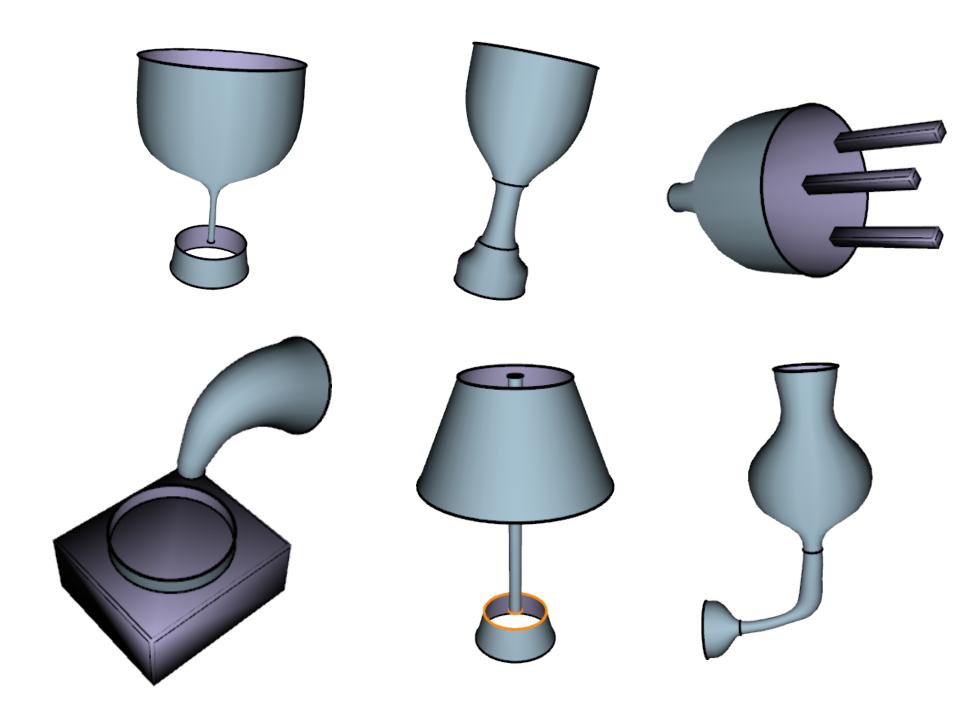


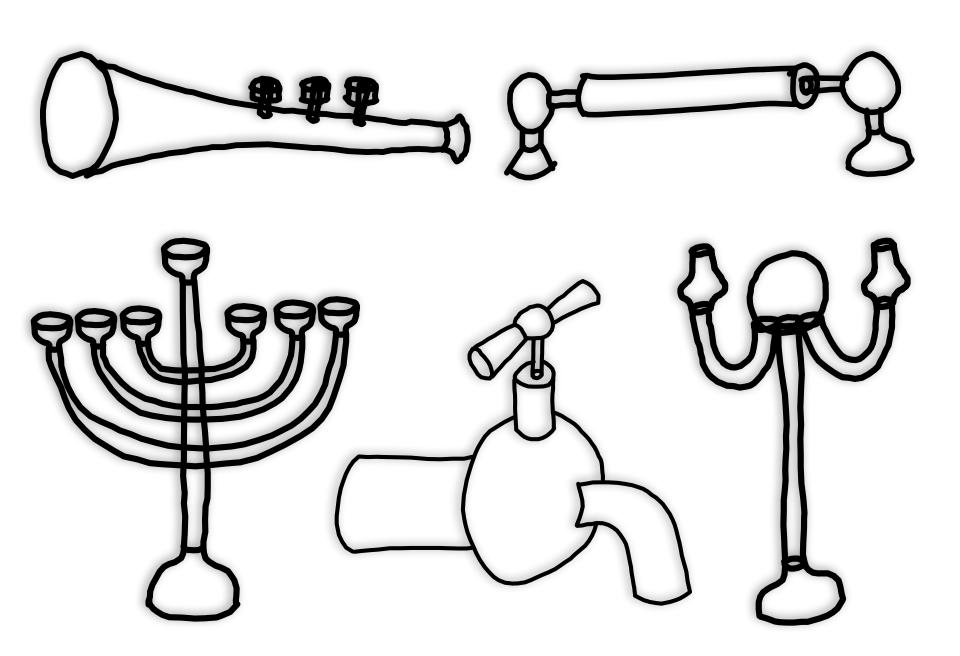
#### Results

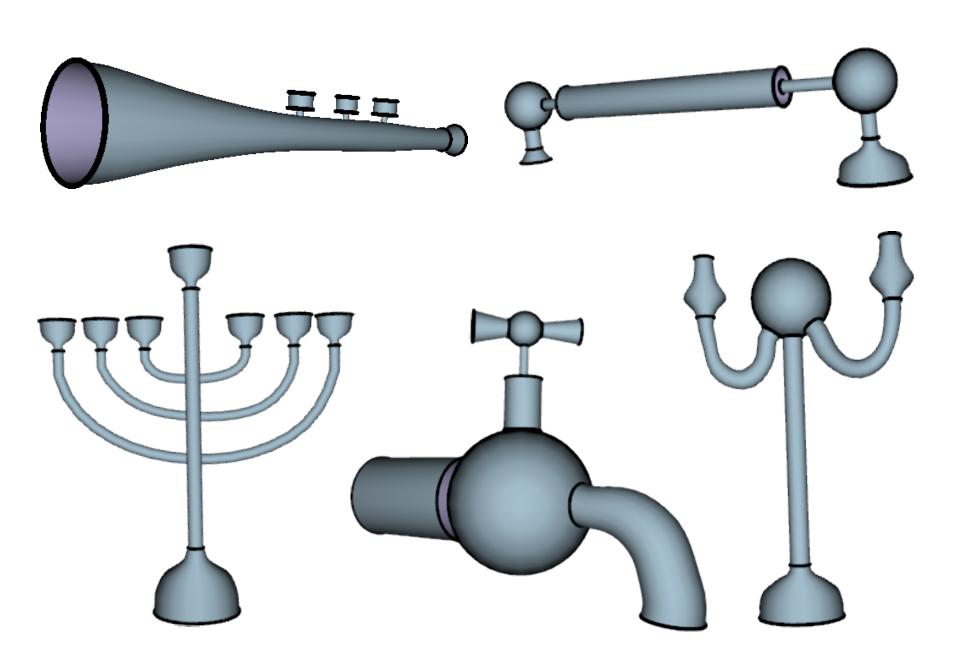


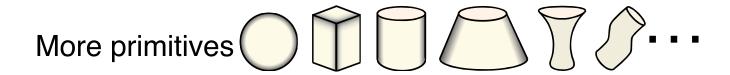








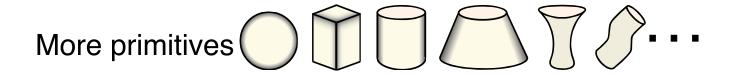




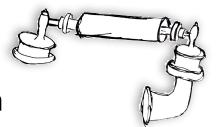
Operate directly on raster sketches



Eliminate sketch curve classification



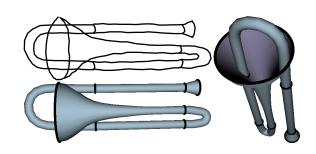
Operate directly on raster sketches



Eliminate sketch curve classification

Sketched occlusions

More geosemantic relations



Make a highly **non-convex** problem tractable by:

· Introducing an interactive solution.

- · Introducing an interactive solution.
- Separating that which is easy for a human and challenging for a computer.

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- Separating that which is easy for a human and challenging for a computer.
- Providing a good starting point via drag-anddrop.

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- Providing a flexible collection of parameterized **primitives**.

- · Introducing an interactive solution.
- Separating that which is easy for a human and challenging for a computer.
- Providing a good starting point via drag-anddrop.
- Providing a flexible collection of parameterized **primitives**.
- Inferring geosemantic relationships for aligning primitives and placing them in depth.

#### Lifting curve networks into 3D

#### Interactively

 Analytic drawing of 3D scaffolds [Schmidt et al. 2009]

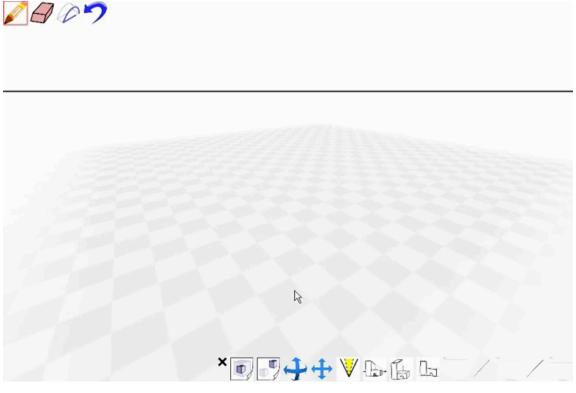
#### Automatically

- CrossShade: Shading Concept Sketches Using Cross-Section Curves [Shao et al. 2012]
- True2Form: 3D curve networks from 2D sketches via selective regularization [Xu et al. 2014]



# Analytic drawing of 3D scaffolds [Schmidt et al. 2009]

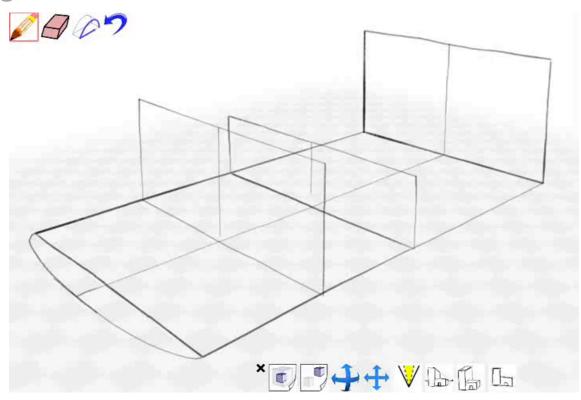
 Draw precise scaffold lines by connecting them to 2-point perspective vanishing points





# Analytic drawing of 3D scaffolds [Schmidt et al. 2009]

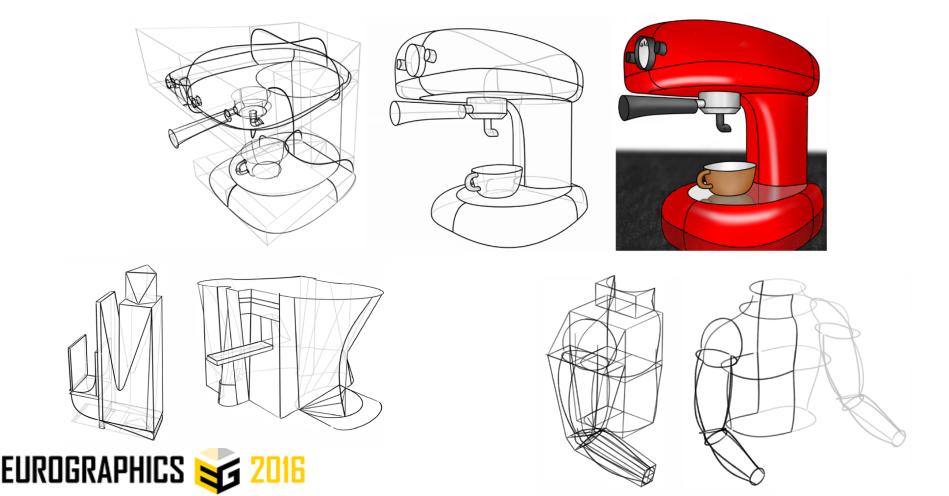
The scaffolds make it possible to draw complex curves





