

|  | Classification |  |
| :---: | :---: | :---: |
|  | - Nested models |  |
|  | O based on a nested subdivisions of the surface domain |  |
| $\bigcirc$ each cell in the subdivision is refined |  |  |
| ${ }^{\prime}$ |  |  |
|  |  | Evolutionary mod |
| s |  | - based on the |
|  |  | $O$ different mes of modificatio |
| EG99 Tutorial |  |  |




## Nested models as MTs

- A node of the tree is not necessarily a node of the MT
- Nodes of the MT are obtained by node clustering
- Clustering rule: if an edge $e$ of a triangle $t$ splits during refinement, then

O the same split must occur in refining triangle $t$ ' adjacent to $t$ along $e$

O the meshes refining $t$ and $t^{\prime}$ must be clustered

- Propagation: many nodes of the tree can be clustered to form one node of the MT because of edge splits





|  | ... Quadtree surface ... |  |  |
| :---: | :---: | :---: | :---: |
| Octree [Wilhelms and Van Gelder, 1994] |  |  |  |
| - Extension of quadtree to volume data | - Extension of quadtree to volume data |  |  |
| O Subdivision of a cubic universe into octants |  |  |  |
| - Data field within each octant approximated through tri-linear patch |  |  |  |
| - Same problems as quadtree with cracks between octants of different levels |  |  |  |
| (2) |  |  |  |
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## Restricted quadtree [Von Herzen \& Barr, 1987]

Merging triangles from different levels without cracks:
O Adjacent quadrants can differ by one level

- Each quadrant is triangulated
- Linear interpolation is used on each triangle



Restricted quadtree and wavelets [Gross et al., 1996]

- Quadtree subdivision naturally adapt to computation of wavelet coefficients at grid vertices
- LOD refers to detail relevance in wavelet space, rather than absolute approximation error on surface
- Selective refinement: vertices are selected according to their LOD, and the resulting quadtree is triangulated a posteriori
- Two quadtree levels are allowed between adjacent quadrants
- More complex lookup table is necessary to obtain all triangulation patterns

Hierarchy of right triangles
[Lindstrom et al., 1996, Evans et al., 1997, Duchaineau et al., 1997, Pajarola, 1998]

Each triangle is recursively bisected by splitting it along its longest edge


Binary tree representation

MT corresponding to a hierarchy of right triangles:

- cluster triangles of the same level that share a short edge
- each node is formed of four triangles (except at the boundary)
- two types of nodes:


## O squares

O diamonds

- each node has two parents and four sons (except at the boundary, root, and leaves)

- Different models are characterized by:

O data structures
O error evaluation
O traversal algorithms

- Trade-off between space complexity and time efficiency

[Duchaineau et al., 1997, Evans et al., 1997]
- Data structure: binary tree of triangles
- Error: a priori evaluation

M Selective refinement: top-down traversal of the tree, by forcing splits where necessary

- no need for numerical computation during refinement
${ }^{(2)} \quad \nabla$ expensive data structure

- Codes for triangles [Hebert, 1995]

O Reference domain: unit square [0,1]x[0,1]

- Quadtree subdivision:
a quadrant is identified by its center
the center of a quadrant at level $m$ is encoded by a sequence of $m$ quaternary digits ( $2 m$ bits)

$$
\sum_{i=1}^{m} 2^{-i} \sigma_{i}
$$

where all $\sigma_{i}$ are pairs of signs: $(-1,-1)(-1,1)(1,-1)(1,1)$

| ...Hierarchy of right triangles... |
| :--- | :--- | :--- |
| O For each level of the quadtree there are two levels in the tree |
| of triangles: each quadrant is subdivided in two possible ways |
| O Triangles in a quadrant are identified by a pair of digits (I,t) |
| where I is the type of subdivision, and tis the index of a |
| triangle in the subdivision (total 4 bits) |

- Topological relations are evaluated by algebraic manipulation of codes. From a triangle we can obtain:
- vertices