# Analytic drawing of 3D scaffolds [Schmidt et al. 2009]

• ... and complex shapes



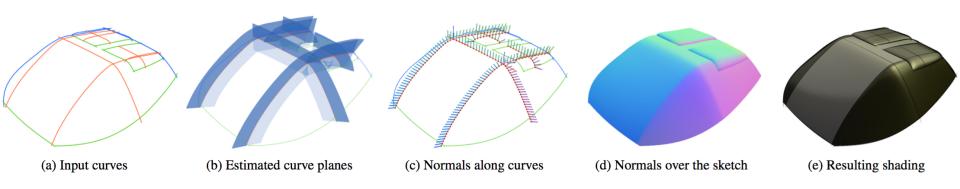
# CrossShade: Shading Concept Sketches Using Cross-Section Curves [Shao et al. 2012]

- We can infer a good normal map from labeled cross section and silhouette curves via properties of designer-drawn cross sections.
   Cross-sections:
  - intersect on orthogonal planes
  - are aligned with principal curvature (and therefore are orthogonal themselves)
  - are geodesics
  - intersect with minimal foreshortening



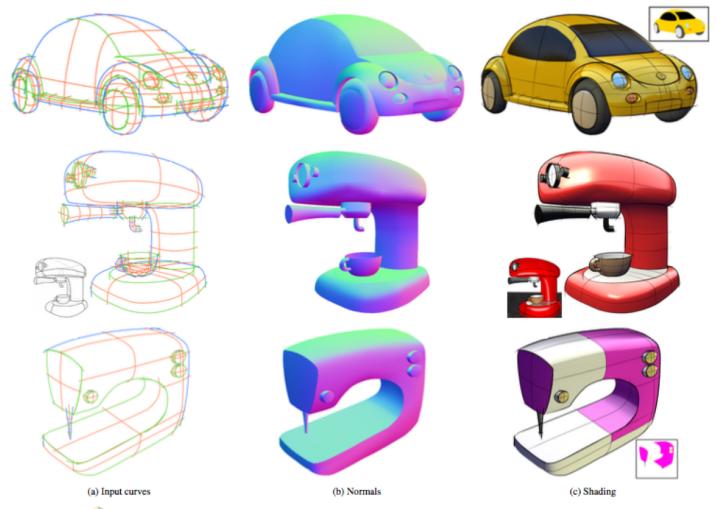
# CrossShade: Shading Concept Sketches Using Cross-Section Curves [Shao et al. 2012]

 With these cues, we can propagate normals everywhere:





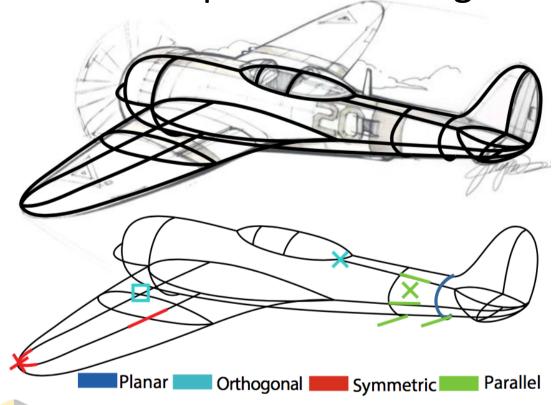
## CrossShade: Shading Concept Sketches Using Cross-Section Curves [Shao et al. 2012]





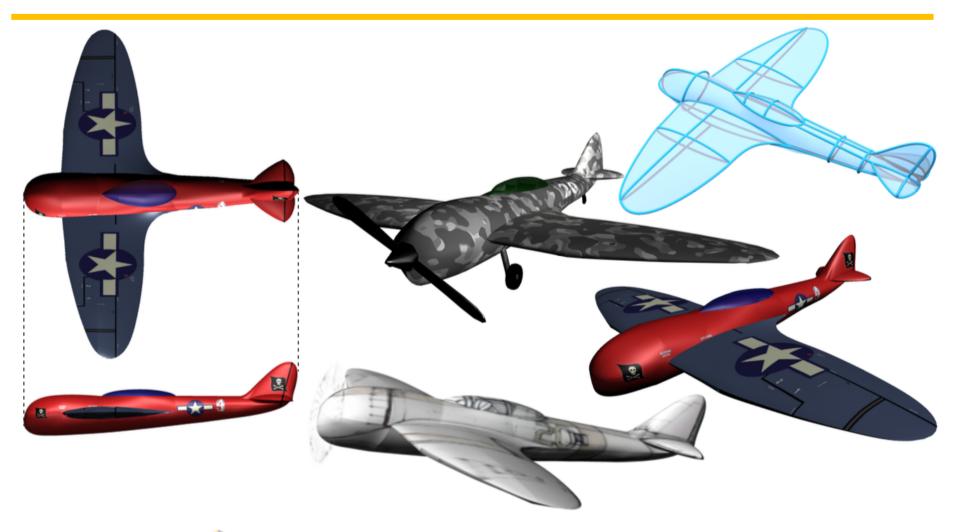
### True2Form: 3D curve networks from 2D sketches via selective regularization [Xu et al. 2014]

 Given 2D curves, we can selectively apply the constraints in an optimization to get 3D curves



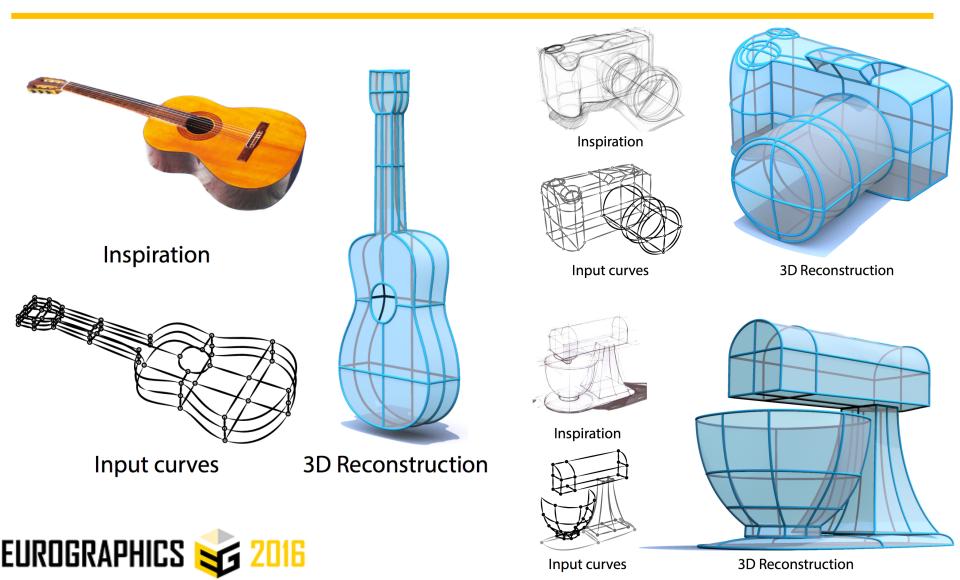


### True2Form: 3D curve networks from 2D sketches via selective regularization [Xu et al. 2014]





#### True2Form: 3D curve networks from 2D sketches via selective regularization [Xu et al. 2014]



#### **Takeaways**

- Make "intractable" problems tractable with perceptually grounded assumptions or by asking the user to help.
  - Don't ask the user for too much. Separate that which is easy for a human and challenging for a computer.
- Consult artistic practice and perceptual psychology for inspiration.



#### References

[Cherlin et al 2005] Joseph Jacob Cherlin, Faramarz Samavati, Mario Costa Sousa, Joaquim A. Jorge. Sketch-based modeling with few strokes. SCCG 2005: 137-145

[Gingold et al 2009] Yotam I. Gingold, Takeo Igarashi, Denis Zorin: Structured annotations for 2D-to-3D modeling. ACM Trans. Graph. 28(5): 148:1-148:9 (2009)

[Vilppu 1997] VILPPU, G. 1997. Vilppu Drawing Manual. Vilppu Studio, Acton, California.

[Blair 1994] BLAIR, P. 1994. Cartoon Animation. Walter Foster, Laguna Hills, California



#### References

[Schmidt et al. 2009b] Ryan Schmidt, Azam Khan, Karan Singh, Gordon Kurtenbach: Analytic drawing of 3D scaffolds. ACM Trans. Graph. 28(5): 149:1-149:10 (2009)

[Andre and Saito 2011] Alexis Andre, Suguru Saito: Single-View Sketch Based Modeling. SBM 2011: 133-140

[Tsang et al. 2004] Steve Tsang, Ravin Balakrishnan, Karan Singh, Abhishek Ranjan: A suggestive interface for image guided 3D sketching. CHI 2004: 591-598



#### References

[Shtof et al. 2013] Alex Shtof, Alexander Agathos, Yotam I. Gingold, Ariel Shamir, Daniel Cohen-Or: Geosemantic Snapping for Sketch-Based Modeling. Comput. Graph. Forum 32(2): 245-253 (2013)

[Shao et al. 2012] Cloud Shao, Adrien Bousseau, Alla Sheffer, Karan Singh: CrossShade: shading concept sketches using cross-section curves. ACM Trans. Graph. 31(4): 45:1-45:11 (2012)

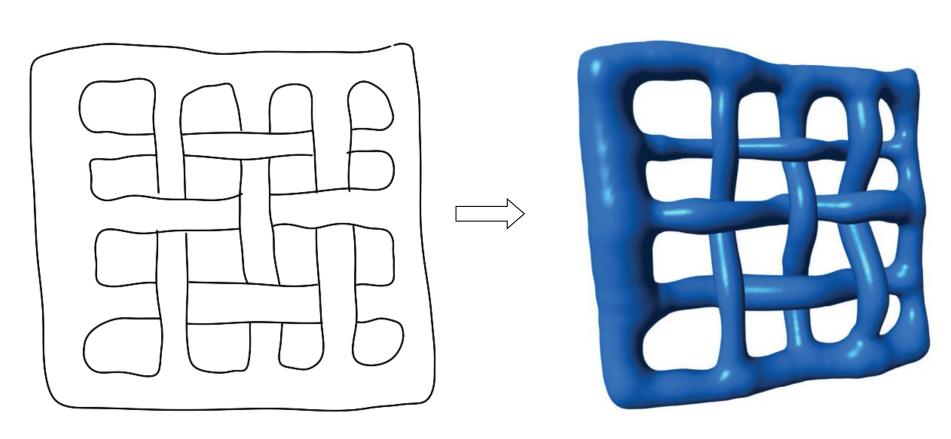
[Xu et al. 2014] Bao-Xuan Xu, William Chang, Alla Sheffer, Adrien Bousseau, James McCrae, Karan Singh: True2Form: 3D curve networks from 2D sketches via selective regularization. ACM Trans. Graph. 33(4): 131:1-131:13 (2014)



# Single-view sketch-based modeling of 3D curves and surfaces Part II

Frederic Cordier

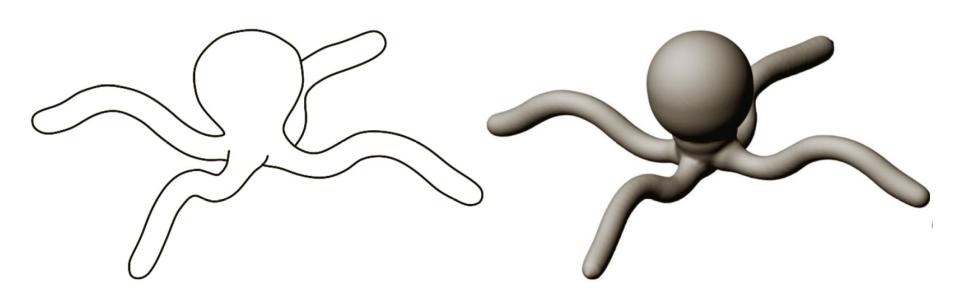
# Free-Form Sketching of Self-Occluding Objects



Frederic Cordier, Hyewon Seo: Free-Form Sketching of Self-Occluding Objects. IEEE Computer Graphics and Applications 27(1): 50-59 (2007)

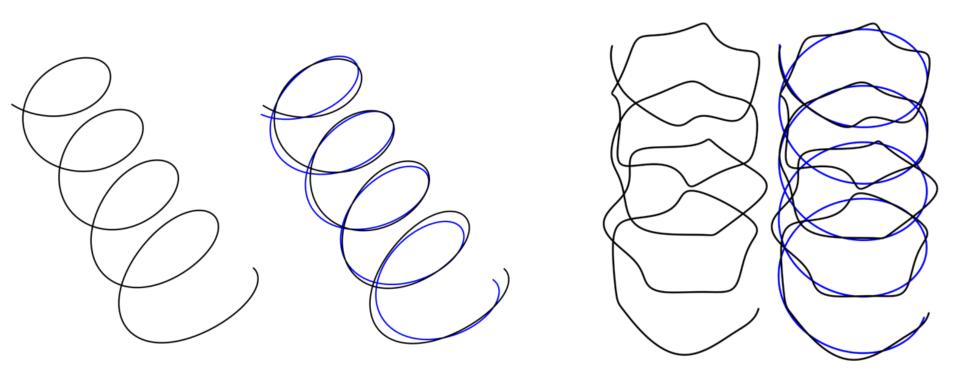


#### Sketching of Mirror-Symmetric Shapes



Frederic Cordier, Hyewon Seo, Jinho Park, Jun-yong Noh: Sketching of Mirror-Symmetric Shapes. IEEE Trans. Vis. Comput. Graph. 17(11): 1650-1662 (2011)

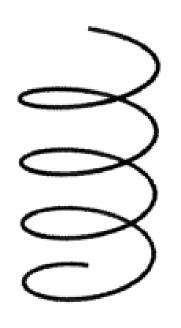




Frederic Cordier, Mahmoud Melkemi, Hyewon Seo: Reconstruction of helices from their orthogonal projection. Computer Aided Geometric Design. In press.



Reconstruction of curves of constant curvature

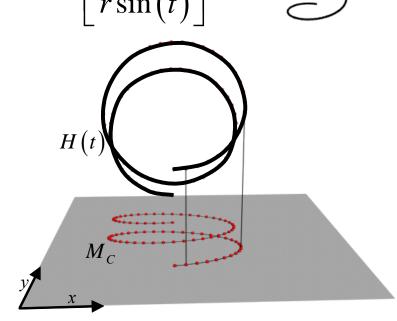




Parametric equation of a helix of radius r and pitch p:

 $H(t) = \begin{bmatrix} r\cos(t) \\ pt \\ r\sin(t) \end{bmatrix}$ 

Computing *r*, *p* and the projection matrix requires non-linear optimization!

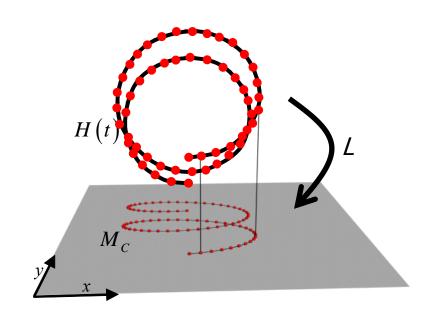




Sampling of the helix

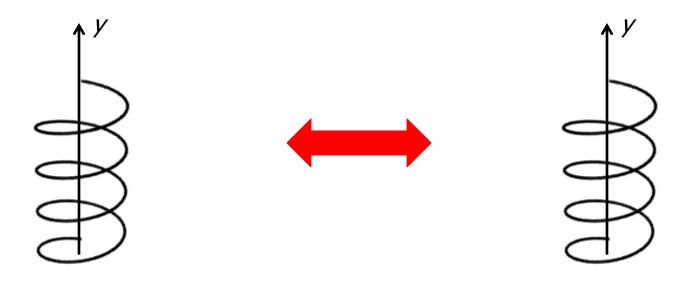
Compute the affine transformation *L* 

Compute the rotation matrix and the helix parameters





#### The key idea:

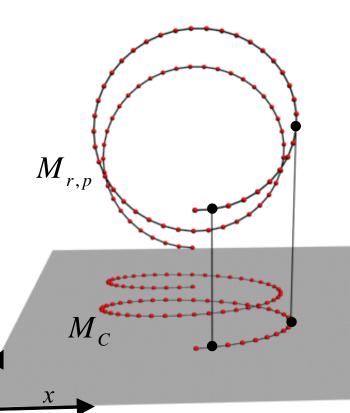


Pitch equal to 1
Scale along y equal to 2

Pitch equal to 2
Scale along y equal to 1



#### Sampling of the helix



$$M_{r,p} = \begin{bmatrix} r\cos(t_1) & pt_1 & r\sin(t_1) \\ r\cos(t_2) & pt_2 & r\sin(t_2) \\ \vdots & \vdots & \vdots \\ r\cos(t_n) & pt_n & r\sin(t_n) \end{bmatrix} = M_U S_{rp}$$

$$M_{U} = \begin{bmatrix} \cos(t_{1}) & t_{1} & \sin(t_{1}) \\ \cos(t_{2}) & t_{2} & \sin(t_{2}) \\ \vdots & \vdots & \vdots \\ \cos(t_{n}) & t_{n} & \sin(t_{n}) \end{bmatrix} \quad S_{rp} = \begin{bmatrix} r & 0 & 0 \\ 0 & p & 0 \\ 0 & 0 & r \end{bmatrix}$$



$$\min_{L} \|M_U L - M_C\|_F^2 \qquad \text{Affine transformation} \\ \bullet \quad \text{Rotation} \\ \bullet \quad \text{Shear} \\ \bullet \quad \text{Scale...}$$

$$\|M_{U}L - M_{C}\|_{F}^{2} = \|(M_{U}S_{rp})(S_{rp}^{-1}L) - M_{C}\|_{F}^{2}$$

Should be close to orthonormal (i.e. rotation matrix)

Key idea: changing the scaling transformation of the helix is equivalent to changing its radius and pitch EUROGRAPHICS 2016

 $\left(S_{rp}^{-1}L\right)$  is a matrix with orthonormal columns if

$$\left(S_{rp}^{-1}L\right)^{T}\left(S_{rp}^{-1}L\right) = I$$

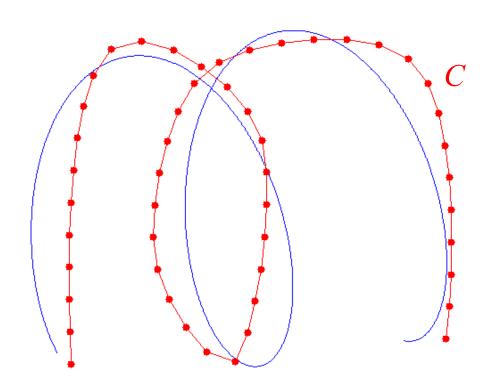
We solve

$$\min_{r,p} \left\| \left( S_{rp}^{-1} L \right)^T \left( S_{rp}^{-1} L \right) - I \right\|_F^2$$

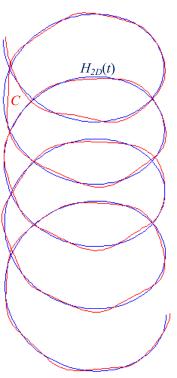
#### Advantages:

- Method that requires solving simple linear systems
- Much faster than using non-linear optimization
- Provides an approximate solution which is very close to the exact solution

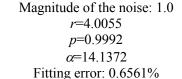




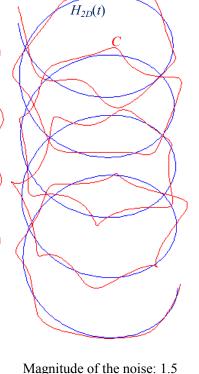




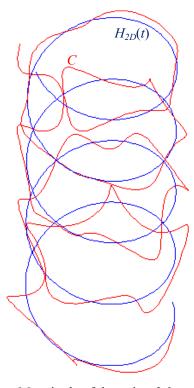
Magnitude of the noise: 0.5 r=4.0076 p=0.9879  $\alpha$ =14.1372 Fitting error: 0.2586%



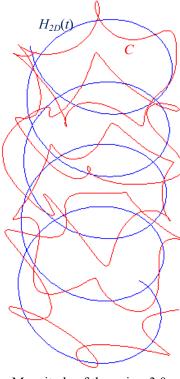
 $H_{2D}(t)$ 



r=3.9417 p=0.9603  $\alpha$ =14.0744 Fitting error: 0.7880%



Magnitude of the noise: 2.0 r=3.7610 p=1.0684  $\alpha=14.0115$  Fitting error: 1.0579%

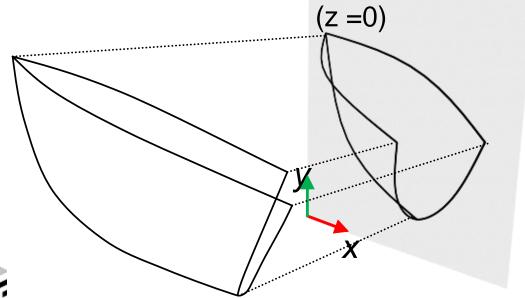


Magnitude of the noise: 3.0 r=3.8014 p=1.0714  $\alpha=14.4514$  Fitting error: 2.6036%

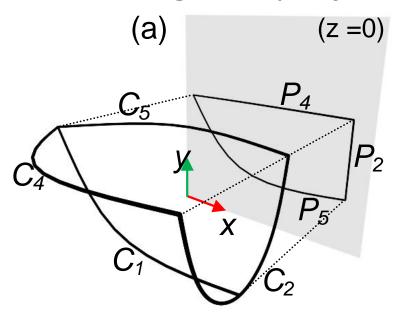


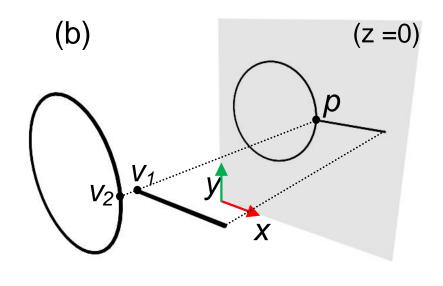
- Input: the 2D sketch of a mirror-symmetric 3D shape
- Output: a set of 3D curves such that their orthogonal projection matches the input sketch

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- Assumptions:
- Mirror-symmetric shape composed of curves
- Orthogonal projection

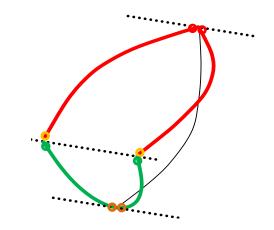




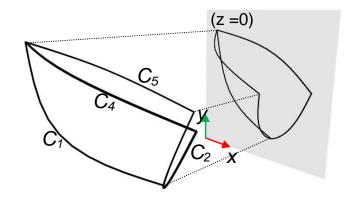


#### Overview

Finding pairs of symmetric curves:



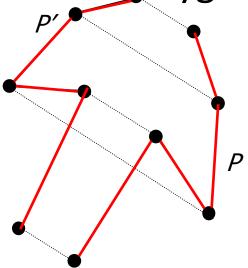
• 3D reconstruction:



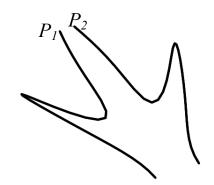


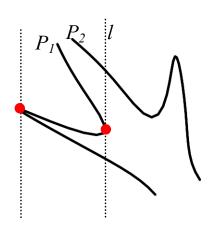
Properties of symmetric polygons

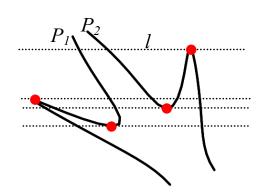
 P and P' are the orthogonal projections of a pair of symmetric 3D polygonal curves:

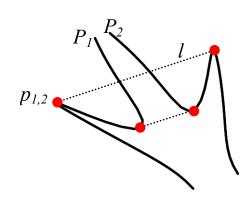


How to find that P1 is symmetric to P2?