O parent triangle
O sons
O adjacent triangles at the same level
O adjacent triangle at the previous level
O adjacent triangles at the next level



- Relations among triangles and nodes are evaluated by algebraic manipulation of codes. From a node we can obtain:
O triangles in it
O triangles in its floor
O parent nodes
O child nodes

The algorithm for selective refinement for MT can be implemented efficiently on a hierarchy of right triangles encoded by the implicit data structure


Multi-tetra framework [Maubach, 1994, Zhou et al., 1997]

- Extension of hierarchy of right triangles to volume data:

O Subdivision of a cubic universe into twelve tetrahedra
O Recursive bisection of each tetrahedron at the midpoint of its longest edge

- Implicit data structure as in the 2D case [Hebert, 1994]


## Quaternary triangulations

- Recursive subdivision of a triangular domain into four triangles by joining the edge midpoints
- Applicable as a refinement scheme to an arbitrary surface mesh at low resolution
- Topological constraints on positions of vertices (needs re-meshing)
- Supports methods based on wavelets

- A mesh made of triangles from different levels has cracks





## Adaptive hierarchical triangulations

- Based on irregular triangulations
- Suitable for sparse data sets
- Error driven subdivision rule: refine a triangle by inserting vertices that cause the largest errors
- Vertices can be inserted inside a triangle and/or on its edges
- More adaptive than models based on fixed subdivision rules
- May contain elongated triangles (slivers)
[Pavlidis and Scarlatos, 1990/92]
- Find the vertex causing the largest error inside the triangle and the vertices causing the largest error along each edge
- Select only vertices whose error is beyond a given threshold

- Use predefined subdivision patterns
[De Floriani and Puppo, 1992/95]
- Insert the vertex causing the largest
- Insert the vertex causing the achieved
- At each insertion compute the Delaunay triangulation
 -


## Evaluation of treelike models

## Regular subdivisions

- Pros:

O easy to handle
O compact data structures
O regular shape of regions
O support wavelets

- Cons:

O only regular data: topological constraints

- quadtrees and right triangles only for terrain
O less adaptive than irregular triangulations


## Irregular subdivisions

- Pros:

O suitable for arbitrary data and for arbitrary surfaces
O more adaptive than regular subdivisions

- Cons:

O elongated triangles
O cumbersome data structures
O selective refinement not easy

## Evolutionary models

Store the evolution of a mesh through either refinement or simplification algorithm based on local modifications

- Partial order is given by relations among components of the mesh (vertices, faces, etc...) before and after each local modification
- Different models characterized by:

O types of surfaces supported

- construction method

O information stored (geometry, connectivity, topology, interference, attributes, error, etc...)
O operations supported - efficiency of algorithms

- Models based on vertex insertion / vertex decimation

O [De Floriani, 1989]
O [de Berg and Dobrindt, 1995]
O [Cignoni et al., 1995/97]

- [Brown, 1996/97]

O [Klein and Strasser, 1996]
O [De Floriani et al., 1996/97/98]

vertex decimation


- Models based on vertex split / edge collapse

O [Hoppe, 1996/97/98]
O [Xia et al., 1996/97]
O [Maheswari et al., 1997]
O [Gueziec et al., 1998]
O [Kobbelt et al., 1998]


## Construction through refinement

- Method applied only to build models based on vertex insertion

O Start from a coarse mesh at low resolution built on a small subset of data
O Perform iterative local refinements until all data have been inserted as vertices of the mesh

- The initial mesh is the root of an MT
- Each local refinement generates a node of an MT formed of new triangles inserted in the mesh
- Difficult to apply to generic manifold surfaces


## ...Construction through refinement...

- Greedy refinement:
$O$ at each step, insert vertex causing the largest error
O mesh update based on either Delaunay or data dependent triangulation
$\Delta$ good heuristic to reduce the number of points to achieve a given accuracy
- inserting vertices of bounded degree guarantees linear growth
method cannot guarantee that accuracy improves at every refinement step
$\nabla$ fragments may pile-up in a high hierarchy: low expressive power low performance of traversal algorithms