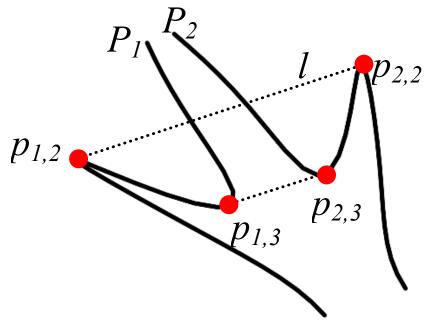






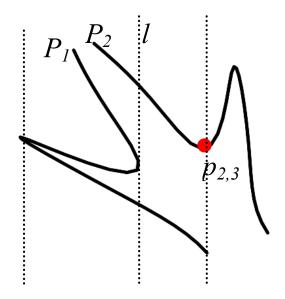


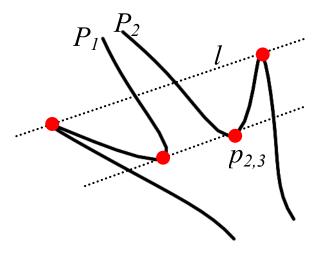
 A turn vertex is a vertex such that the two adjacent vertices are located in the same halfplane delimited by I.



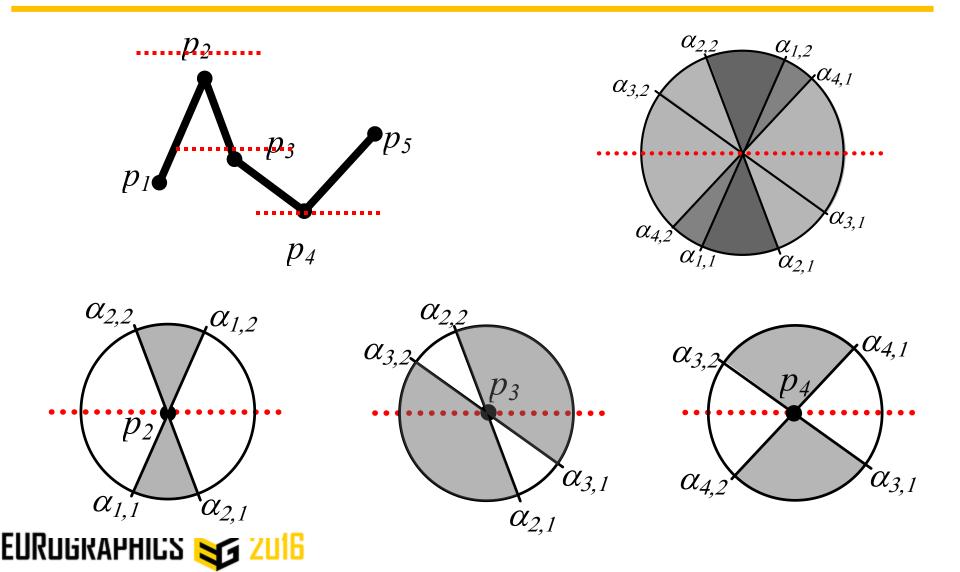


 A turn vertex is a vertex such that the two adjacent vertices are located in the same halfplane delimited by I.

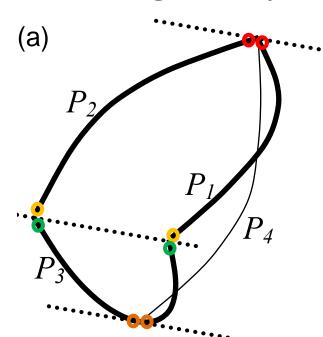




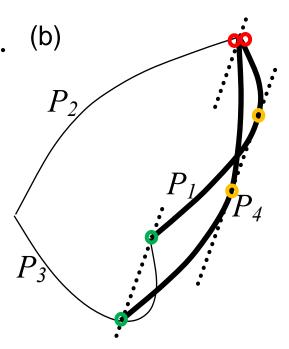




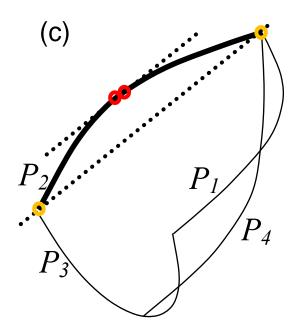
#### Finding the symmetric curves



 $P_1$  and  $P_2$  symmetric  $P_3$  self-symmetric  $P_4$  non-symmetric



 $P_1$  and  $P_4$  symmetric  $P_3$  and  $P_2$  non-symmetric

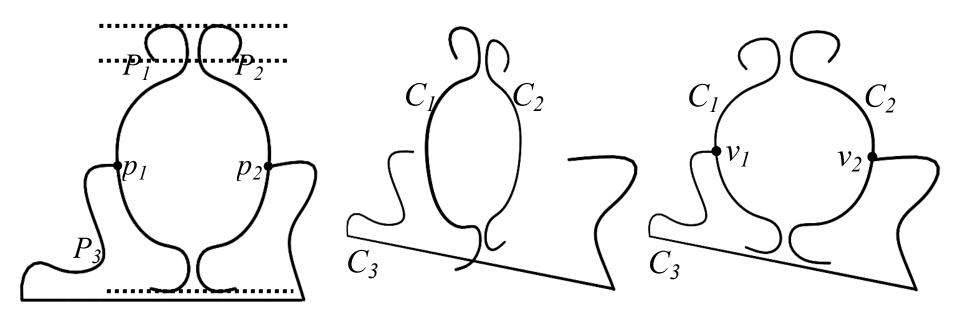


 $P_2$  self-symmetric  $P_1$ ,  $P_3$  and  $P_4$  nonsymmetric



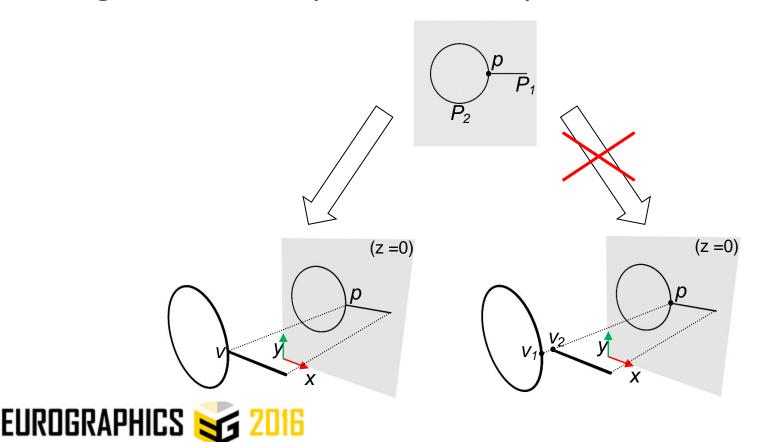
#### Computing the symmetry relationship

Unnatural 3D reconstruction

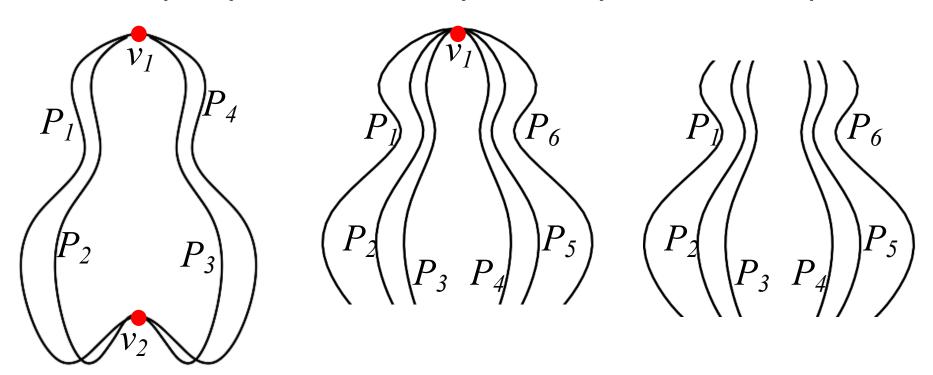




Exploiting the curve connectivity and the generic viewpoint assumption

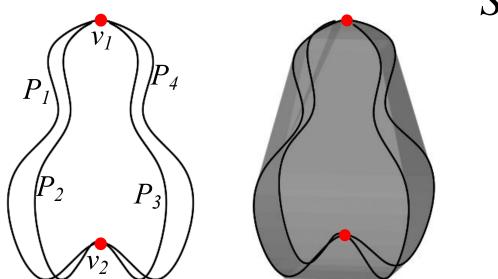


 The curve connectivity is not sufficient to uniquely define the symmetry relationship.



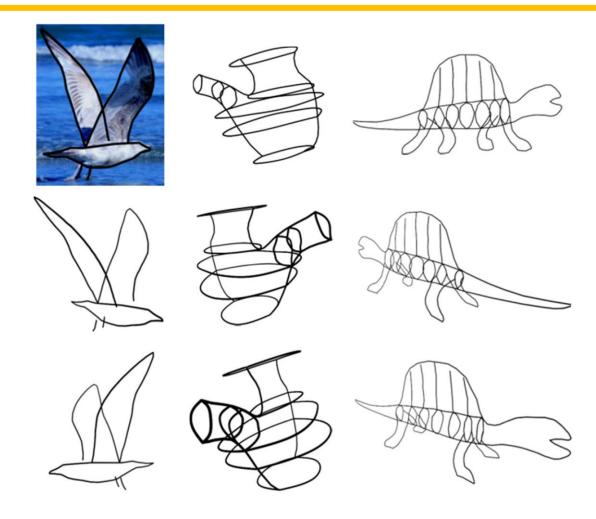


Maximizing the compactness of the reconstructed curves:  $C(O) = \frac{V(O)^2}{S(O)^3}$ 



Li Y, Pizlo Z, Steinman RM. A computational model that recovers the 3D shape 33 of an object from a single 2D retinal representation. Vision Research. 2009; 34 49(9):979–91.







#### Sketch-based editing

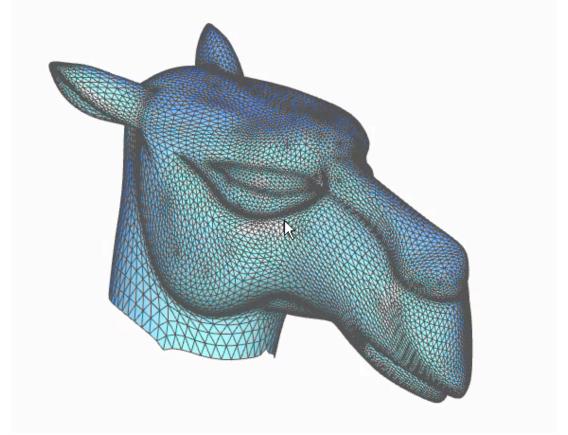
Yotam Gingold

#### **Editing operations**

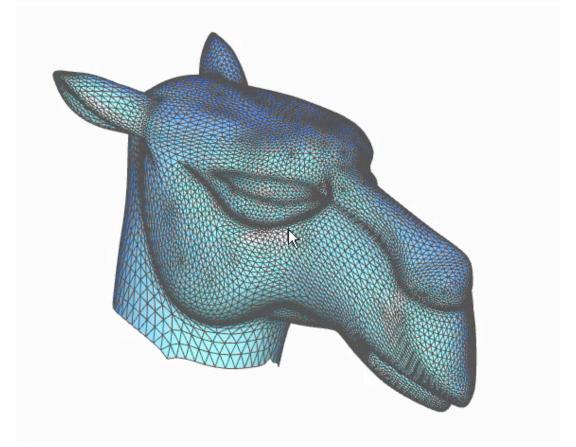
- Cutting (we saw earlier)
- Deform by sketching new silhouettes
- Edit relief by sketching shading

#### A Sketch-Based Interface for Detail-Preserving Mesh Editing [Nealen et al. 2005]

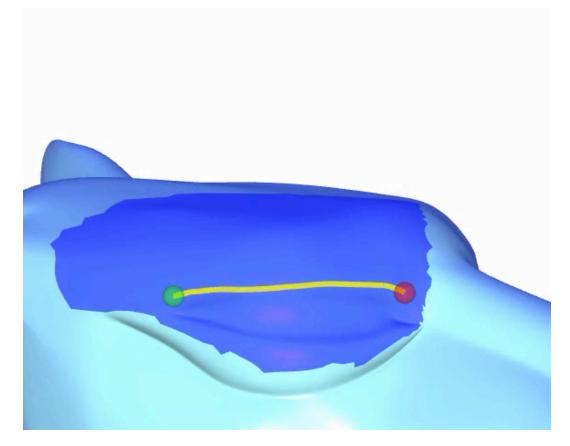
Silhouette editing



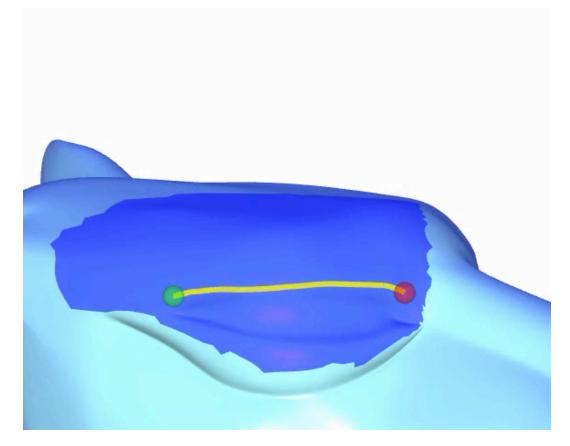
Silhouette editing



Silhouette creation



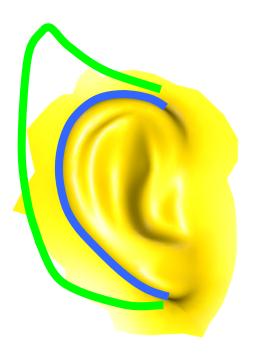
Silhouette creation



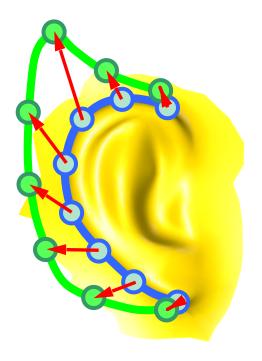
- To edit a silhouette:
  - Parameterize silhouette edges



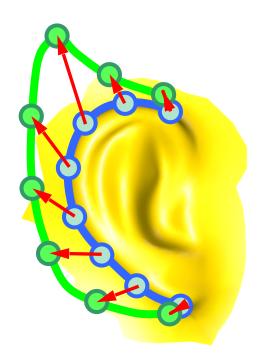
- To edit a silhouette:
  - Parameterize silhouette edges
  - Parameterize sketch



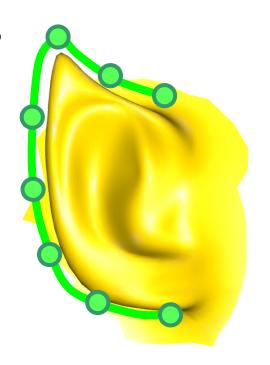
- To edit a silhouette:
  - Parameterize silhouette edges
  - Parameterize sketch
  - Find correspondences



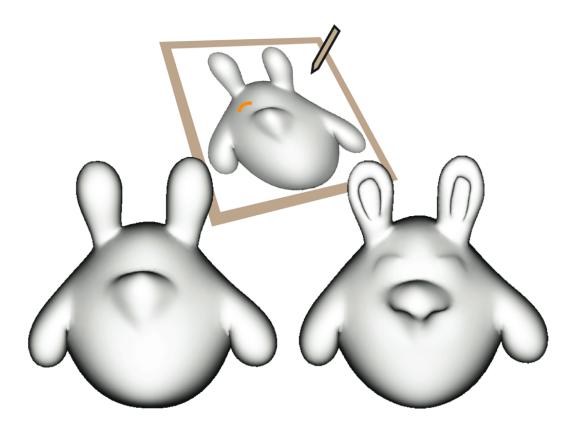
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- To edit a silhouette:
  - Parameterize silhouette edges
  - Parameterize sketch
  - Find correspondences
  - Use as xy position constraints (keep z unchanged)
  - Minimize Laplacian Surface
     Editing energy [Sorkine et al. 2004]



#### Surface relief editing by sketching shading



Shading-Based Surface Editing [Gingold and Zorin 2008]



## Shading

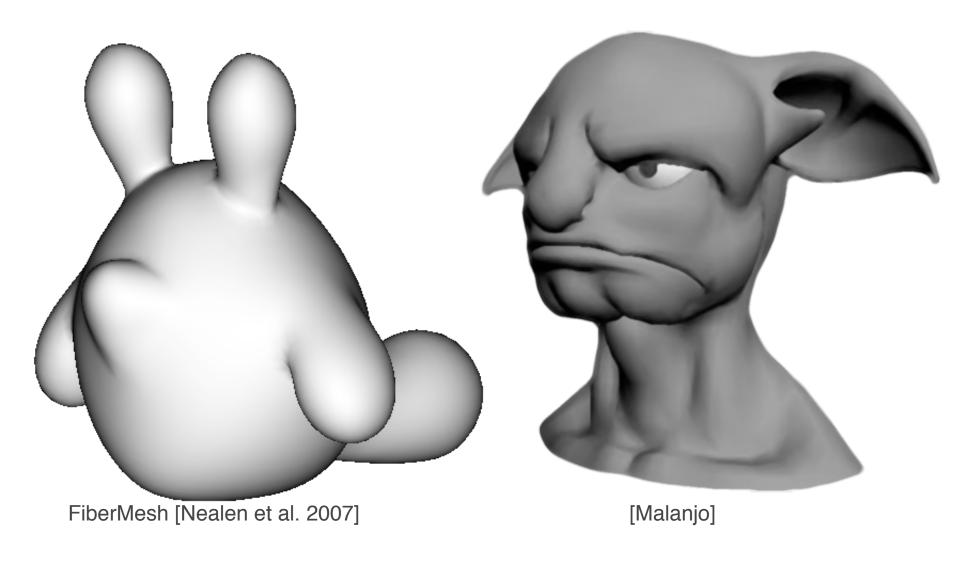


[Michelangelo]



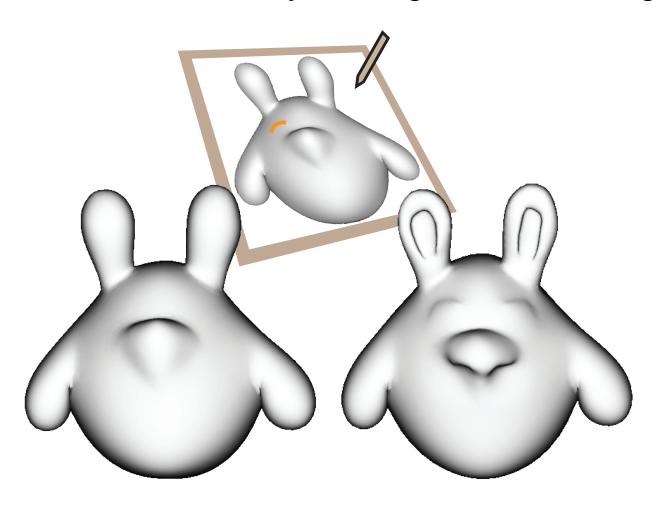
[Dürer]

#### Shaded 3D Models



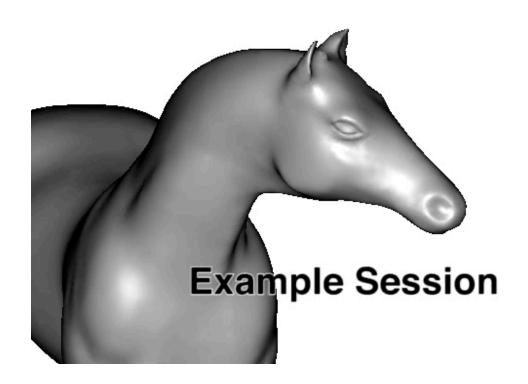
### Approach

Obtain a new 3D model by shading over an existing one.



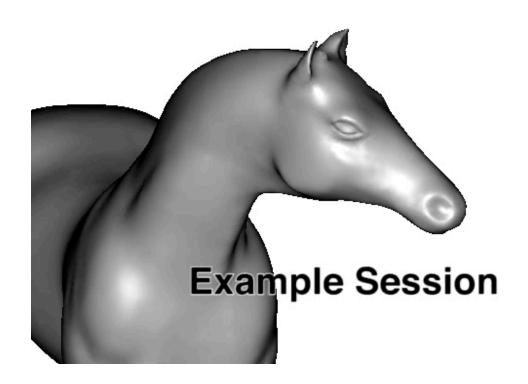
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· Leverages artists' experience with shading

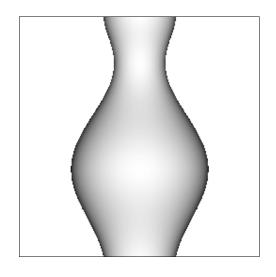
An interactive tool for surface editing by "drawing what you want to see."

- · Leverages artists' experience with shading
- · Brush parameters similar to paint programs

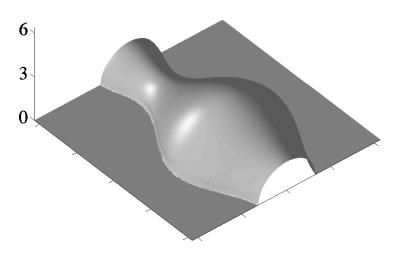
An interactive tool for surface editing by "drawing what you want to see."

- · Leverages artists' experience with shading
- · Brush parameters similar to paint programs
- Stable, predictable, approximate solution for a special case of Shape-from-Shading

Given a shaded image of an object, can we recover its shape?



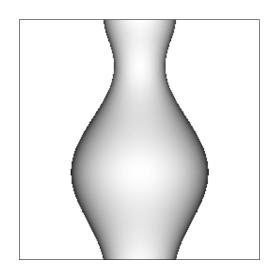
Shaded Image



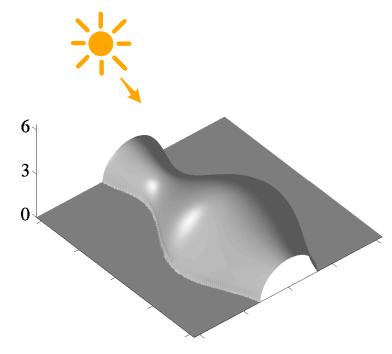
Shape (Height Field)

Given a shaded image of an object, can we recover

its shape?