## ...Construction through refinement...

Extension to 3D [Cignoni et al., 1994/1997]

- Iterative insertion of vertices in a Delaunay tetrahedrization
- Vertex selection rule as in 2D
- Applicable to convex and curvilinear volume data sets


## Construction through simplification

- Any local simplification rule can be used (vertex decimation, edge collapse, etc.)
O Start from mesh at full resolution, based on all data
O Perform iterative local simplifications
- The final mesh is the root of an MT
- Each simplification step generates a node formed of triangles eliminated from the mesh
- The new portion of mesh generated by a simplification step is the floor of the corresponding node
(2)
- Applicable to generic manifold surfaces


## ...Construction through simplification...

- Vertex decimation:

O node: a star of triangles surrounding the removed vertex
O floor of a node: a star-shaped triangulated polygon


- Key issues:

O selection of vertices to remove
O triangulation method
O degree of vertices (size of fragments)
O error estimation
O height of the resulting hierarchy


## ...Construction through simplification...

- Greedy decimation:

O at each step, remove vertex causing the least error increase
O mesh update based on either Delaunay triangulation or heuristics

- result similar to greedy refinement
$\Delta$ removing vertices of bounded degree guarantees linear growth
$\nabla$ components may pile-up in an unbalanced DAG





## ...Construction through simplification...

- Edge collapse on midpoint:

O node: cycle of triangles surrounding the collapsed edge
O floor: star of triangles surrounding the vertex resulting from collapse

- Edge collapse on endpoint:


O node: star of triangles surrounding the endpoint
O floor: fan of triangles centered at endpoint
O equivalent to decimation with special update rule



## ...Construction through simplification...

Illegal edge collapse: one or more triangles flip over because of collapse operation.


## ...Construction through simplification...

- Edge collapsing rules:

O Greedy: collapse an edge at each step:

$$
\triangleleft \text { the shortest edge }
$$

$\diamond$ the edge causing the least error increase
$\triangleleft$ an edge surrounded by almost coplanar faces
O Independent set:
$\triangleleft$ two edges are independent if they have disjoint influence regions
$\diamond$ select a maximal set of independent edges and collapse them all together

- Results similar to decimation:
$\Delta$ removing vertices of bounded degree guarantees bounded width and linear growth
$\Delta$ removing an independent set guarantees logarithmic height
$\nabla$ in greedy collapse fragments may pile-up in a high hierarchy


## ...Construction through simplification...

Extension to 3D [Cignoni et al., 1997]

- Edge collapse in a tetrahedrization: collapse an edge and the star of tetrahedra surrounding it
- Edge selection as in 2D
- Applicable to all kinds of volume data sets



## Data structures

Relevant information on evolutionary models

- Geometry: coordinates of vertices
- Connectivity: triples of vertices forming triangles
- Topology: adjacency, boundary, co-boundary relations
o local topology: among elements of a single node
O global topology: among components of different nodes
- Spatial interference: relations among nodes and triangles that have spatial interference
- Additional information: accuracy, material, surface normal, etc.


## ...Data structures...

- Different data structures characterized by the amount of information stored
- Trade-off between spatial complexity and efficiency
o compact data structures more suitable to storage and transmission
O extended data structures more suitable to complex operations:
$\triangleleft$ selective refinement
$\diamond$ spatial queries
- Compactness can be achieved by exploiting properties of special models


## ...Data structures...

Linear sequences: store sequences of local modifications that produce a refined mesh starting at a coarse mesh

- List of vertices [Klein \& Strasser, 1996] :

O store initial mesh plus sequence of vertices in suitable order
O each vertex in the sequence is inserted iteratively to refine mesh
O mesh is updated with Delaunay (implicit) rule at each insertion

- very compact
$\boldsymbol{\nabla}$ suitable only to explicit and parametric surfaces
$\nabla$ local update requires numerical computation
$\nabla$ selective refinement is computationally expensive
$\boldsymbol{\nabla}$ no connectivity, topological, and interference information maintained


## ...Data structures...

- List of triangles [Cignoni et al., 1995] :

O store all triangles appearing during refinement/simplification
O each triangle is tagged with a life: range of accuracies through which it "survives" during refinement/simplification
O life is used to extract meshes at a given (uniform) LOD
O extended to 3D for volume data [Cignoni et al., 1997]

A applicable to all kinds of surface
$\Delta$ extraction of a uniform LOD very efficient
$\Delta$ moderately compact
$\nabla$ selective refinement not possible
$\boldsymbol{\nabla}$ no topology and interference maintained

## ...Data structures...

- Progressive Meshes [Hoppe, 1996/98]:

O store initial coarse mesh plus a sequence of vertex splits (inverse operation of edge collapse) in suitable order
O each vertex split is maintained in compressed format
O each vertex split gives a node of a corresponding MT
O a uniform LOD is extracted by expanding the sequence up to the desired level
$\Delta$ compact
$\Delta$ extraction of a uniform LOD efficient without numerical computation

- suitable additional structures to maintain attributes
$\nabla$ selective refinement needs additional information
$\nabla$ no connectivity, topology and interference maintained


## ...Data Structures...

Explicit MT representation [De Floriani et al., 1996/98]

- Geometry: vertex coordinates
- Connectivity:

O for each triangle: error + references to its three vertices

- DAG structure:

O for every $\operatorname{arc}\left(\boldsymbol{T}_{\boldsymbol{j}} \boldsymbol{T}_{\boldsymbol{i}}\right)$ : links to source and destination node, link to the set of triangles of $\boldsymbol{T}_{\boldsymbol{j}}$ which form the floor of $\boldsymbol{T}_{\boldsymbol{i}}$
O for every node: link to the sets of its incoming and outcoming arcs


## ...Data structures...

...Explicit MT representation...
$\triangle$ Supports selective refinement efficiently

- Supports spatial queries efficiently
$\nabla$ High storage cost
$\nabla$ No topology


## Compressed hierarchies:

- Key ideas:

O each node of an MT is a local modification that can be encoded in compressed form
O hierarchical links among nodes are encoded explicitly

- Different structures for models based on edge collapse (PM):

O [Xia et al., 1996/97]
O [Hoppe, 1997]
O [Gueziec et al., 1998]

- One structure for models based on vertex decimation:

O [De Floriani et al., 1997/98]

## ...Data structures...

## Compressed hierarchies for PMs

Vertex tree (forest) [Xia et al., 1996/97]

- Binary forest of vertices
topmost level: vertices of the base mesh
children of a vertex: vertices resulting from split
O Vertex split can be encoded in compressed form
O Rule for selective refinement: a vertex can split if and only if all boundary vertices of the corresponding fragment belong to the current mesh $\rightarrow$ need for additional interference links
) For each vertex:
parent-child relation in forest
$\triangleleft$ additional links to vertices that must exist in order to allow split
More compact than explicit MT
Less general than explicit MT
No control on accuracy of triangles





## ...Data structures...

## Compressed hierarchies for MT based on decimation

Implicit MT [De Floriani et al., 1997/98]
O Each node corresponds to vertex insertion/decimation

- Partial order of nodes is maintained

O Array of vertices, each entry storing vertex coordinates
O Array of arcs - for every arc a:
$\triangleleft$ indexes of source and destination nodes
$\triangleleft$ index of next arc with same destination node
O Array of nodes - for every node n:
$\checkmark$ index of first outgoing and incoming arcs
$\triangleleft$ number of outgoing arcs
$\triangleleft$ maximum error of its triangles
$\triangleleft$ compressed information to perform vertex insertion/decimation


## ...Data structures...

Hypertriangulation [Cignoni et al., 1995/97]

- Interpretation of an MT in a higher dimensional space:
triangles of a new node are lifted along a "resolution axis" and welded on floor at the node boundary