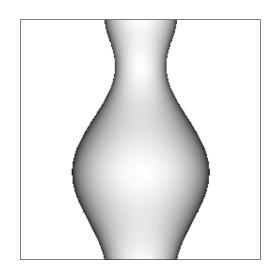
Shaded Image



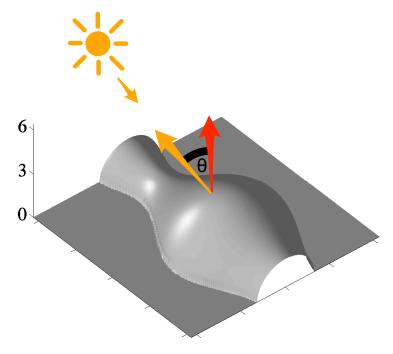
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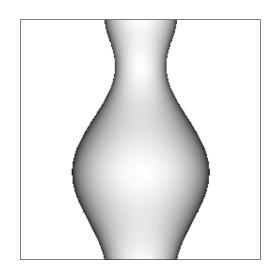
Shaded Image



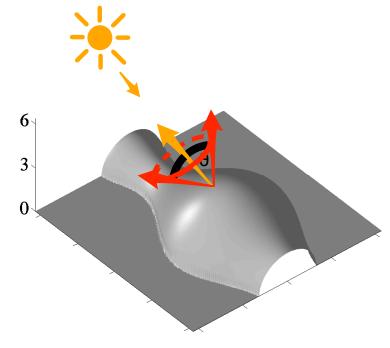
Shape (Height Field)

Given a shaded image of an object, can we recover

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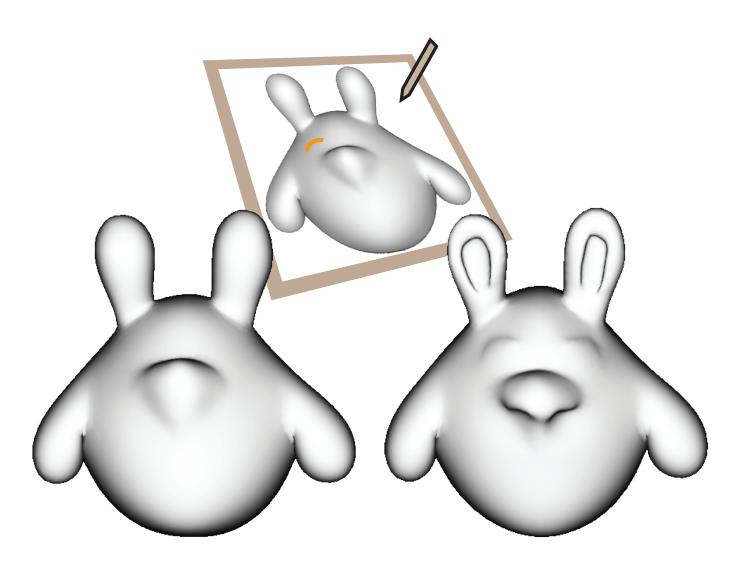


Shaded Image



Shape (Height Field)

#### User Interface



### Shading Strokes



### Shading Strokes

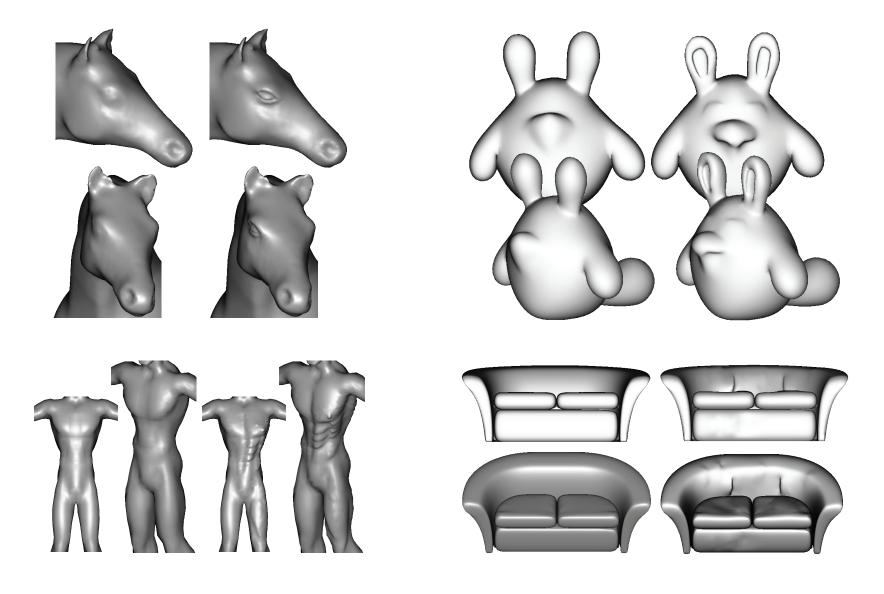


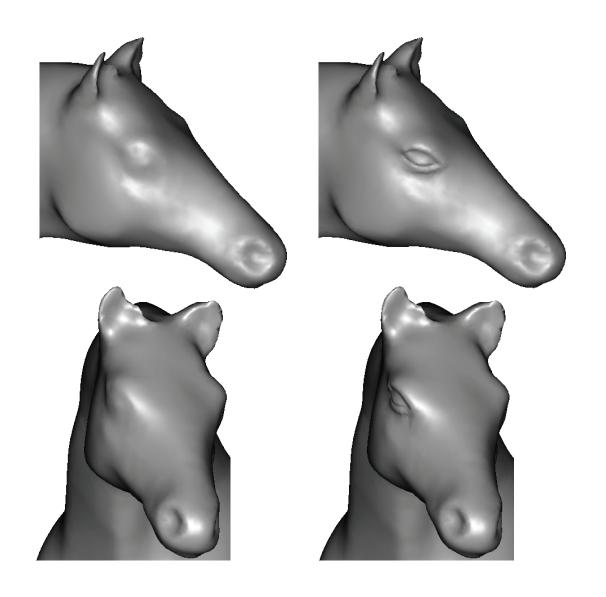
#### Silhouette Stroke

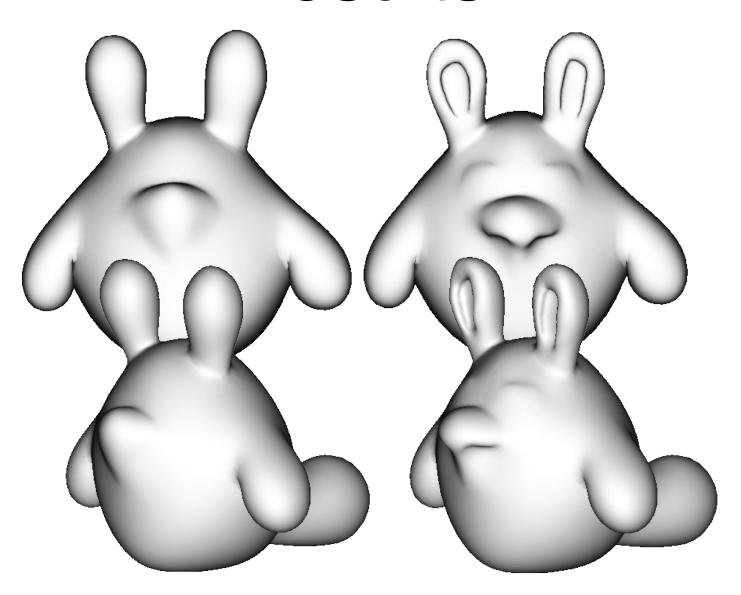


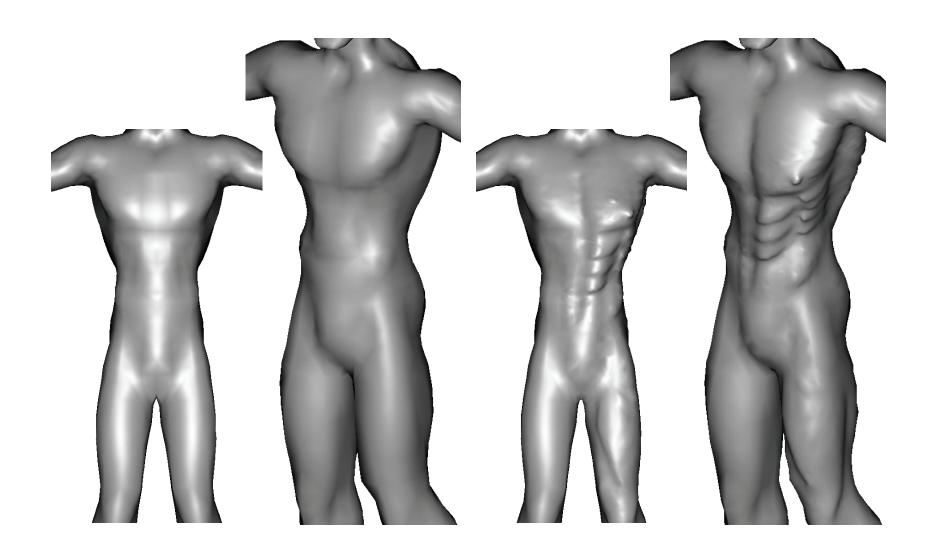
#### Silhouette Stroke

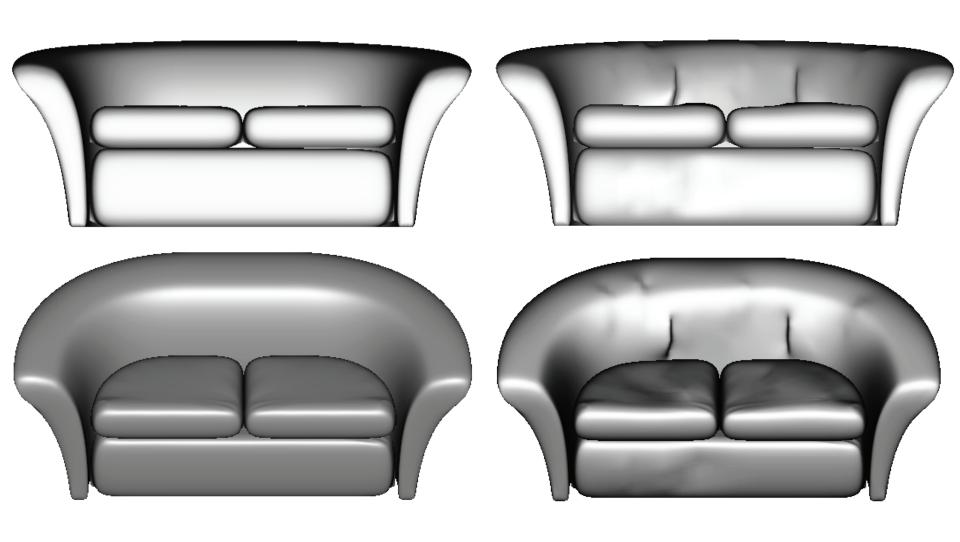












#### Video

Refining a model created in the FiberMesh system at 2x speed

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### Criteria for Controllability

Interface should balance:

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Stability (small changes produce small effects)

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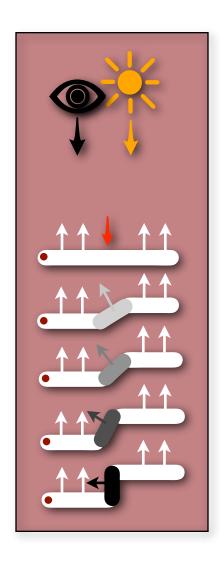
#### Interface should balance:

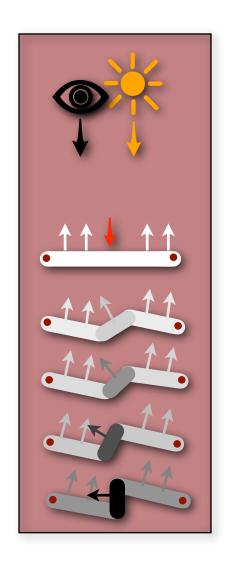
- Stability (small changes produce small effects)
- Appearance and shape preserved elsewhere

# Criteria for Controllability

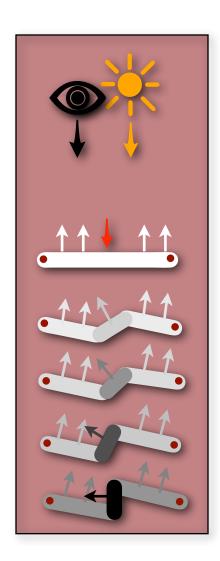
#### Interface should balance:

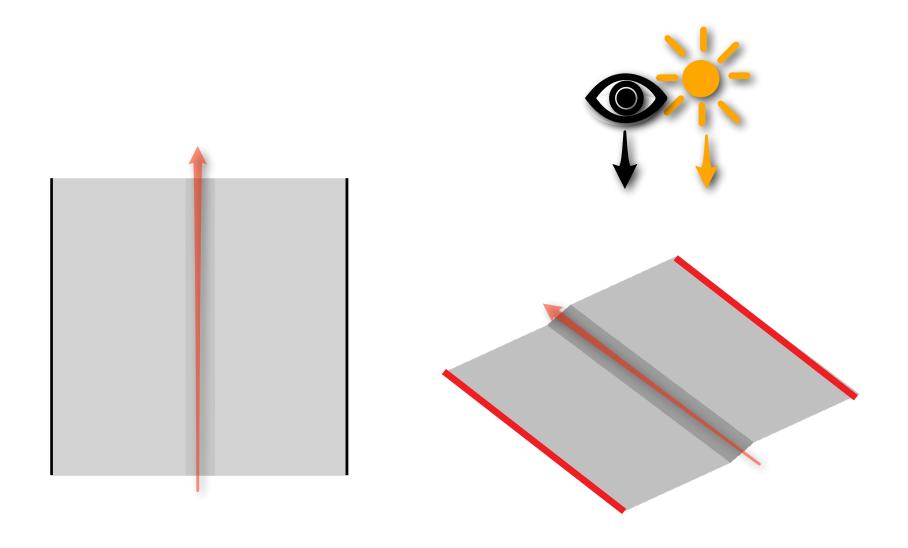
- Stability (small changes produce small effects)
- Appearance and shape preserved elsewhere
- Predictability





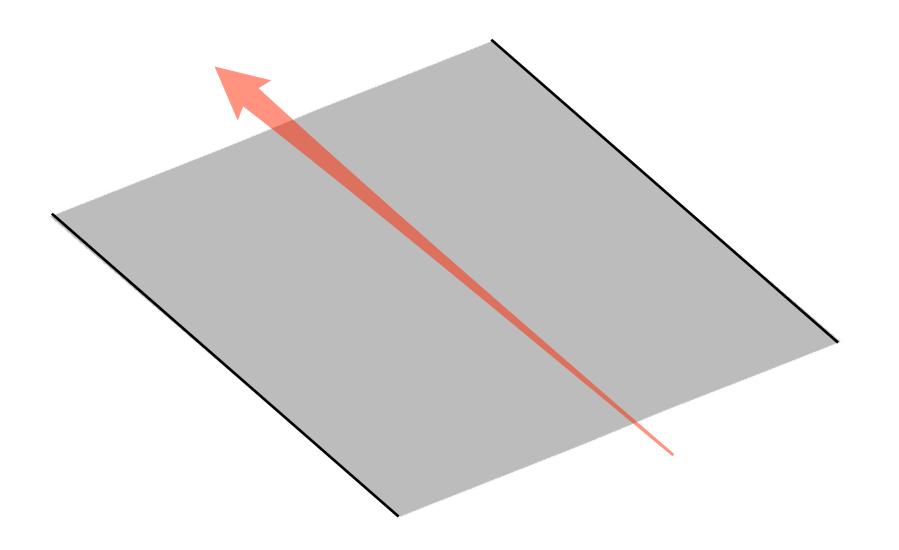
The change is global



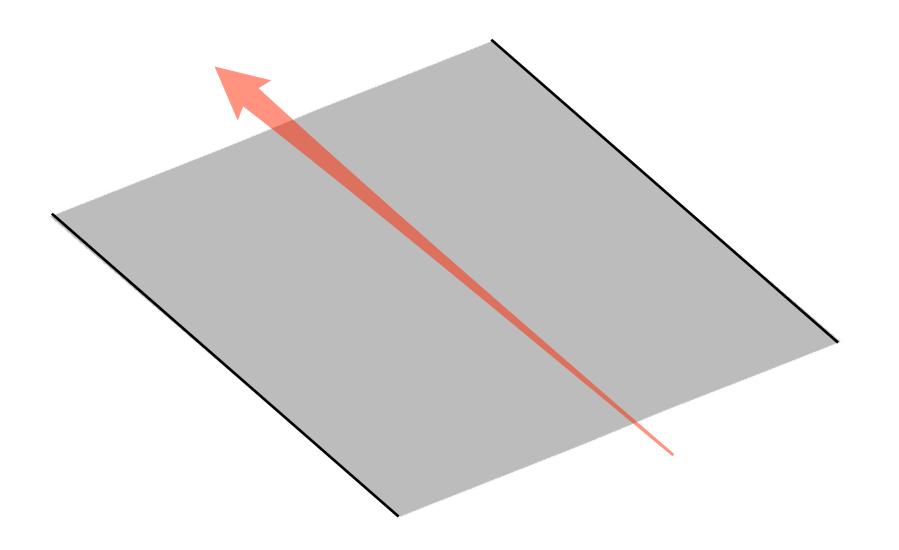


The change is global

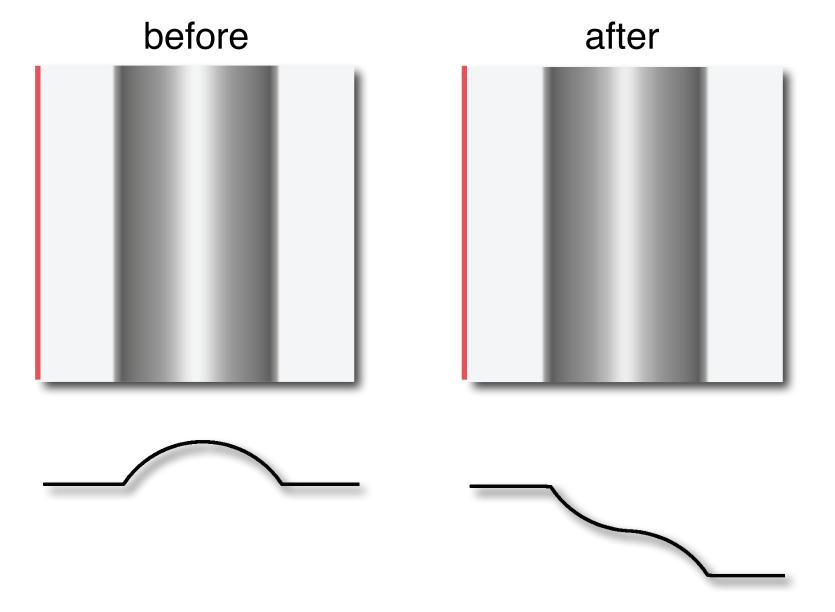
#### Rotation about the stroke



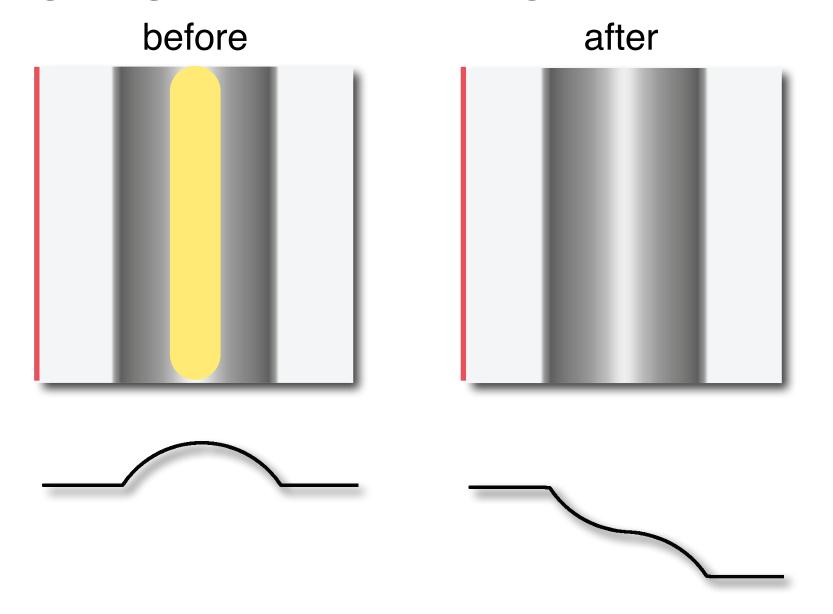
#### Rotation about the stroke



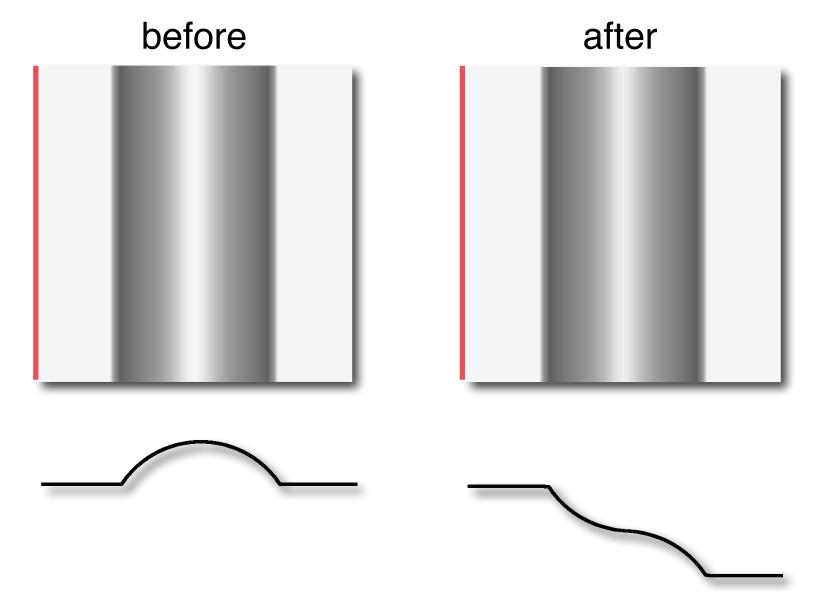
#### Highlight Darkening Instability

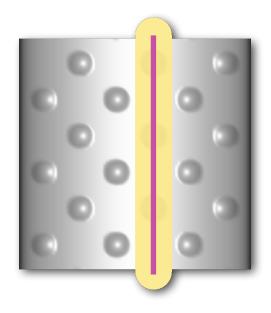


#### Highlight Darkening Instability



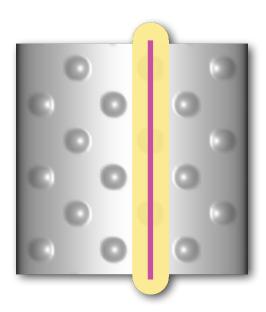
#### Highlight Darkening Instability





Centerline of stroke: rotate surface about the stroke

· stable, predictable

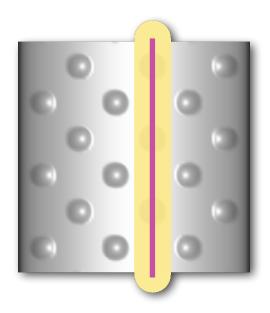


Centerline of stroke: rotate surface about the stroke

· stable, predictable

Elsewhere: Laplacian Editing Energy

· preserves appearance & shape



Centerline of stroke: rotate surface about the stroke

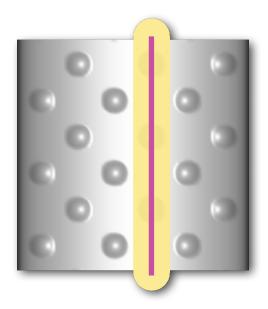
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Variable vertex weights for our brush parameters