## Selective refinement

- Top-down traversal of hierarchy:

O on generic MT [Puppo, 1996, De Floriani et al., 1997/98]
O on PM [Hoppe, 1997, Xia et al., 1997]
O on restricted quadtrees [Von Herzen and Barr, 1987, Gross et al., 1996]
O on hierarchy of right triangles [Evans et al., 1997, Duchaineau et al., 1997]
O on hierarchy of irregular triangles [De Floriani \& Puppo, 1995]

- Bottom-up traversal of hierarchy:

O on PM [Xia et al., 1996]
O on hierarchy of right triangles [Lindstrom et al., 1996]

- Breadth-first traversal of surface:

O on hypertriangulation [Cignoni et al., 1995/97]
O on hierarchical triangulation [De Floriani \& Puppo, 1995]

## Top-down on MT

- Visit DAG starting at cut just below its root
- Recursively move cut below a node $n$ when a triangle labeling an arc entering $n$ has accuracy worse than LOD

Algorithm on explicit MT:
$\Delta$ Optimally efficient (on MT with linear growth)
A Applicable to all models
$\nabla$ Needs expensive data structure
Algorithm on implicit MT:
$\Delta$ Lighter data structure
$\nabla$ Slower

- Output mesh larger
- Applicable only to special models


## Top-down on PM (vertex forest or DAG)

- Visit forest/DAG starting at topmost level
- Recursively expand a vertex when accuracy worse than LOD
- Find all vertices that constrain selected vertices
- Perform all splits corresponding to selected vertices in the default order
- Fast

マ Needs expensive data structure


## Top-down on tree of right triangles

- Visit tree starting at its root
- Recursively refine a triangle when accuracy worse than LOD
- Propagate vertex dependencies to obtain a conforming mesh
- Easy and fast if all vertex dependencies are available

Top-down on trees of irregular triangles

- Visit tree starting at its root
- Recursively expand a triangle when accuracy worse than LOD
- Triangulate mesh a posteriori to make it conforming
- Easy and fast
v No control on error of triangles generated a posteriori


## Bottom-up on PM (vertex forest):

- Visit forest starting at leaves
- Recursively discard leaves that can be collapsed
- Perform splits corresponding to selected vertices in default order


## Bottom-up on hierarchy of right triangles:

- Visit tree starting at leaves
- Recursively merge sibling leaves when possible
- All vertices must be analyzed even to extract a coarse LOD


## ...Selective refinement..

## Breadth-first traversal of domain on hypertriangulations and on hierarchical triangulations

- Start with a triangle where highest LOD is required
- Incrementally add triangles adjacent to the boundary of current triangulation through global adjacencies
- Each time a boundary edge $e$ is crossed, select a triangle which is as coarse as possible, satisfied the LOD, and is compatible with current mesh
- Supports dynamic local refinement/abstraction of detail (resolution editing)
- Ideal for propagating LOD through the surface rather than through space
- Applicable only for LOD monotonically decreasing with distance from a given point
- Computational complexity is super-linear
- Needs expensive data structure


|  | ...Discussion... |  |
| :---: | :---: | :---: |
| Types of surfaces supported |  |  |
|  | - All types: <br> O MT, PM, HyT, quaternary triangulations |  |
| $\bigcirc$ |  |  |
| M | - Explicit and parametric surfaces only: |  |
| D E L | o quadtrees, restricted quadtrees, hierarchies of right triangles (problems with trimming curves) |  |
| s | O Adaptive hierarchical triangulations |  |
| (2) |  |  |
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## Expressive power

- Number of different meshes that can be extracted
- Possibility to adapt a mesh to arbitrary LOD
- Ratio accuracy/size

More expressive, higher ratio

- Explicit MT

PM, Implicit MT
HyT
Quaternary triangulations
Hierarchy of right triangles, quadtree, restricted quadtree,
Less expressive, lower ratio

Adaptive hierarchical triangulations