· controllable



Centerline of stroke: rotate surface about the stroke

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Variable vertex weights for our brush parameters

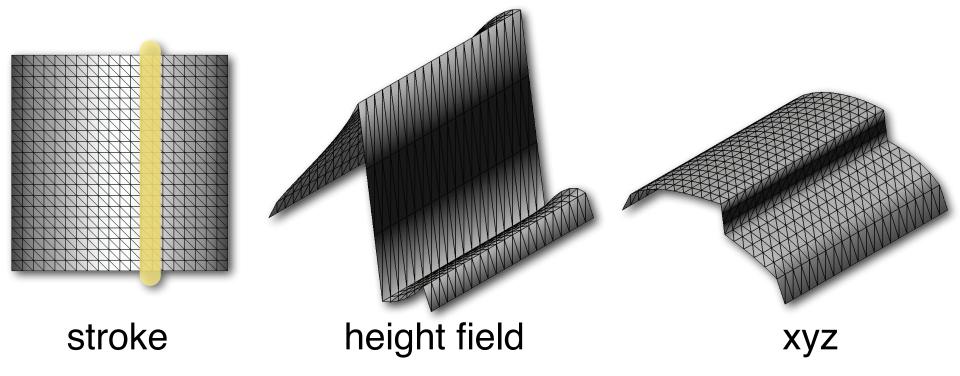
· controllable

Linear Constraints + Quadratic Energy = sparse linear system of equations

```
vertices (degrees of freedom) E(V') =
```

vertices (degrees of freedom)

$$E(V') =$$



```
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```

vertices

(degrees of freedom)

$$E(V') = \sum_{i=1}^{n} g(v_i) ||\Delta v_i - \Delta v_i'||^2$$

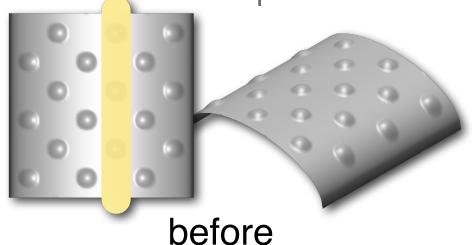
difference in laplacian, squared

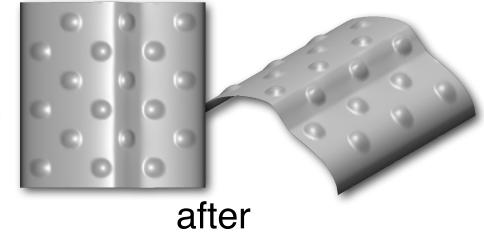
#### vertices

(degrees of freedom)

$$E(V') = \sum_{i=1}^{n} g(v_i) ||\Delta v_i - \Delta v_i'||^2$$

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vertices

(degrees of freedom)

$$E(V') = \sum_{i=1}^{n} g(v_i) ||\Delta v_i - \Delta v_i'||^2$$

difference in laplacian, squared

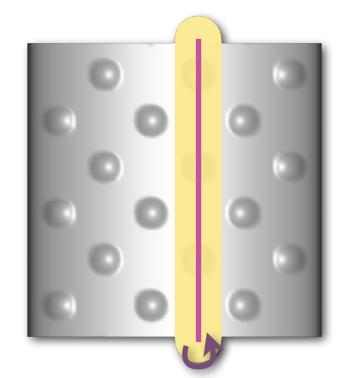
vertices (degrees of freedom)

 $E(V') = \sum_{i=1}^{n} g(v_i) \|\Delta v_i - \Delta v_i'\|^2 + w_{lsq} \sum_{i=1}^{n} \|(v_i' - v_j') - e^{trg}\|^2$ 

difference in laplacian, squared

constraint rotating the surface under the stroke

$$\frac{1}{w_{lsq} \sum_{(i,j)=e \in C} \|(v_i' - v_j') - e^{trg}\|^2}$$

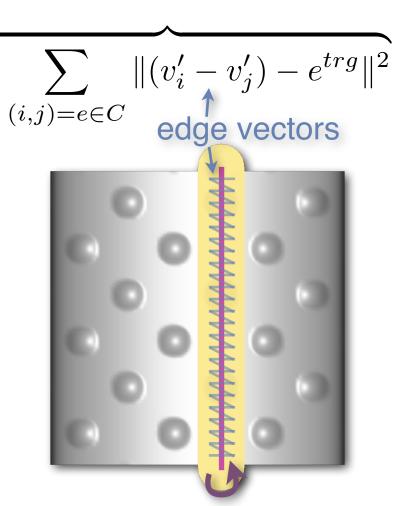


vertices (degrees of freedom)

 $E(V') = \sum_{i=1}^{n} g(v_i) \|\Delta v_i - \Delta v_i'\|^2 + \underbrace{w_{lsq} \sum_{(i,j)=e \in C} \|(v_i' - v_j') - e^{trg}\|^2}_{\text{edge vectors}}$ 

difference in laplacian, squared

constraint rotating the surface under the stroke



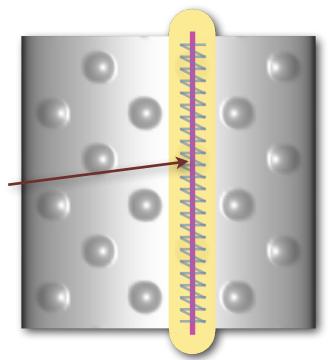
vertices (degrees of freedom)

constraint rotating the surface under the stroke

$$E(V') = \sum_{i=1}^{n} g(v_i) \|\Delta v_i - \Delta v_i'\|^2 + \underbrace{w_{lsq} \sum_{(i,j)=e \in C} \|(v_i' - v_j') - e^{trg}\|^2}_{(i,j)=e \in C}$$

difference in laplacian, squared

image-plane constraints (not shown in E)



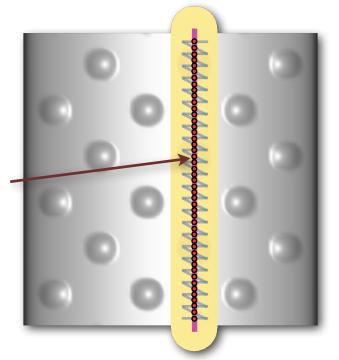
vertices (degrees of freedom)

constraint rotating the surface under the stroke

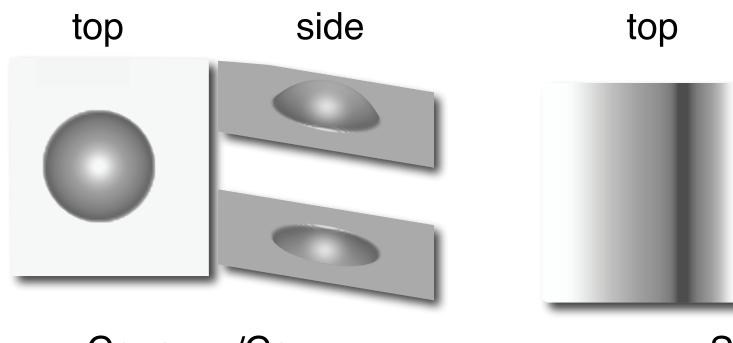
$$E(V') = \sum_{i=1}^{n} g(v_i) \|\Delta v_i - \Delta v_i'\|^2 + \underbrace{w_{lsq} \sum_{(i,j)=e \in C} \|(v_i' - v_j') - e^{trg}\|^2}_{(i,j)=e \in C}$$

difference in laplacian, squared

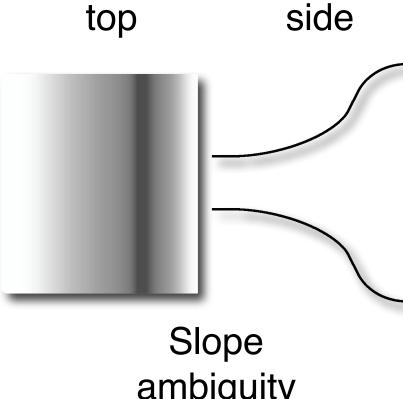
image-plane constraints (not shown in E)



# Flip Ambiguity

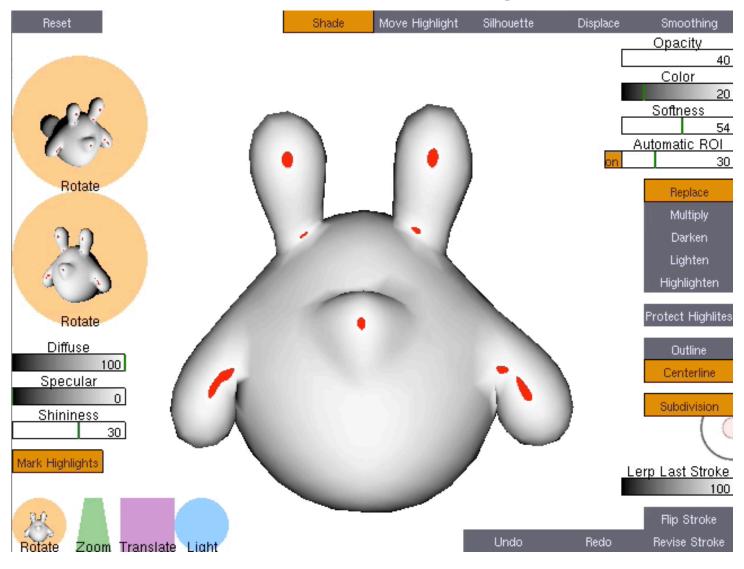


Concave/Convex ambiguity

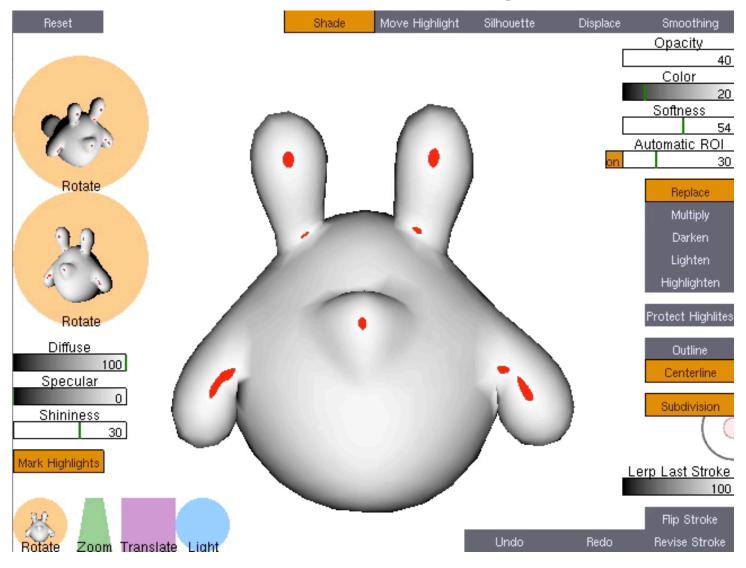


ambiguity

# Summary



# Summary



#### Limitations

Shading requires expertise.

Speed: modifications aren't local.

Lack of integration with sculpting tools and silhouette editing.

Highlight control is limited.